The background of the slide is a deep space image featuring a dense field of stars of various magnitudes, some with prominent diffraction spikes. Interspersed among the stars are wisps and clouds of interstellar dust and gas, primarily in shades of reddish-brown and orange, creating a rich, textured cosmic environment.

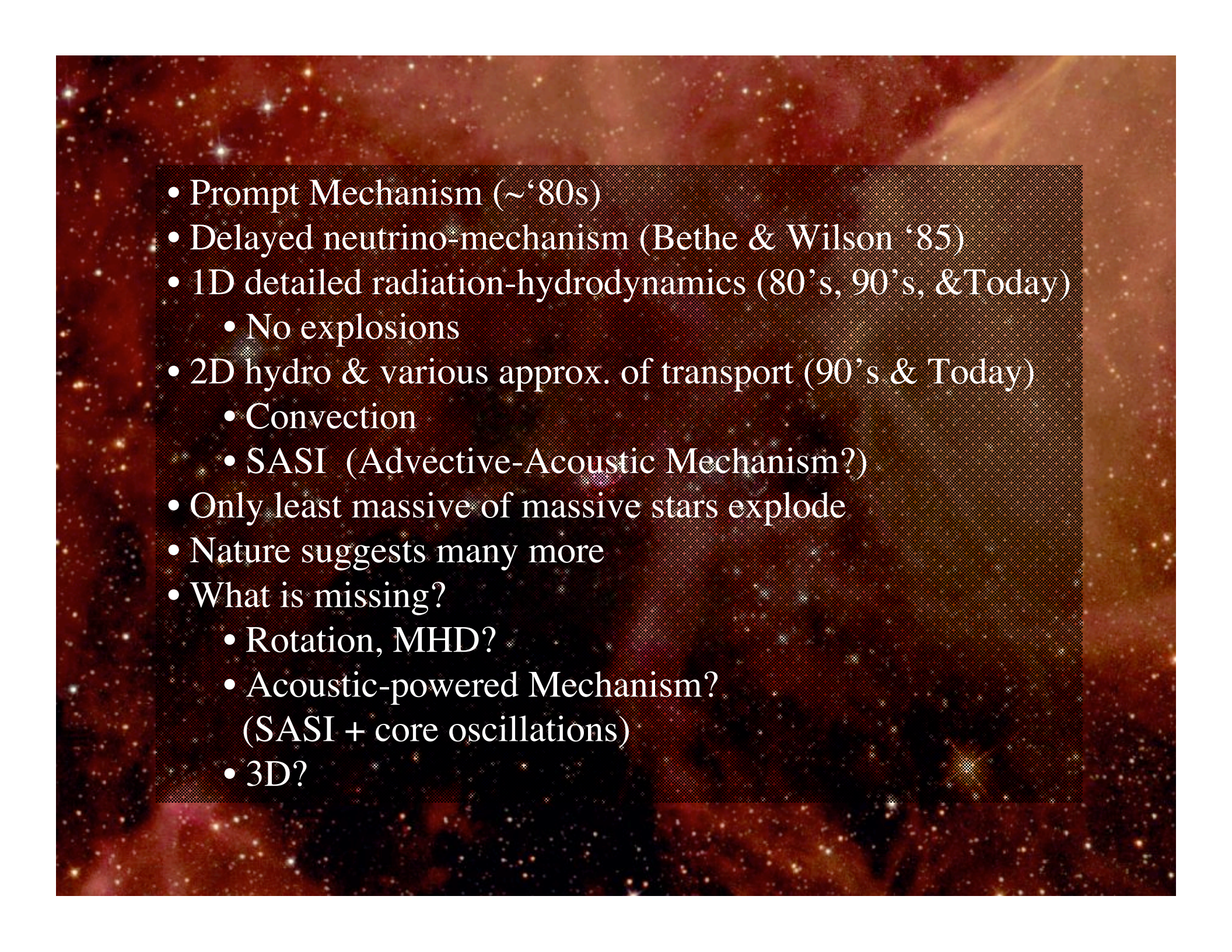
Criteria for Core-collapse Supernova Explosions by the Neutrino Mechanism

by

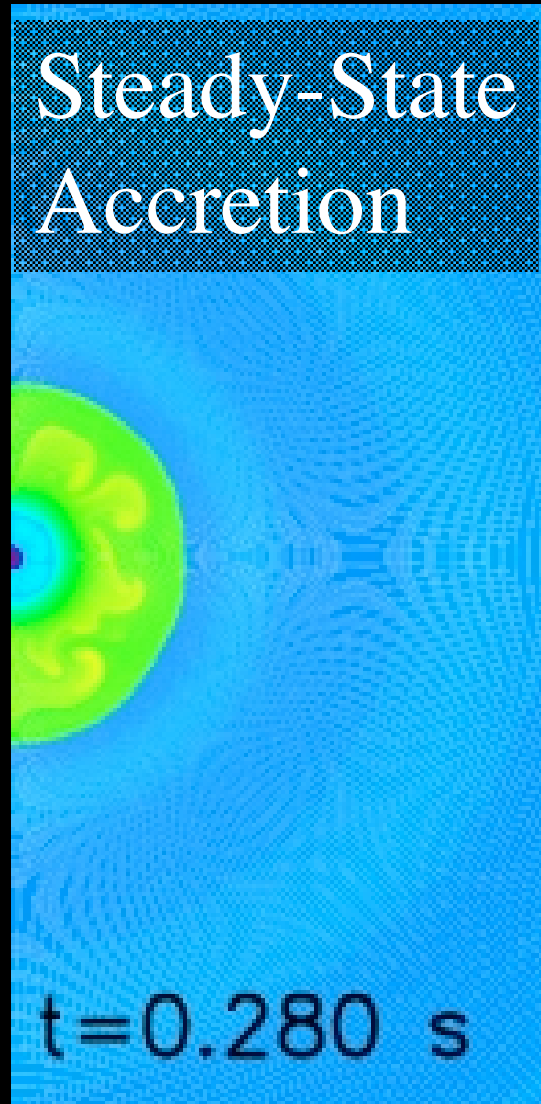
Jeremiah W. Murphy
(Steward Observatory/UW)

&

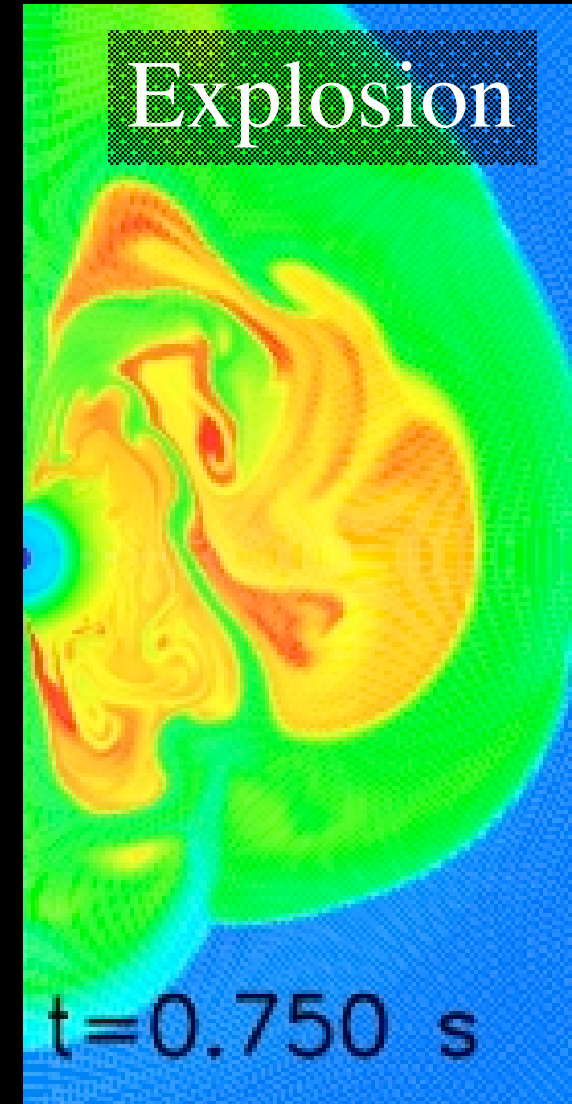
Adam Burrows (Princeton U.)

- 
- Prompt Mechanism (~'80s)
 - Delayed neutrino-mechanism (Bethe & Wilson '85)
 - 1D detailed radiation-hydrodynamics (80's, 90's, & Today)
 - No explosions
 - 2D hydro & various approx. of transport (90's & Today)
 - Convection
 - SASI (Advective-Acoustic Mechanism?)
 - Only least massive of massive stars explode
 - Nature suggests many more
 - What is missing?
 - Rotation, MHD?
 - Acoustic-powered Mechanism?
(SASI + core oscillations)
 - 3D?

Fundamental Question of Core-Collapse Theory



?



