# Observational constraints on the tidal parameters k<sub>2</sub> and Q in the solar system

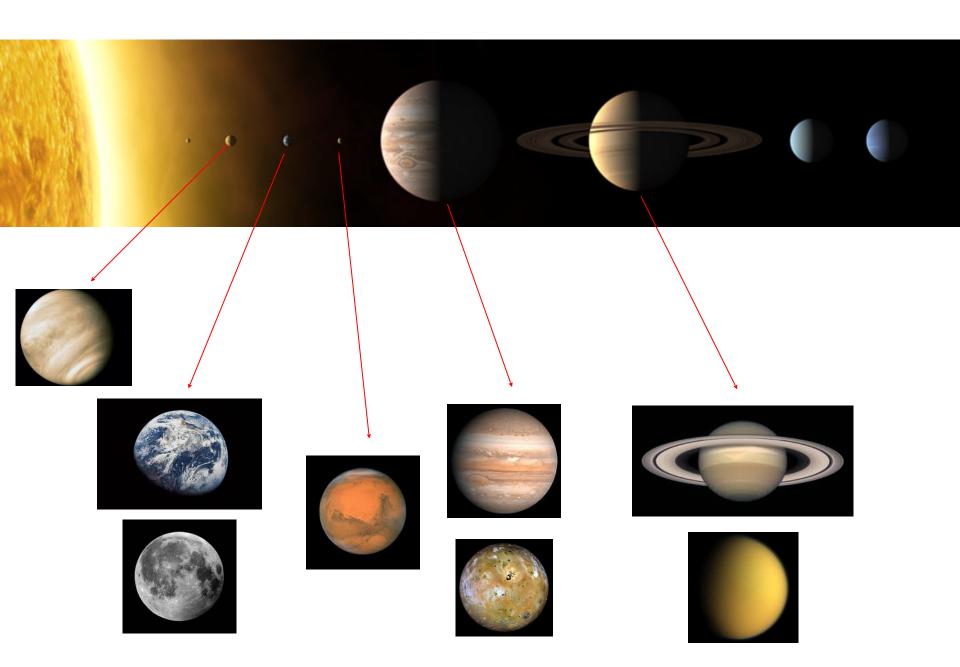
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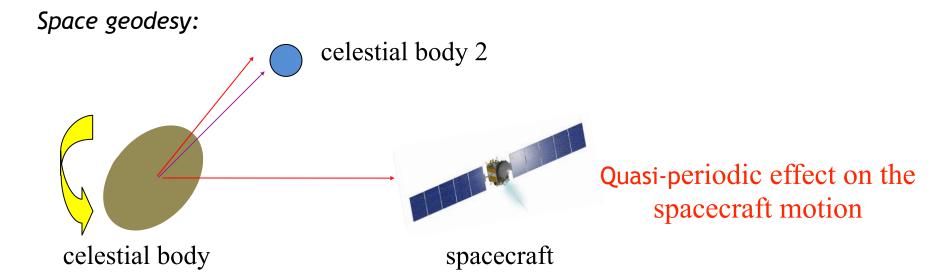


Workshop in Saclay, France. 18-21 november 2014

## Solar system bodies with tidal parameters known from observations



## <u>Determination of tidal parameters</u>



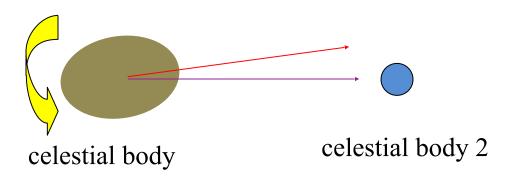
This method benefits from the accuracy of geodesic technics (SLR/GPS/altimetry/radio-science...)

Tidal lag is a small angle, hence difficult to catch...

Requires a spacecraft!

## **Determination of tidal parameters**

## Astrometry:



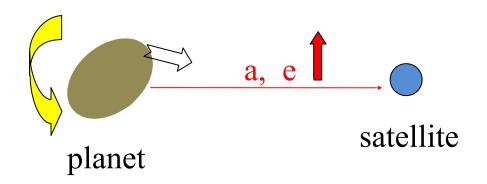
Secular effect on the orbit of the celestial body

The astrometric observations are much less accurate than geodesic ones (except for the LLR) but can be done from ground « rather » easily

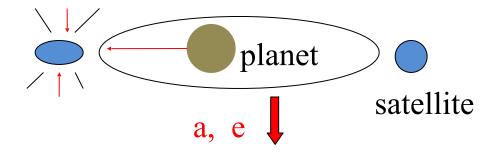
Pretty hard to separate k<sub>2</sub> and Q

Correlations arise when tidal dissipation arises in both celestial bodies

## Competition between tidal dissipation effects



Secular deceleration on the mean motion



Secular acceleration on the mean motion

## Orbit determination of natural satellites and spacecraft

NB: Orbit determination of natural satellites and spacecraft follow exactly the <u>same</u> methodology...

## Method in three steps:

- 1- modeling of the dynamical system
- 2- gathering the observations
- 3- fitting the model to the observations

Today, this kind of work is done completely numerically

S/C: GINS, DPODP, GEODYN, ...

SAT: NOE, ODYSSEY...

## Step 1: Modeling of the dynamical system

$$\ddot{\vec{r}}_{i}^{i} = -G(m_{0} + m_{i}) \left( \frac{\vec{r}_{i}}{r_{i}^{3}} - \nabla_{i} U_{\bar{i}\hat{0}} + \nabla_{0} U_{\bar{0}\hat{i}} \right) + \sum_{j=1, j \neq i}^{N} Gm_{j} \left( \frac{\vec{r}_{j} - \vec{r}_{i}}{r_{ij}^{3}} - \frac{\vec{r}_{j}}{r_{j}^{3}} - \nabla_{j} U_{\bar{j}\hat{i}} + \nabla_{i} U_{\bar{i}j} + \nabla_{j} U_{\bar{j}\hat{0}} - \nabla_{0} U_{\bar{0}\hat{j}} \right)$$

$$+\frac{(m_0+m_i)}{m_im_0} \left(\vec{F}_{\bar{i}\hat{0}}^T - \vec{F}_{\bar{0}\hat{i}}^T\right) - \frac{1}{m_0} \sum_{j=1, j \neq i}^{N} \left(\vec{F}_{\bar{j}\hat{0}}^T - \vec{F}_{\bar{0}\hat{j}}^T\right) + RT$$

## Step 1: Modeling of the dynamical system

$$\begin{split} \ddot{\vec{r}}_{i}^{!} &= -G(m_{0} + m_{i}) \Bigg( \frac{\vec{r}_{i}}{r_{i}^{3}} - \nabla_{i} U_{\bar{i}\,\hat{0}} + \nabla_{0} U_{\bar{0}\,\hat{i}} \Bigg) + \sum_{j=1,\,j\neq i}^{N} Gm_{j} \Bigg( \frac{\vec{r}_{j} - \vec{r}_{i}}{r_{ij}^{3}} - \frac{\vec{r}_{j}}{r_{j}^{3}} - \nabla_{j} U_{\bar{j}\,\hat{i}} + \nabla_{i} U_{\bar{j}\,\hat{0}} - \nabla_{0} U_{\bar{0}\,\hat{j}} \Bigg) \\ &+ \frac{(m_{0} + m_{i})}{m_{i} m_{0}} \Big( \vec{F}_{\bar{i}\,\hat{0}}^{T} - \vec{F}_{\bar{0}\,\hat{i}}^{T} \Big) - \frac{1}{m_{0}} \sum_{j=1,\,j\neq i}^{N} \Big( \vec{F}_{\bar{j}\,\hat{0}}^{T} - \vec{F}_{\bar{0}\,\hat{j}}^{T} \Big) + RT \end{split} \quad \text{N-body problem} \end{split}$$

## Step 1: Modeling of the dynamical system

$$\begin{split} \ddot{\vec{r}_{i}} &= -G(m_{0} + m_{i}) \Bigg( \frac{\vec{r}_{i}}{r_{i}^{3}} - \nabla_{i} U_{\vec{i} \, \hat{0}} + \nabla_{0} U_{\vec{0} \, \hat{i}} \Bigg) + \sum_{j=1, j \neq i}^{N} Gm_{j} \Bigg( \frac{\vec{r}_{j} - \vec{r}_{i}}{r_{ij}^{3}} - \frac{\vec{r}_{j}}{r_{j}^{3}} - \nabla_{j} U_{\vec{j} \, \hat{i}} + \nabla_{i} U_{\vec{j} \, \hat{j}} + \nabla_{j} U_{\vec{j} \, \hat{0}} - \nabla_{0} U_{\vec{0} \, \hat{j}} \Bigg) \\ &+ \frac{(m_{0} + m_{i})}{m_{i} m_{0}} \Big( \vec{F}_{\vec{i} \, \hat{0}}^{T} - \vec{F}_{\vec{0} \, \hat{i}}^{T} \Big) - \frac{1}{m_{0}} \sum_{j=1, j \neq i}^{N} \Big( \vec{F}_{\vec{j} \, \hat{0}}^{T} - \vec{F}_{\vec{0} \, \hat{j}}^{T} \Big) + RT \end{split}$$
N-body problem
Extended gravity fields