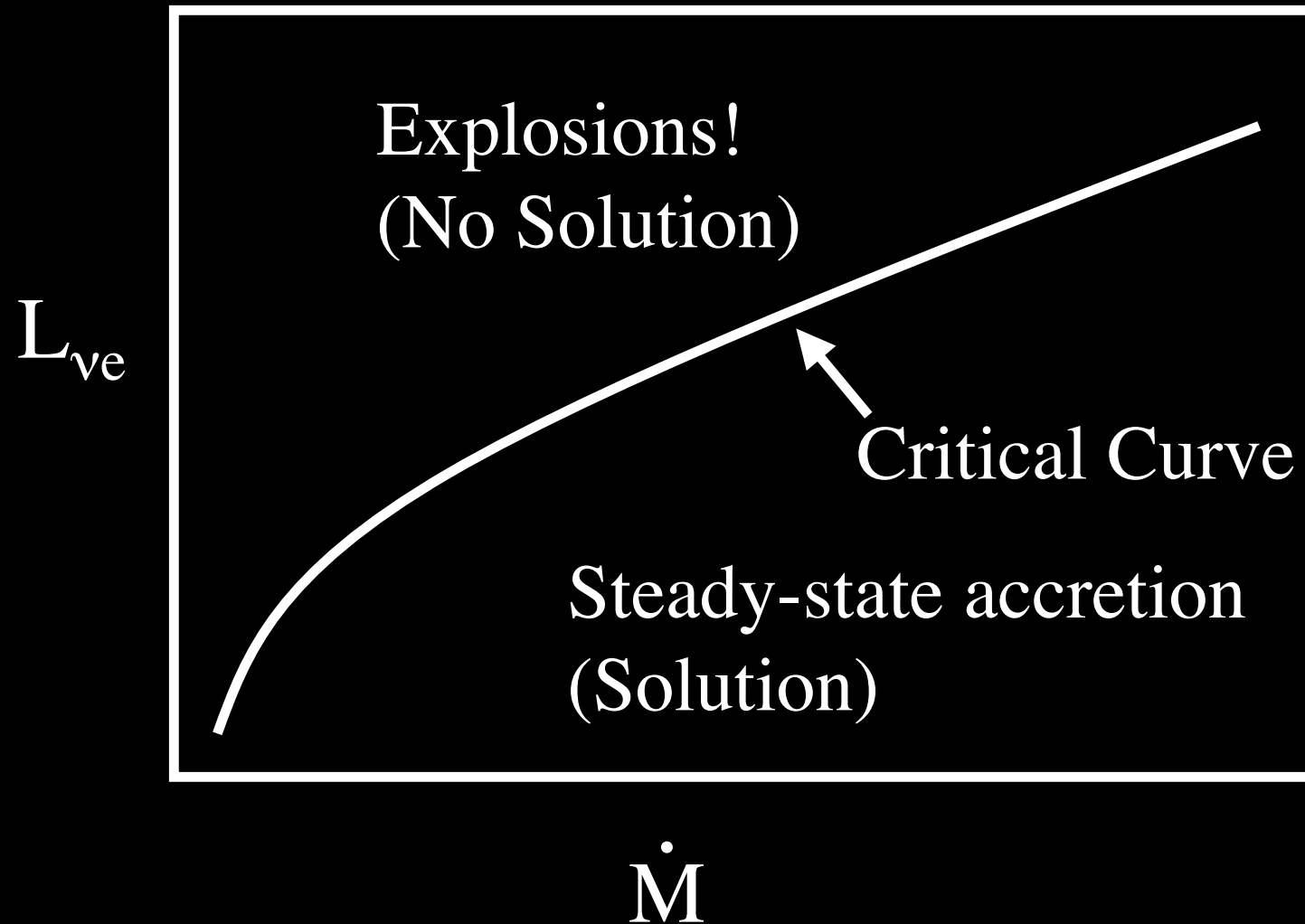
*And why is it easier to explode
in 2D compared to 1D?*

Two Paths to the Solution

- Detailed 3D radiation-hydrodynamic simulations (“Accurate” energies, NS masses, nucleo., etc.)
- Parameterizations that capture essential physics (Tease out fundamental mechanisms)

Burrows & Goshy '93

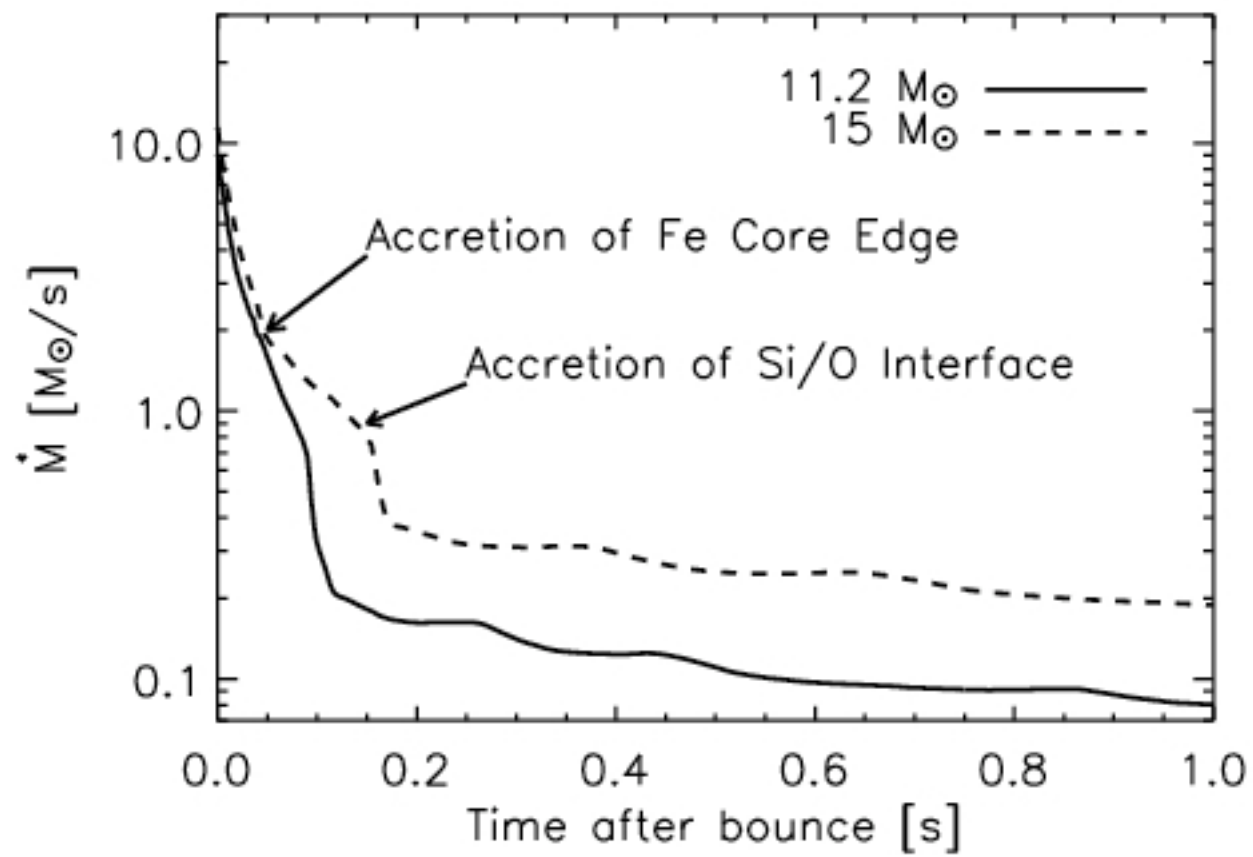
Steady-state solution (ODE)



Conditions for Explosions by the Neutrino Mechanism

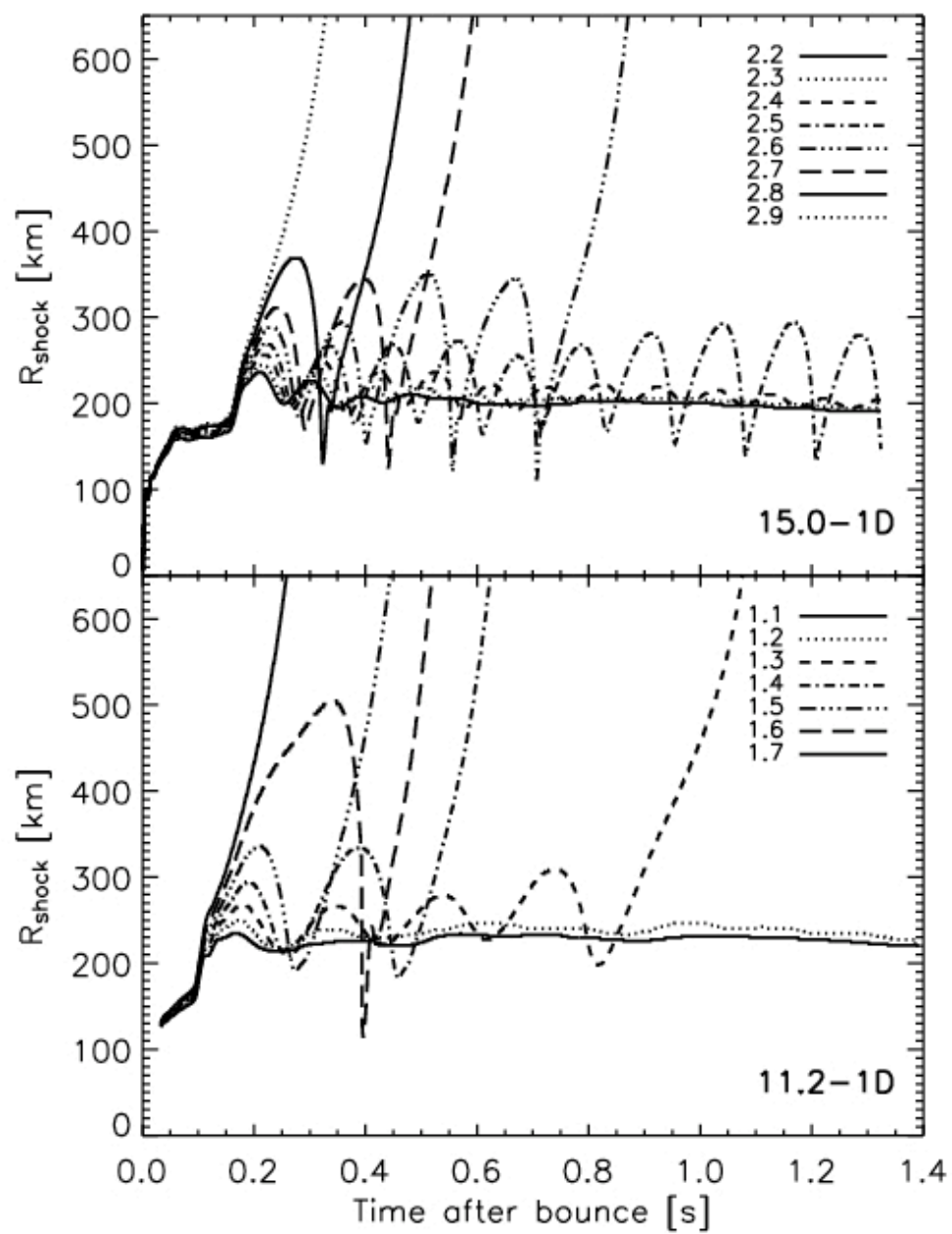
Parameter Study

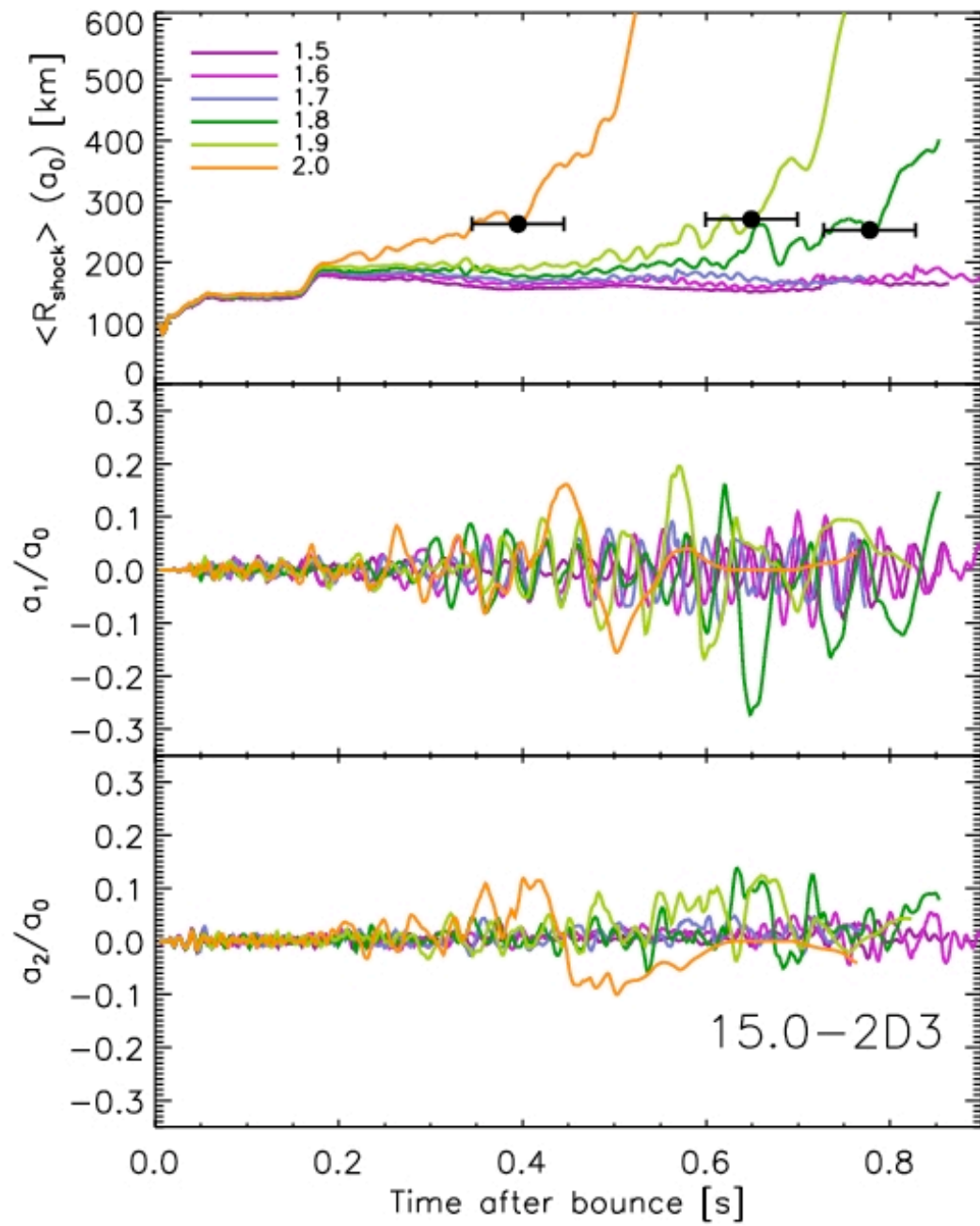
- Neutrino Luminosity (Local heating and cooling)
- 1D, 2D (90° and 180°)
- 11.2 and 15 M_{\odot} (range of accretion rates)
- Resolution
- ~100 simulations