## Step 1: Modeling of the dynamical system

$$\ddot{\vec{r}}_{i}^{i} = -G(m_{0} + m_{i}) \left( \frac{\vec{r}_{i}}{r_{i}^{3}} - \nabla_{i}U_{\bar{i}\hat{0}} + \nabla_{0}U_{\bar{0}\hat{i}} \right) + \sum_{j=1, j \neq i}^{N} Gm_{j} \left( \frac{\vec{r}_{j} - \vec{r}_{i}}{r_{ij}^{3}} - \frac{\vec{r}_{j}}{r_{j}^{3}} - \nabla_{j}U_{\bar{j}\hat{i}} + \nabla_{i}U_{\bar{i}j} + \nabla_{j}U_{\bar{j}\hat{0}} - \nabla_{0}U_{\bar{0}\hat{j}} \right)$$

$$+\frac{(m_0+m_i)}{m_im_0}\left(\vec{F}_{\hat{i}\hat{0}}^T - \vec{F}_{\bar{0}\hat{i}}^T\right) - \frac{1}{m_0}\sum_{j=1,j\neq i}^N \left(\vec{F}_{\hat{j}\hat{0}}^T - \vec{F}_{\bar{0}\hat{j}}^T\right) + RT$$

$$= \frac{N-\text{body problem}}{\text{Extended gravity fields}}$$

$$= \frac{1}{m_0}\sum_{j=1,j\neq i}^N \left(\vec{F}_{\hat{j}\hat{0}}^T - \vec{F}_{\bar{0}\hat{j}}^T\right) + RT$$

## Step 1: Modeling of the dynamical system

## **Equations of motion**

$$\ddot{\vec{r}}_{i}^{i} = -G(m_{0} + m_{i}) \left( \frac{\vec{r}_{i}}{r_{i}^{3}} - \nabla_{i} U_{\bar{i}\hat{0}} + \nabla_{0} U_{\bar{0}\hat{i}} \right) + \sum_{j=1, j \neq i}^{N} Gm_{j} \left( \frac{\vec{r}_{j} - \vec{r}_{i}}{r_{ij}^{3}} - \frac{\vec{r}_{j}}{r_{j}^{3}} - \nabla_{j} U_{\bar{j}\hat{i}} + \nabla_{i} U_{\bar{i}j} + \nabla_{j} U_{\bar{j}\hat{0}} - \nabla_{0} U_{\bar{0}\hat{j}} \right)$$

$$+\frac{(m_{0}+m_{i})}{m_{i}m_{0}}\left(\vec{F}_{\bar{i}\hat{0}}^{T}-\vec{F}_{\bar{0}\hat{i}}^{T}\right)-\frac{1}{m_{0}}\sum_{j=1,j\neq i}^{N}\left(\vec{F}_{\bar{j}\hat{0}}^{T}-\vec{F}_{\bar{0}\hat{j}}^{T}\right)+RT$$

N-body problem
Extended gravity fields
Tidal effects

\* Relativistic terms

## Step 1: Modeling of the dynamical system

## **Equations of motion**

$$\ddot{\vec{r}}_{i}^{i} = -G(m_{0} + m_{i}) \left( \frac{\vec{r}_{i}}{r_{i}^{3}} - \nabla_{i}U_{\bar{i}\hat{0}} + \nabla_{0}U_{\bar{0}\hat{i}} \right) + \sum_{j=1, j \neq i}^{N} Gm_{j} \left( \frac{\vec{r}_{j} - \vec{r}_{i}}{r_{ij}^{3}} - \frac{\vec{r}_{j}}{r_{j}^{3}} - \nabla_{j}U_{\bar{j}\hat{i}} + \nabla_{i}U_{\bar{i}j} + \nabla_{j}U_{\bar{j}\hat{0}} - \nabla_{0}U_{\bar{0}\hat{j}} \right)$$

$$+\frac{(m_{0}+m_{i})}{m_{i}m_{0}}\left(\vec{F}_{\bar{i}\hat{0}}^{T}-\vec{F}_{\bar{0}\hat{i}}^{T}\right)-\frac{1}{m_{0}}\sum_{j=1,j\neq i}^{N}\left(\vec{F}_{\bar{j}\hat{0}}^{T}-\vec{F}_{\bar{0}\hat{j}}^{T}\right)+RT$$