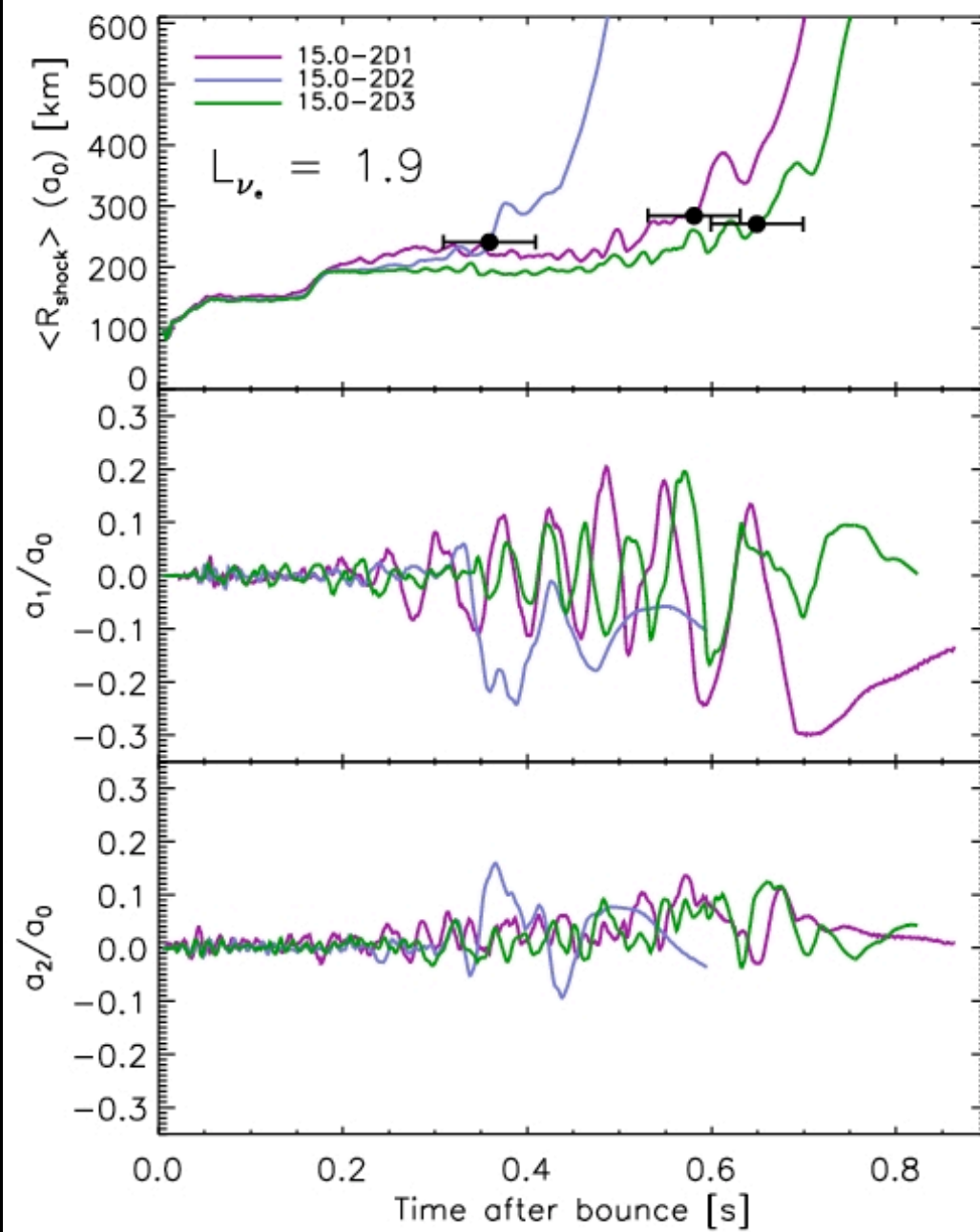


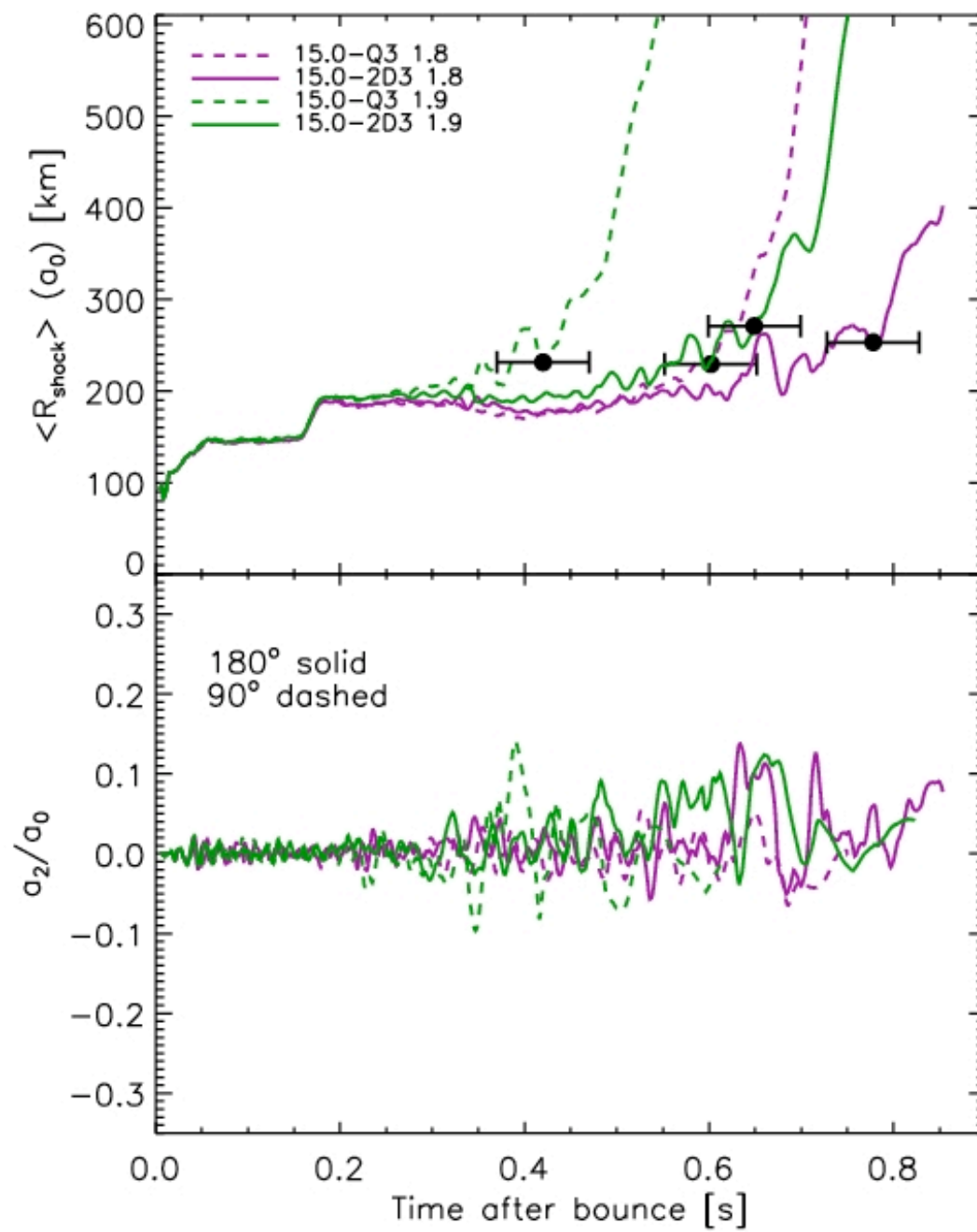
Is a critical luminosity relevant in hydrodynamic simulations?

- 1D
- 2D Convection and SASI?

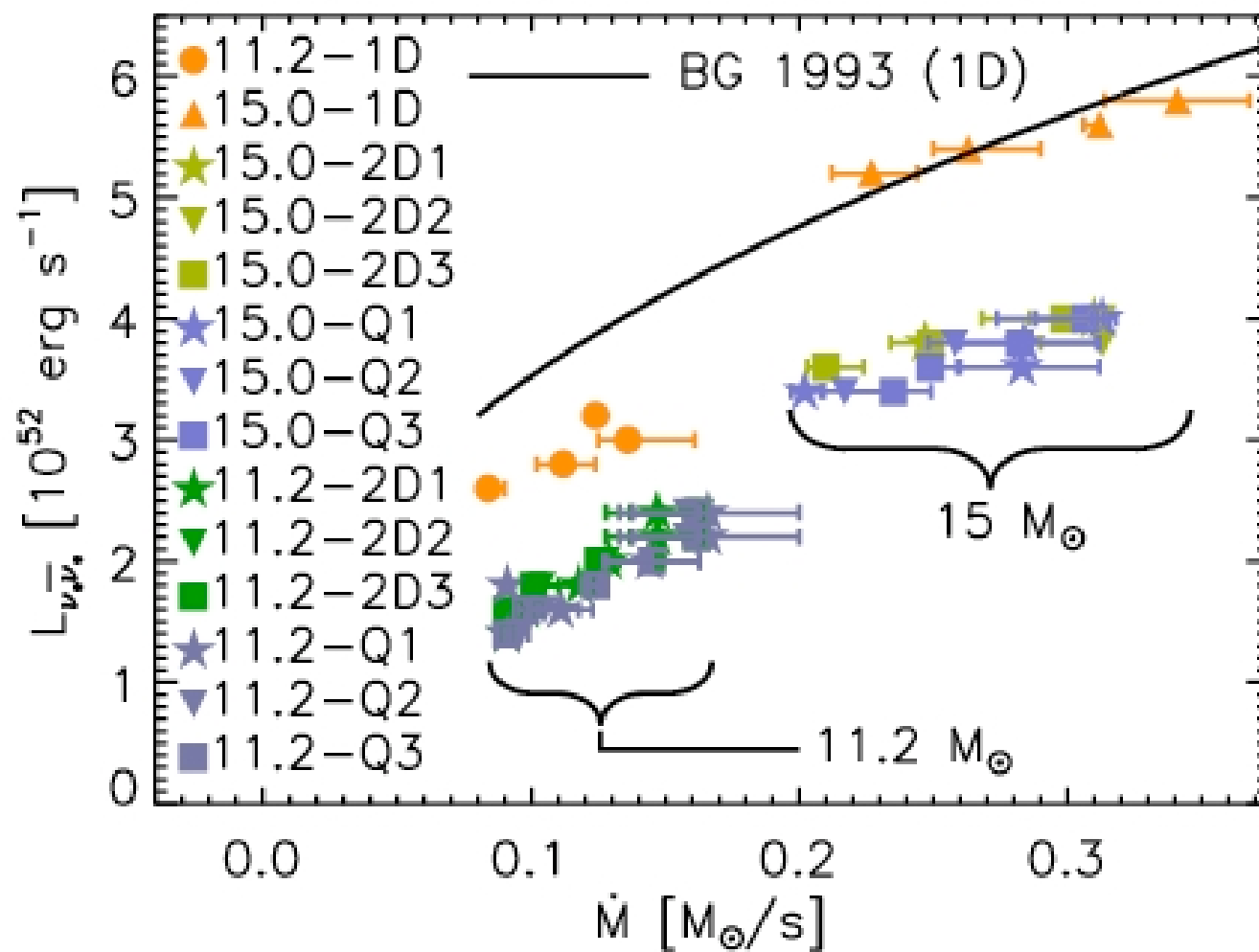






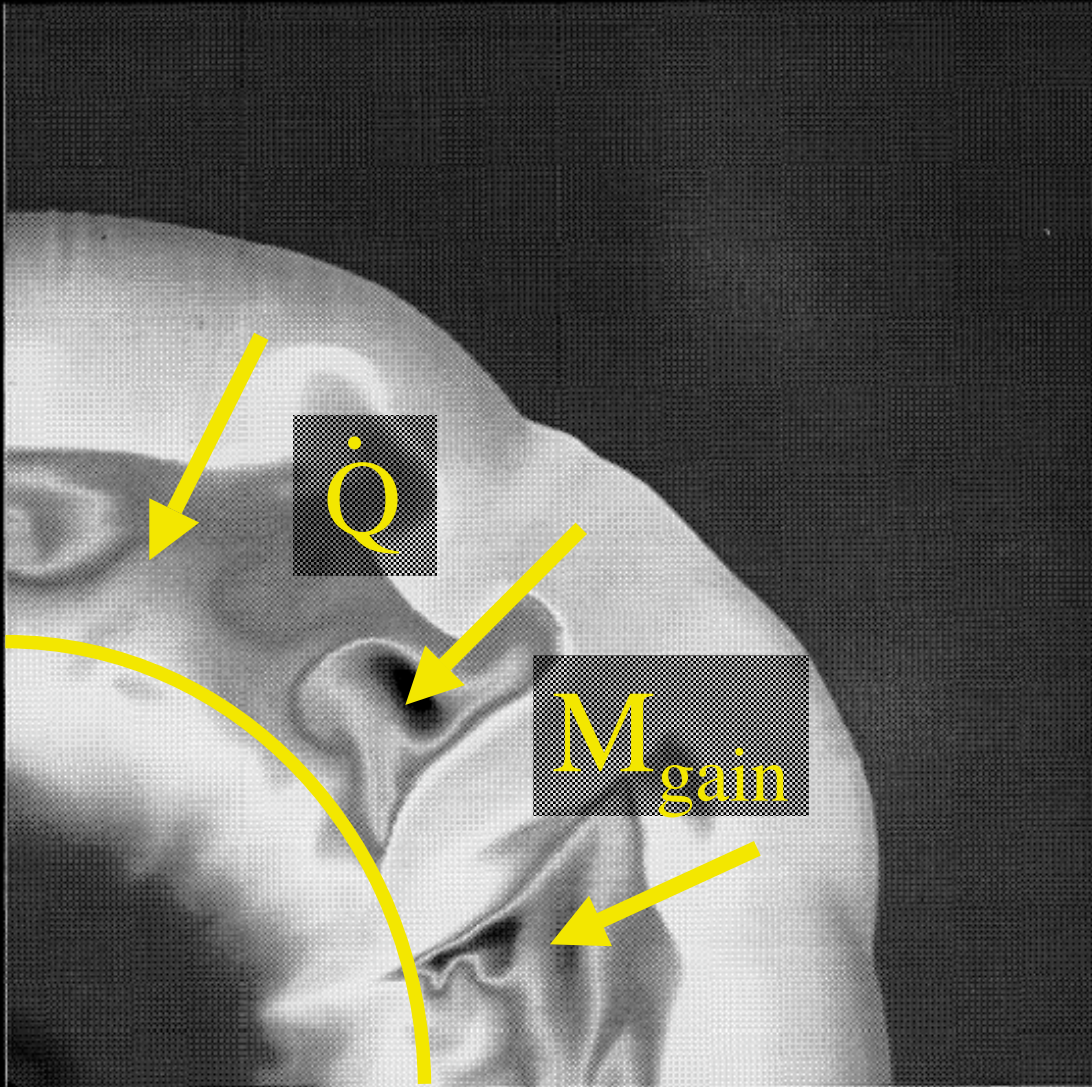


How do the critical luminosities
differ between 1D and 2D?



Why is critical luminosity of 2D
simulations $\sim 70\%$ of 1D?

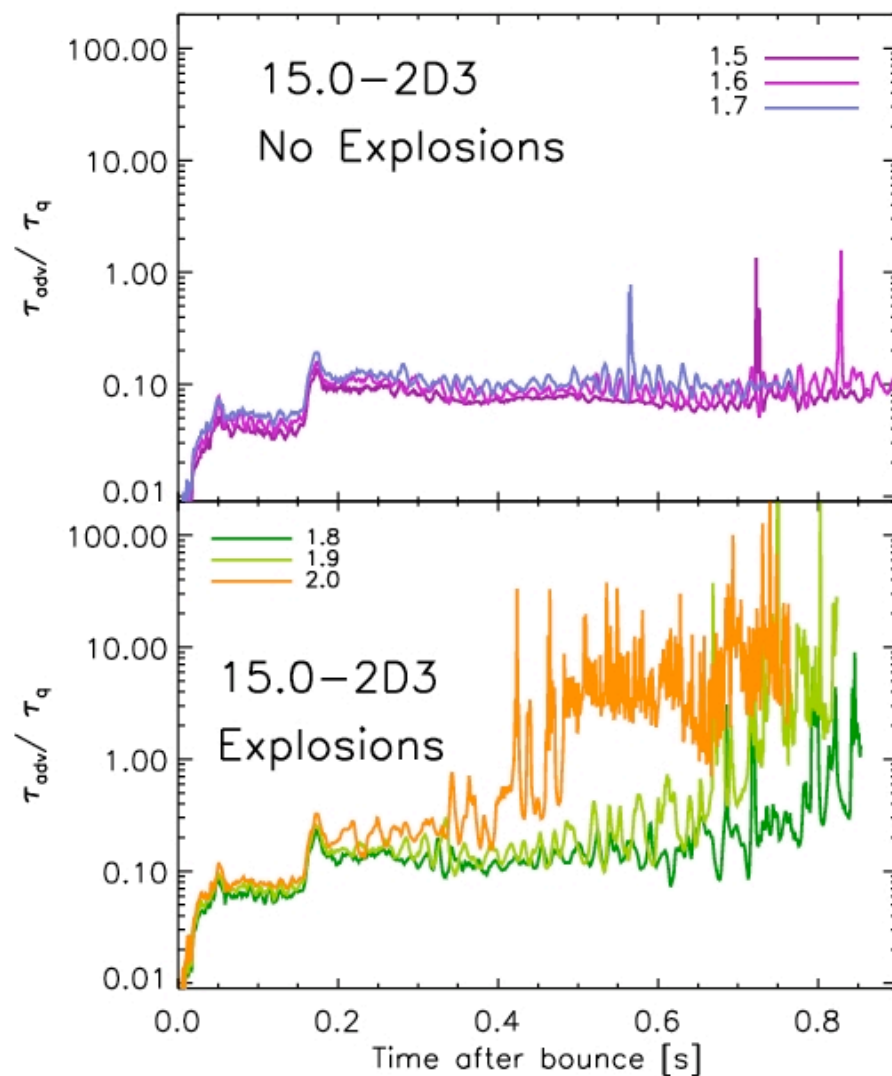
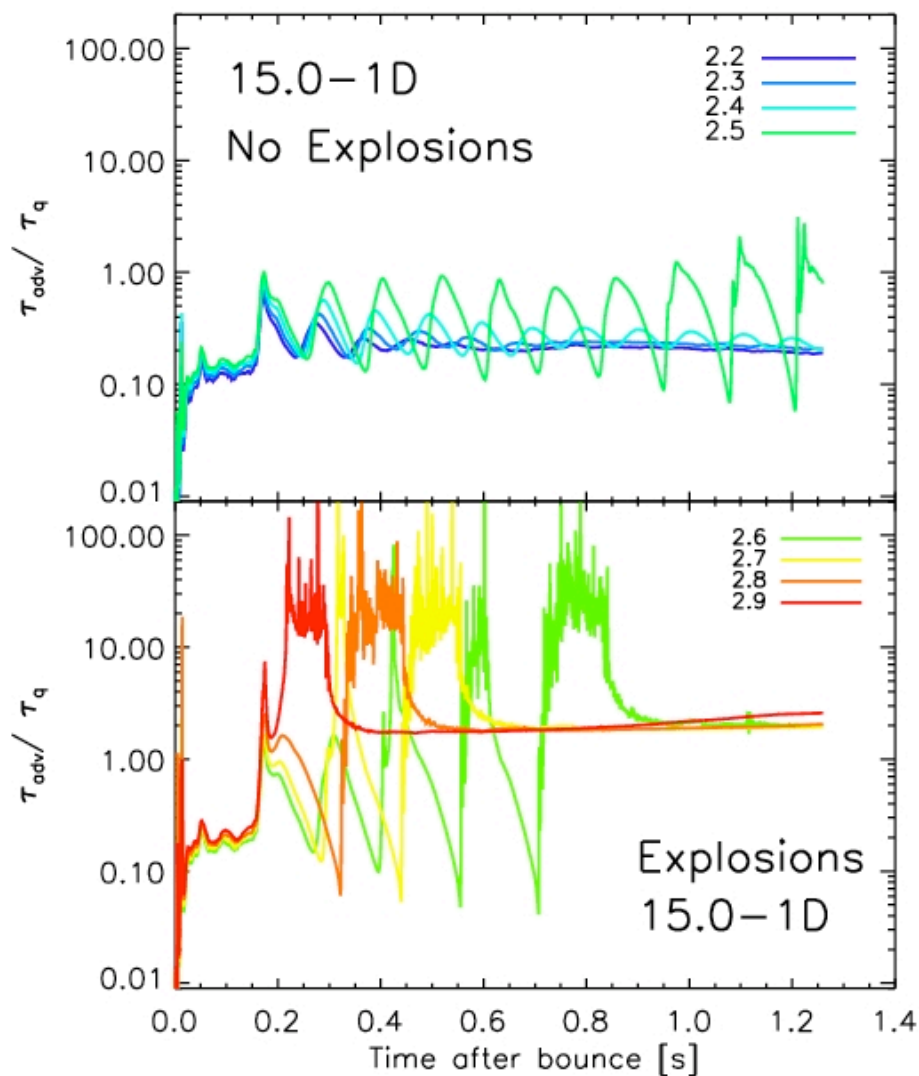
Conditions during Explosion



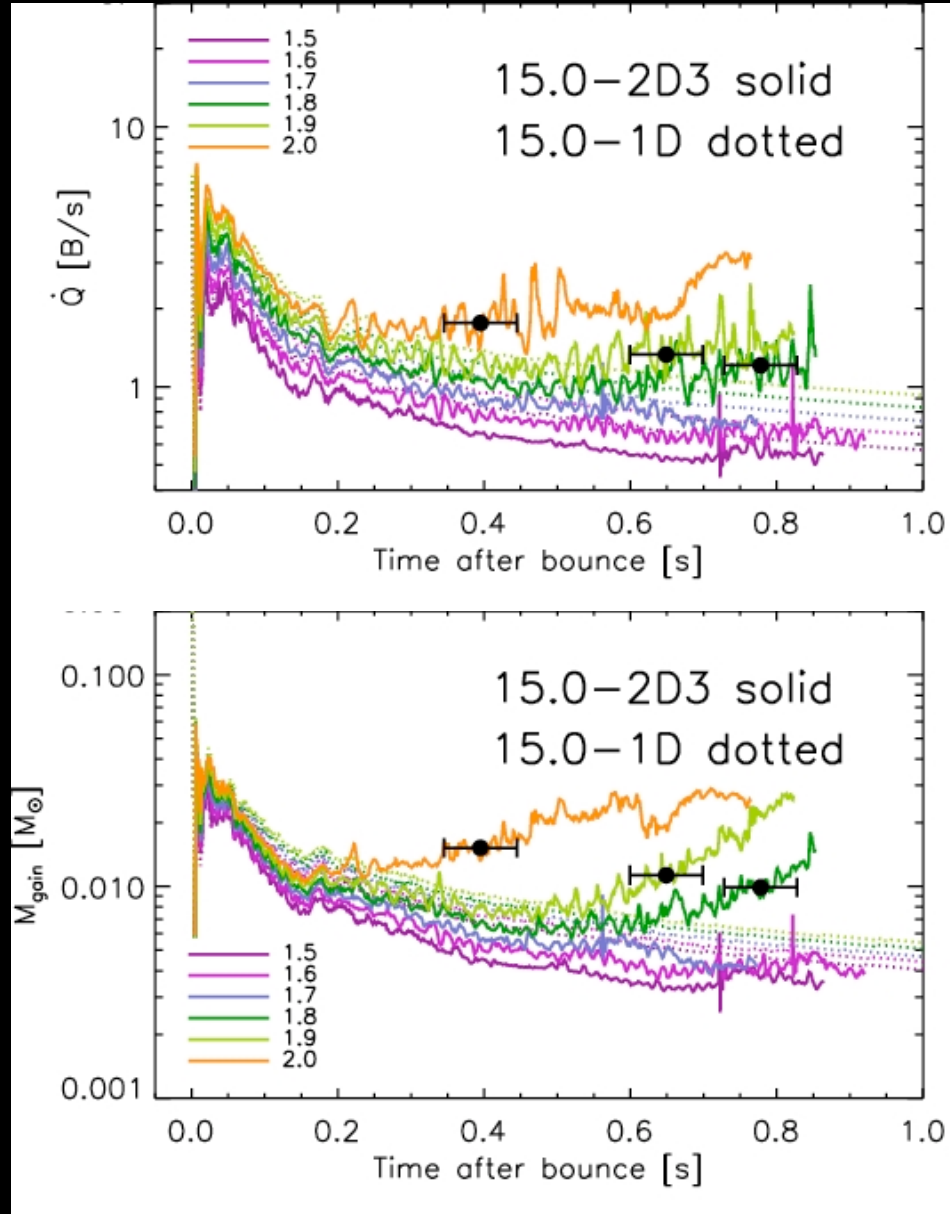
$$\tau_{\text{adv}} = \frac{\Delta r_{\text{gain}}}{v_r}$$