N-body problem
Extended gravity fields
Tidal effects
Relativistic terms

Initial conditions are required to solve for equations of motion...

Problem: How will we find the « real » initial conditions of the system we consider?

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Clearly we need to know at every observation time t the quantity  $\frac{\partial r_i}{\partial c_i}$ 

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## **Variational equations**

$$\frac{d^2 \vec{r}_i}{dt^2} = \frac{1}{m_i} \vec{F}_i$$

Problem: How can we find the « real » initial conditions of the system we consider? Clearly we need to know at every observation time t the quantity  $\frac{\partial \vec{r}_i}{\partial r_i}$ 

Variational equations

$$\frac{d^{2}\vec{r}_{i}}{dt^{2}} = \frac{1}{m_{i}}\vec{F}_{i} \qquad \qquad \frac{\partial}{\partial c_{l}} \left(\frac{d^{2}\vec{r}_{i}}{dt^{2}}\right) = \frac{1}{m_{i}}\frac{\partial \vec{F}_{i}}{\partial c_{l}}$$

Problem: How can we find the « real » initial conditions of the system we consider? Clearly we need to know at every observation time t the quantity  $\frac{\partial \vec{r}_i}{\partial r_i}$ 

## **Variational** equations

$$\frac{d^2 \vec{r}_i}{dt^2} = \frac{1}{m_i} \vec{F}_i \qquad \qquad \frac{\partial}{\partial c_l} \left( \frac{d^2 \vec{r}_i}{dt^2} \right) = \frac{1}{m_i} \frac{\partial \vec{F}_i}{\partial c_l}$$

$$\frac{\partial}{\partial c_{l}} \left( \frac{d^{2} \vec{r}_{i}}{dt^{2}} \right) = \frac{1}{m_{i}} \left[ \sum_{j} \left( \frac{\partial \vec{F}_{i}}{\partial \vec{r}_{j}} \frac{\partial \vec{r}_{j}}{\partial c_{l}} + \frac{\partial \vec{F}_{i}}{\partial \dot{\vec{r}}_{j}} \frac{\partial \dot{\vec{r}}_{j}}{\partial c_{l}} \right) + \frac{\partial \vec{F}_{i}}{\partial c_{l}} \right]$$

Problem: How can we find the « real » initial conditions of the system we consider?

Clearly we need to know at every observation time t the quantity  $\frac{\partial \vec{r}_i}{\partial c_l}$ 

## **Variational equations**

$$\frac{d^{2}\vec{r}_{i}}{dt^{2}} = \frac{1}{m_{i}}\vec{F}_{i}$$

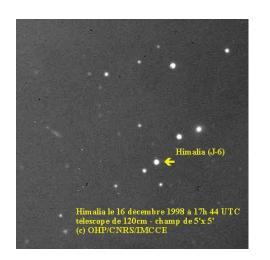
$$\frac{\partial}{\partial c_{l}}\left(\frac{d^{2}\vec{r}_{i}}{dt^{2}}\right) = \frac{1}{m_{i}}\frac{\partial \vec{F}_{i}}{\partial c_{l}}$$

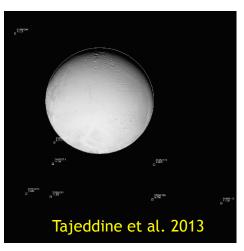
$$\frac{\partial}{\partial c_{l}} \left( \frac{d^{2} \vec{r}_{i}}{dt^{2}} \right) = \frac{1}{m_{i}} \left[ \sum_{j} \left( \frac{\partial \vec{F}_{i}}{\partial \vec{r}_{j}} \frac{\partial \vec{r}_{j}}{\partial c_{l}} + \frac{\partial \vec{F}_{i}}{\partial \dot{\vec{r}}_{j}} \frac{\partial \dot{\vec{r}}_{j}}{\partial c_{l}} \right) + \frac{\partial \vec{F}_{i}}{\partial c_{l}} \right]$$

Computation of variational equations can be time consuming and requires a lot of development time!

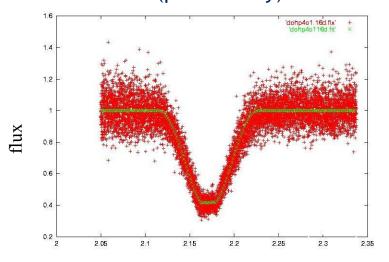
## Step 2: gathering the observations

#### Direct astrometric measurement

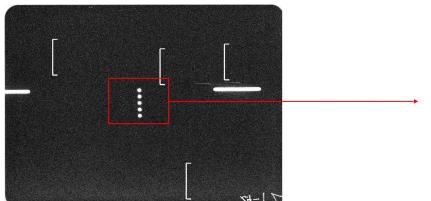


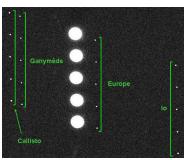


Undirect astrometric measurement (photometry)

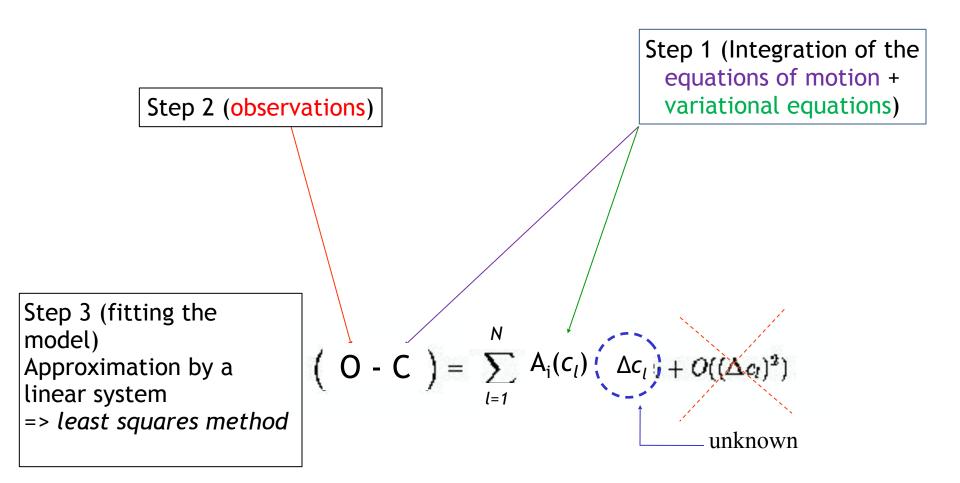


Astrometric remeasurement (benefit from modern scanning machine)