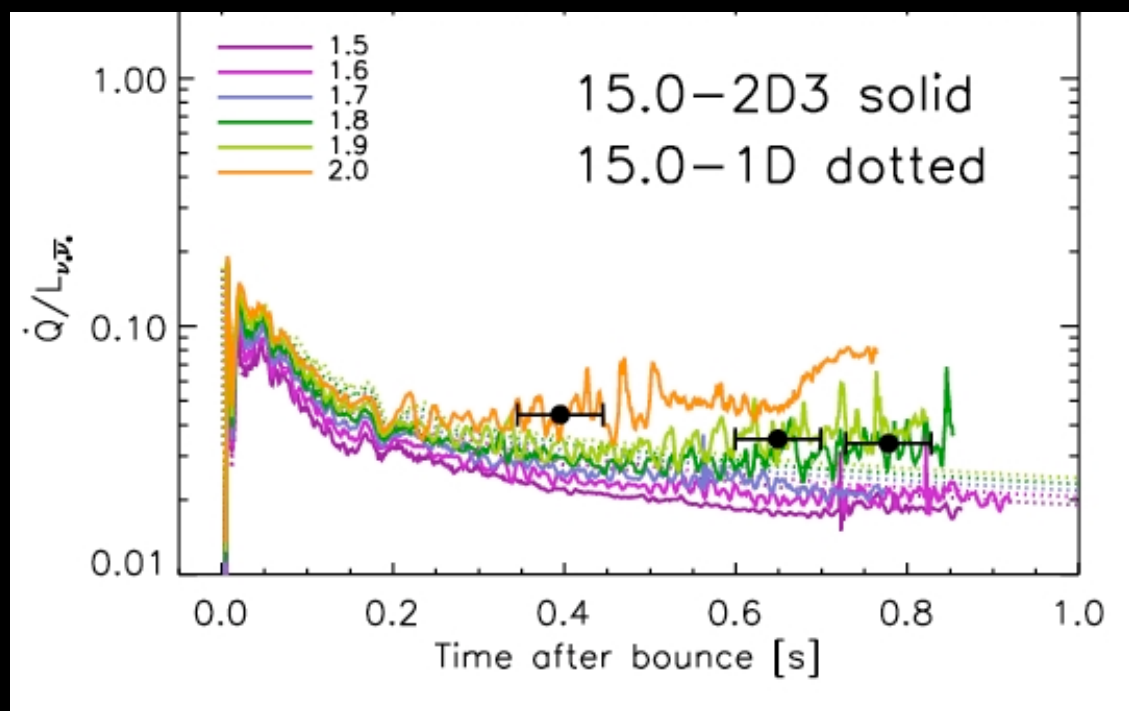
$$\tau_q = \frac{E}{\dot{Q}}$$

$$\frac{\tau_{\text{adv}}}{\tau_q} \gtrsim 1$$



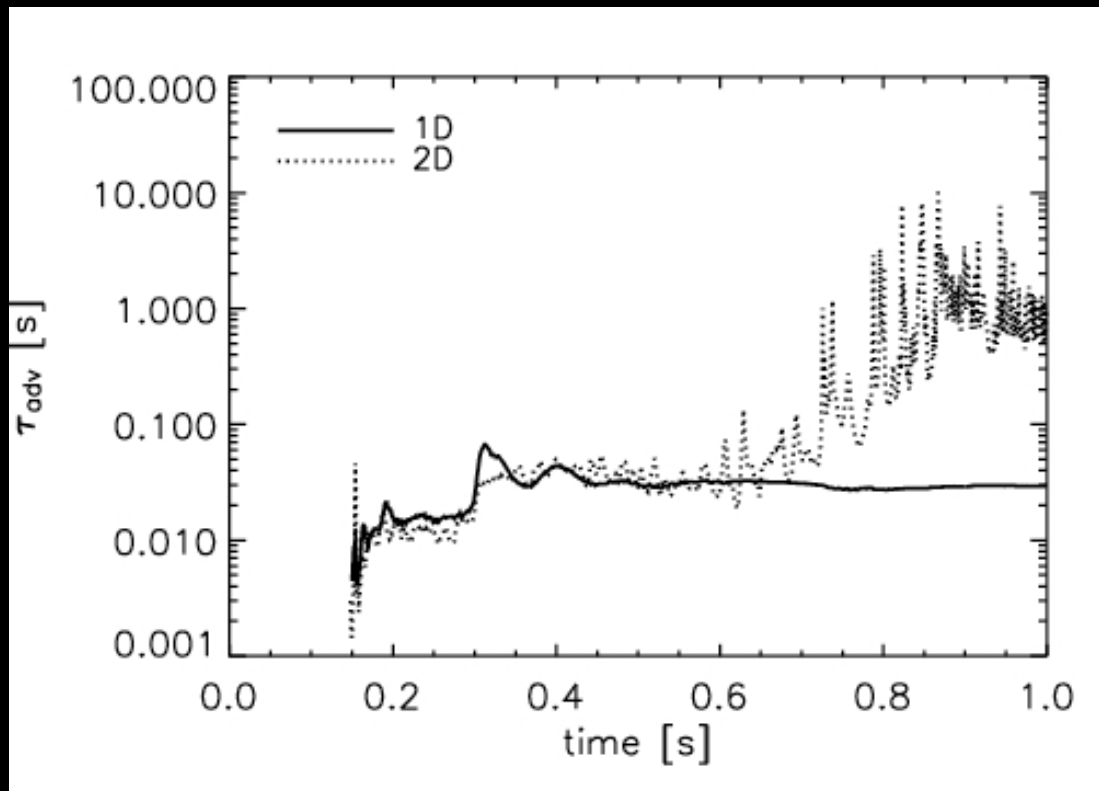
1D vs. 2D





Why?