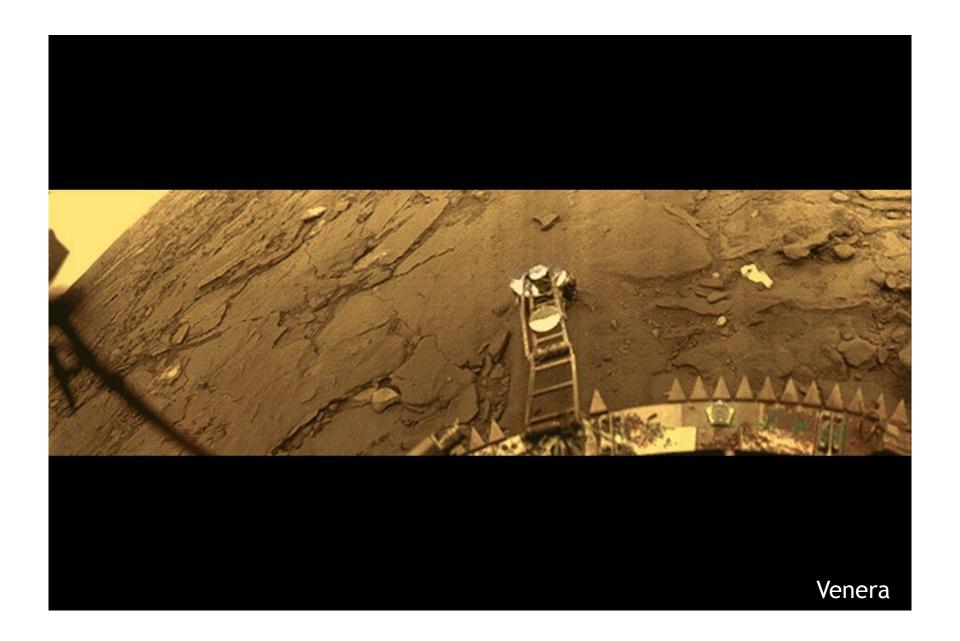




Step 3: Fitting the model to the observations

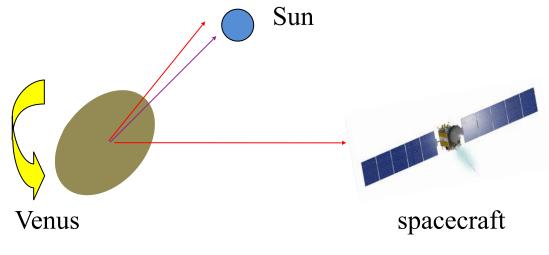


# <u>Venus</u>



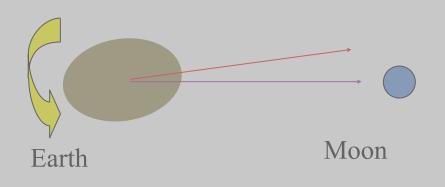
## **Venus**

## Space geodesy:



Allows the determination of Venus: k<sub>2</sub>

## Astrometry:

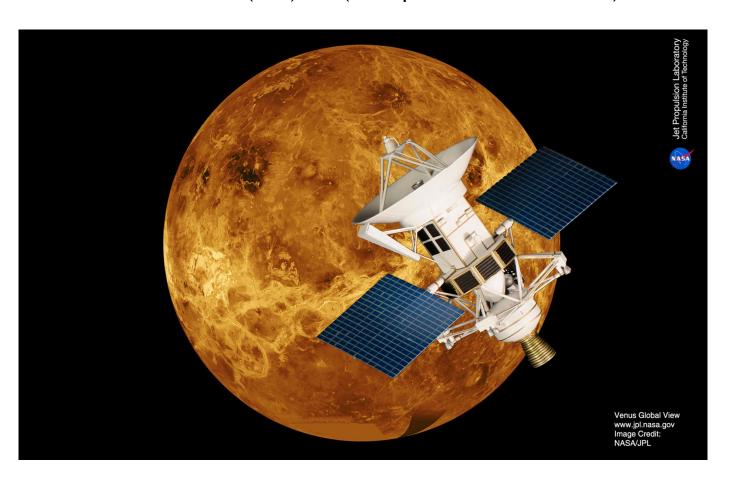


Allows the determination of Earth:  $k_2/Q$  (ocean tide)
Moon:  $k_2$  and Q

## **Venus**

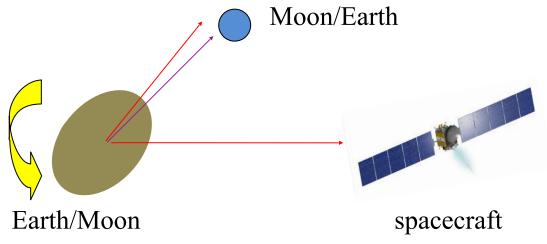
The only measurement so far comes from Magellan and Pioneer Venus Orbiter spacecraft

$$k_2=0.295 + (-0.066 (2-\sigma))$$
 (Konopliv and Yoder 1996)





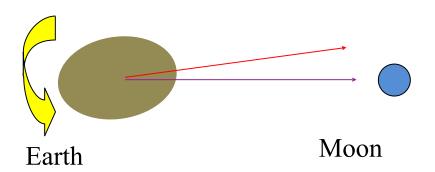
## Space geodesy:



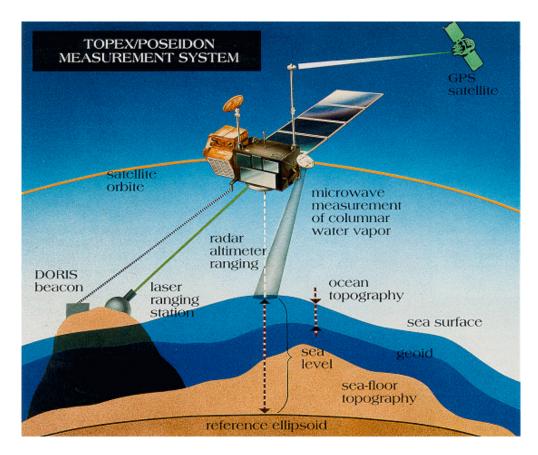
Allows the determination of Earth: k<sub>2</sub> and Q (both ocean and terrestrial tide)

Moon: k<sub>2</sub>

## Astrometry:



Allows the determination of Earth:  $k_2/Q$  (ocean tide)
Moon:  $k_2$  and Q



The first reliable estimate of the Earth's Q associated to terrestrial tide is from Ray et al. Nature 1996

$$Q = 370 (200, 800)$$

later improved by Ray et al. 2001

$$Q = 280 (230, 360)$$

using  $k_2$ =0.302 (Lerch et al. 1992; Lemoine et al. 1998)

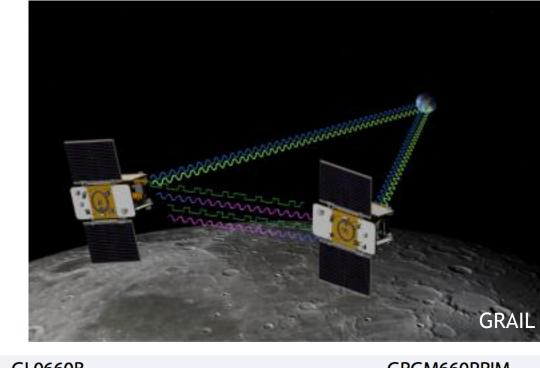
A real challenge: separating the terrestrial tide from the ocean tide (much more significant)

The GRAIL mission allows an unprecedented accuracy in our knowledge of the Lunar

gravity field.

Combined with Lunar Laser Ranging (LLR), a full solution including gravity harmonics up to degree and order 420.

From LLR the Lunar Q is estimated to be Q=37.5 +/- 4 (Williams et al. JGR 2014)



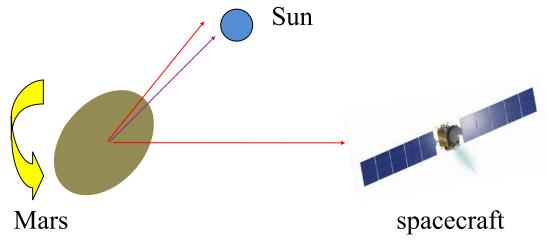
Parameter	GLUOOUB	GRGMOOUPRIM
R	1738.0 km	1738.0 km
k <sub>20</sub>	$0.02408 \pm 0.00045$	$0.024165 \pm 0.00228$
k <sub>21</sub>	$0.02414 \pm 0.00025$	$0.023915 \pm 0.00033$
k <sub>22</sub>	$0.02394 \pm 0.00028$	$0.024852 \pm 0.00042$
k <sub>2</sub>	$0.02405 \pm 0.000176$	$0.02427 \pm 0.00026$
k <sub>30</sub>		$0.00734 \pm 0.00375$
k <sub>3</sub>	$0.0089 \pm 0.0021$	