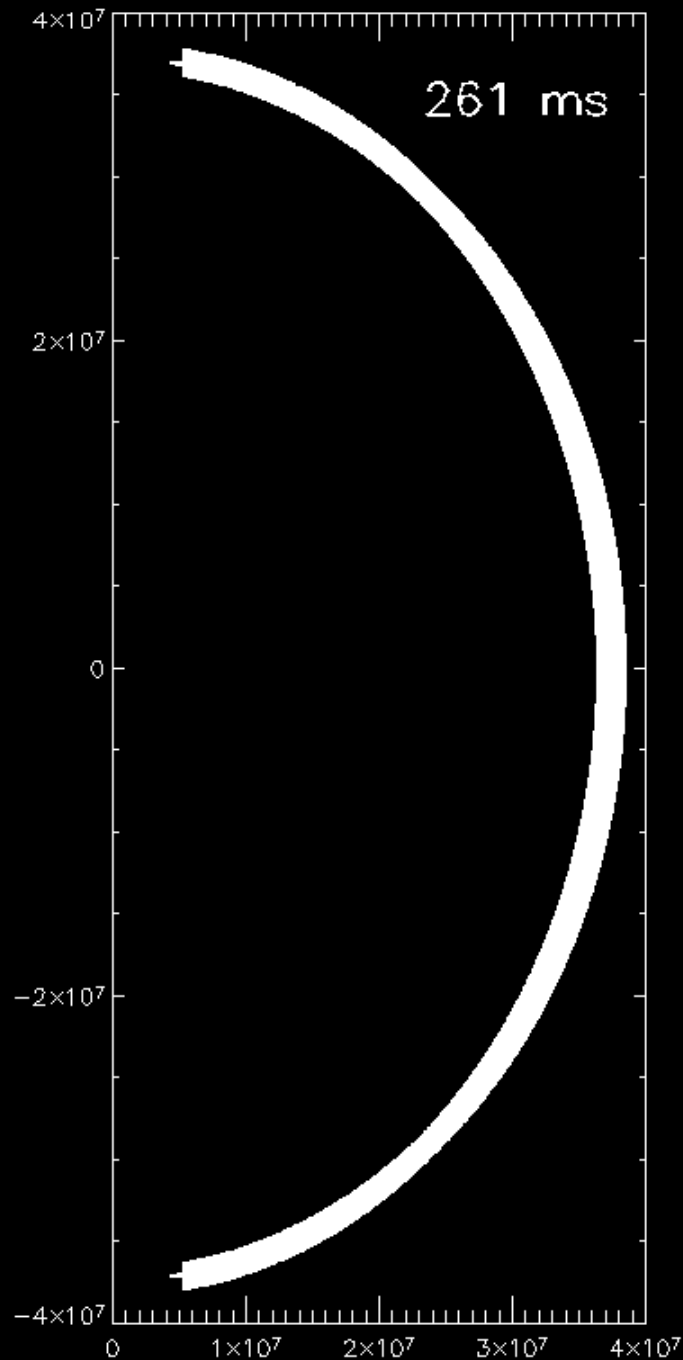
Average Advection Timescale



$$\langle v_r \rangle = \frac{\dot{M}}{4\pi r^2 \rho}$$

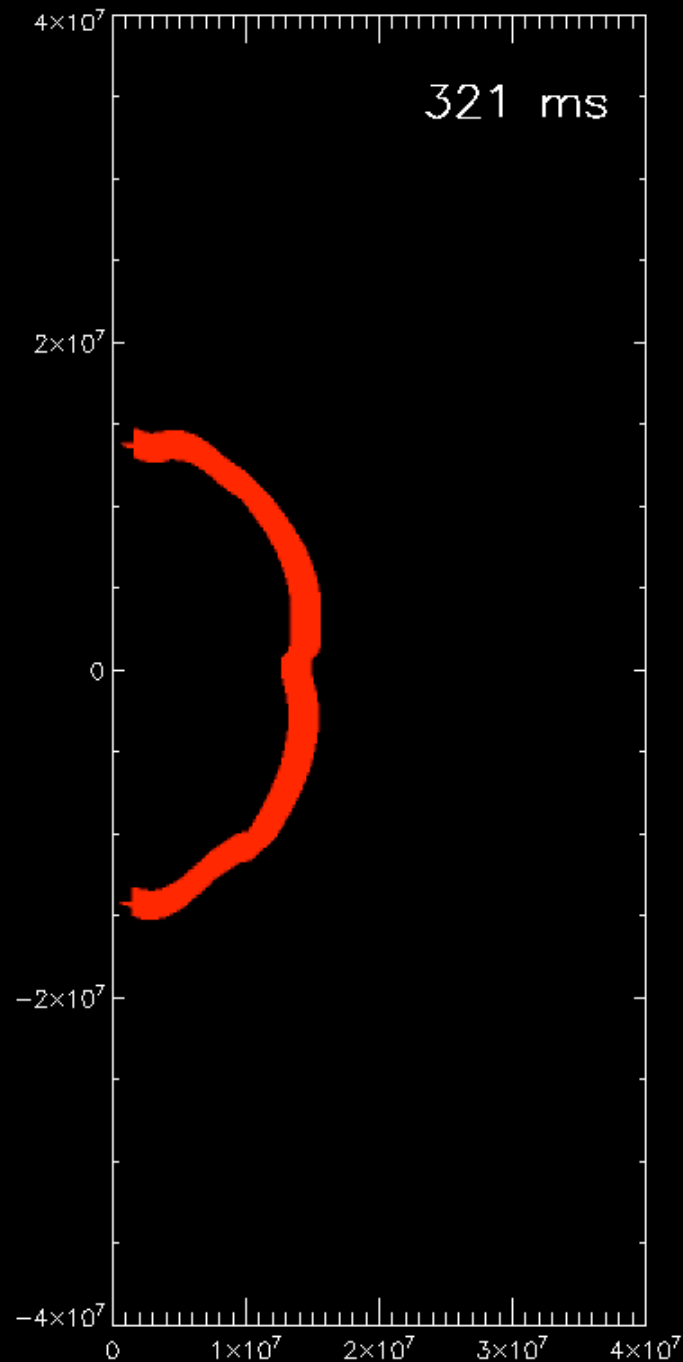
$$\tau_{adv} = \frac{\Delta r_{gain}}{v_r}$$

Distribution of Residence Times

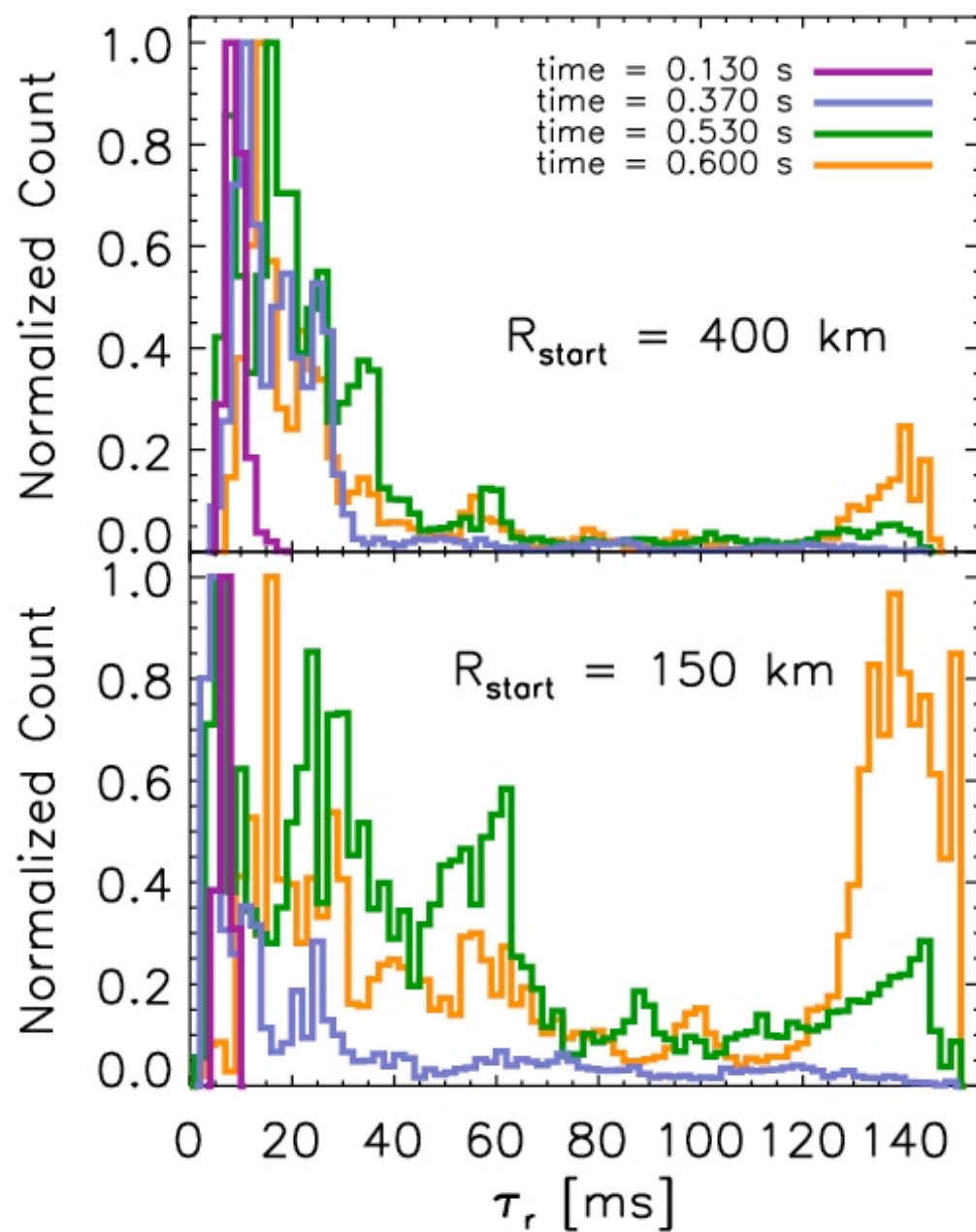
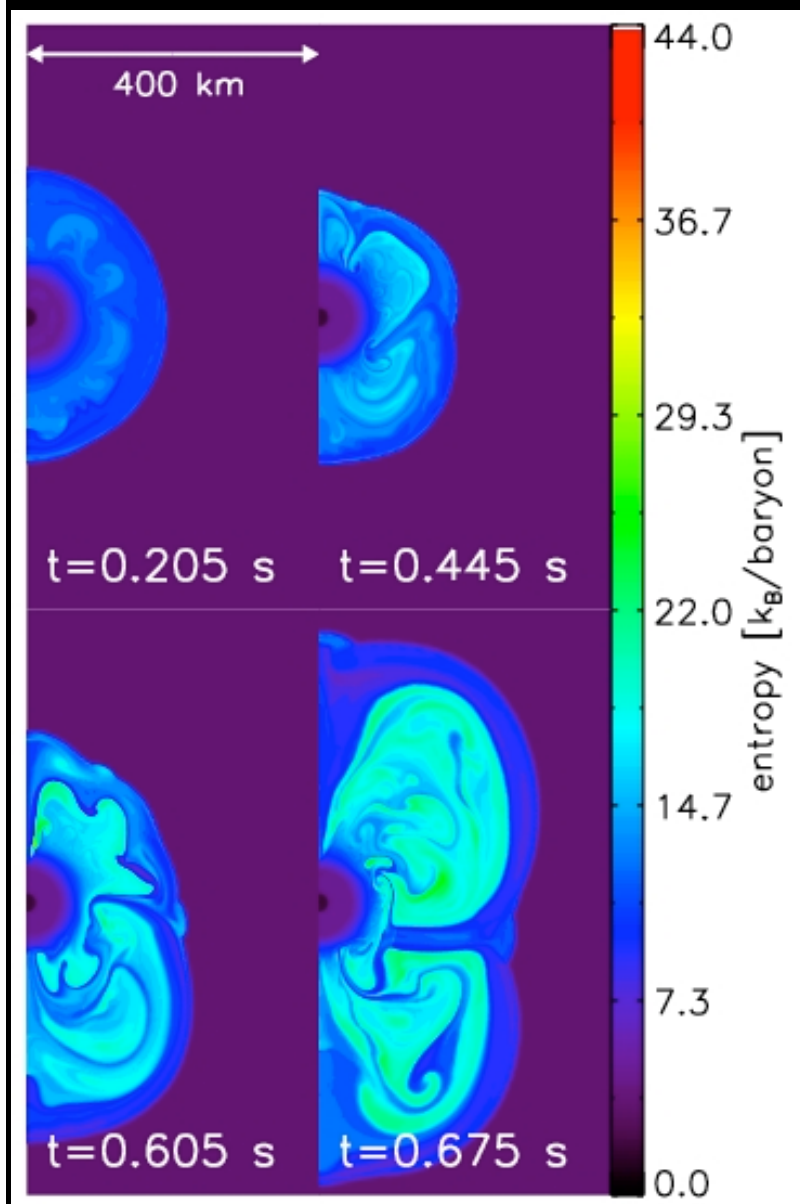


- 50,000 tracer particles at 400 km (**outside of shock**)
- Follow trajectories for 150 ms
- White = exterior to shock
- Red = net heating
- Blue = net cooling
- Distribution of τ_r
- **Most accrete through gain region quickly**

Distribution of Residence Times

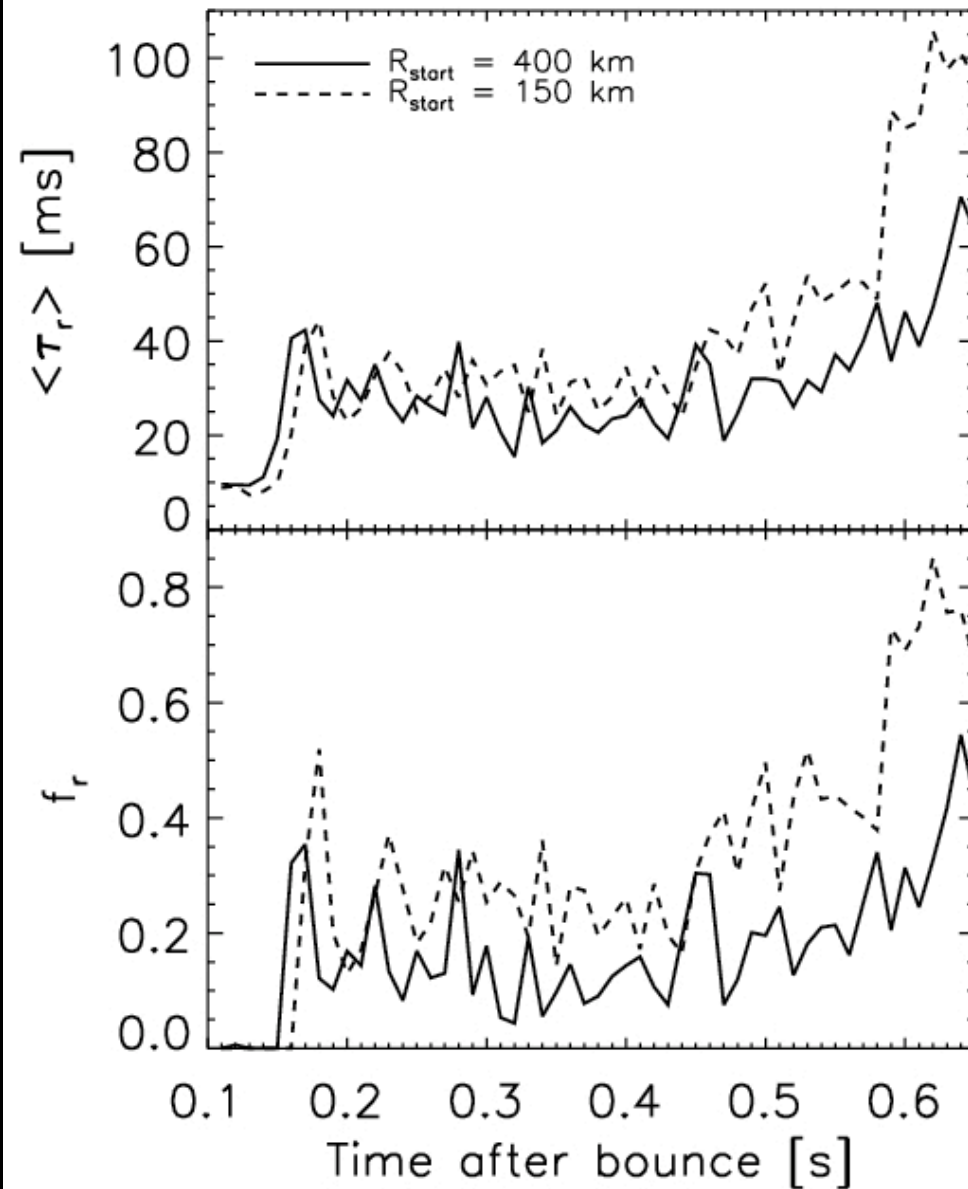


- 50,000 tracer particles at 150 km (inside gain region)
 - Follow trajectories for 150 ms
 - White = exterior to shock
 - Red = net heating
 - Blue = net cooling
 - Distribution of τ_r
-
- A larger fraction have longer dwell times



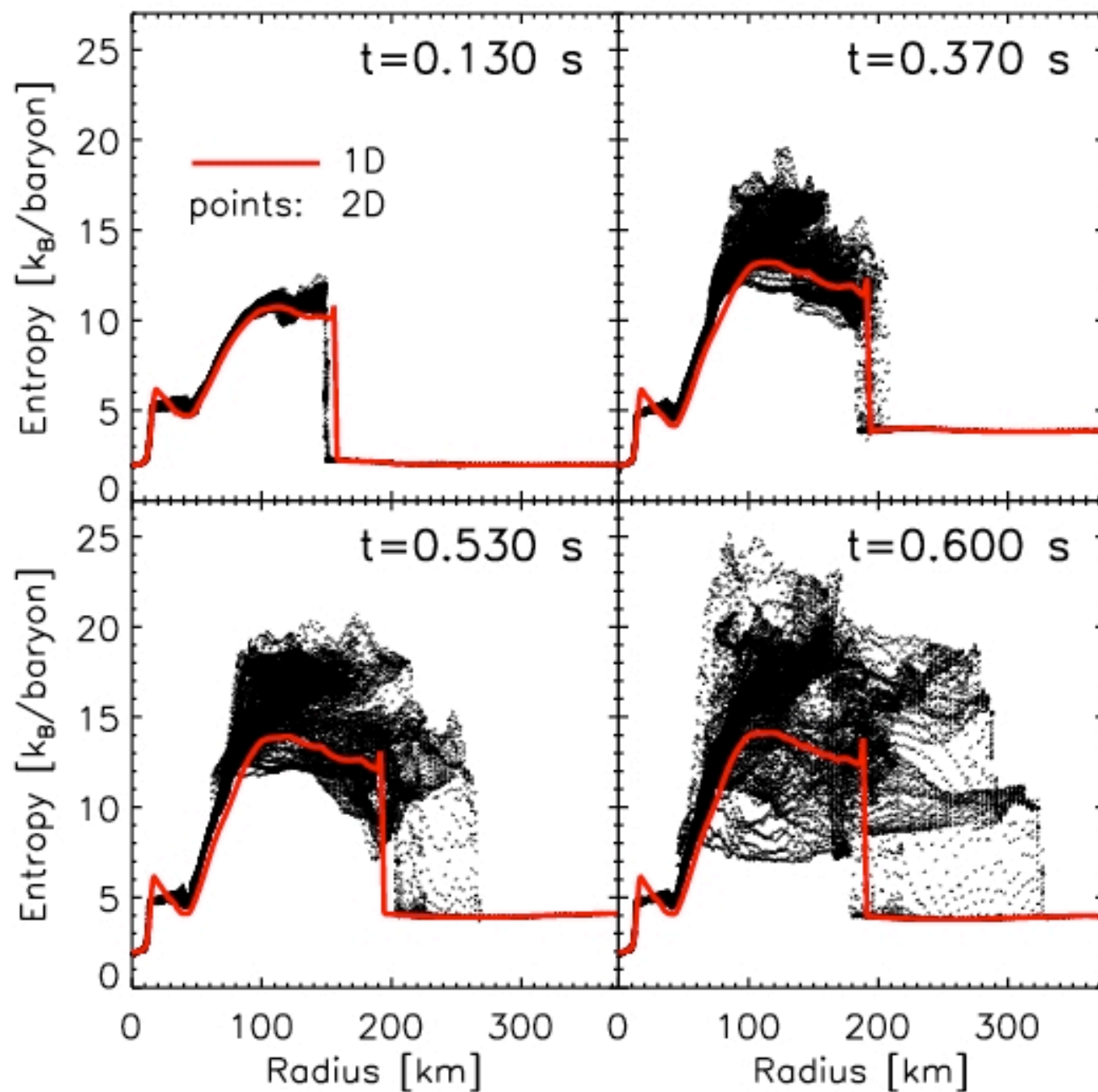
Average Residence Time

Fraction of particles
With $\tau_r > 40$ ms



Do large τ_r translate to extra heating?

$$\Delta S = \frac{Q}{T}$$



Conclusions

- Critical luminosity in hydrodynamic simulations (1D & 2D)
- Radial oscillations vs. SASI
- 2D $\sim 70\%$ of 1D
- Insensitive to resolution or angular domain
- Residence time in multi-D simulations
- Long τ_r explains reduction in critical luminosity