# The Mars system



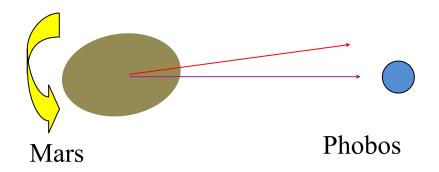
## Example of the Mars system

## Space geodesy:



Allows the determination of k<sub>2</sub>

## Astrometry:



Allows the determination of  $k_2/Q$ 

## Example of the Mars system

## Estimation of the Mars Love number from Mars' spacecraft

Spacecraft	$Re(k_2)$ , $Im(k_2) = 0$	$Re(k_2)$ , $Im(k_2) = 0.01$	$Re(k_2)$ , $Im(k_2)$ est.	Notes
MGS	0.173 ± 0.009	0.168 ± 0.009	$0.159 \pm 0.016$ $0.023 \pm 0.025$	Best overall solution this paper $\text{Im}(k_2)$ = 0, 5× formal $\sigma$
MGS	$0.153 \pm 0.017$			Data to April 14, 2002, Yoder et al. (2003)
MGS	$0.166 \pm 0.011$			Data to December 5, 2004, Konopliv et al. (2006)
ODY	0.172 ± 0.014	0.185 ± 0.014	0.167 ± 0.025 -0.004 ± 0.016	Without arcs affected by dust, best Odyssey solution $\text{Im}(k_2)$ = 0, $10 \times$ formal $\sigma$
ODY	$0.104 \pm 0.013$		0.015 ± 0.021 -0.076 ± 0.014	All arcs but with no dust model
ODY	$0.161 \pm 0.013$	$0.173 \pm 0.013$	0.131 ± 0.022 -0.025 ± 0.014	All arcs but with dust model to 30–40 km
ODY	$0.172 \pm 0.013$	$0.184 \pm 0.013$	0.154 ± 0.022 -0.015 ± 0.014	All arcs but with dust model to 30–50 km
MRO	0.175 ± 0.010	0.175 ± 0.010	$0.176 \pm 0.010$ $0.036 \pm 0.040$	10 $ imes$ formal $\sigma$
Other determi	nations			
MGS	$0.201 \pm 0.059$			Bills et al. (2005)
	$0.163 \pm 0.056$			
MGS	$0.176 \pm 0.041$			Lemoine et al. (2006)
MGS	$0.130 \pm 0.030$			Balmino et al. (2005) (see Marty et al., 2009)
MGS + ODY	$0.120 \pm 0.003$			Marty et al. (2009)

Konopliv et al. (2011) provides  $k_2=0.164 +/- 0.009$ 

The various estimation of the tidal Love number  $k_2$  have changed much in the last decade.

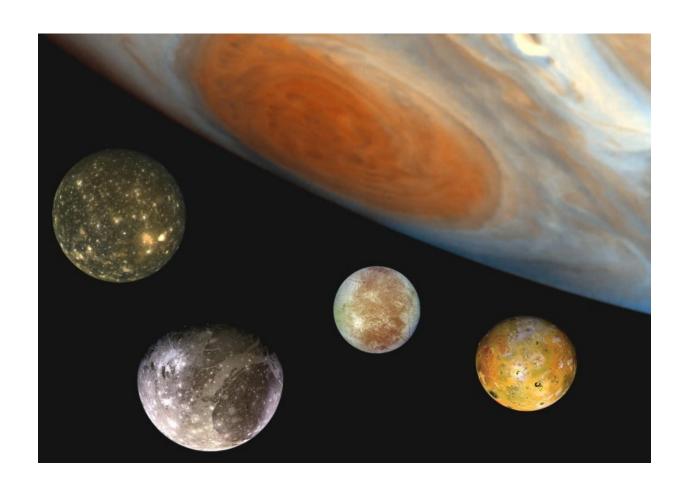
## Example of the Mars system

Estimation of Phobos tidal acceleration over time (Jacobson 2010):

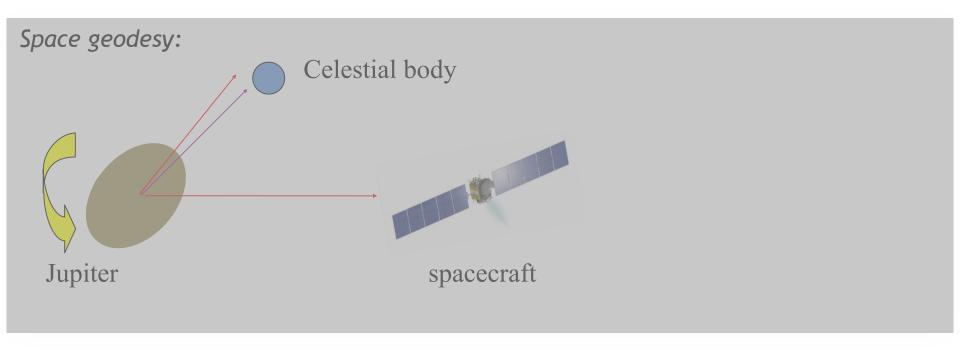
Reference	$s \times 10^{-3}$	κ2	Q	γ
	$(\text{deg yr}^{-2})$			(deg)
Sharpless (1945)	$1.882 \pm 0.171$			
Shor (1975)	$1.427 \pm 0.147$			
Sinclair (1978)	$1.326 \pm 0.118$			
Jacobson et al. (1989)	$1.249 \pm 0.018$			
Chapront-Touzé (1990)	$1.270 \pm 0.008$			
Emelyanov et al. (1993)	$1.290 \pm 0.010$			
Bills et al. (2005)	$1.367 \pm 0.006$	0.163	$85.6 \pm 0.4$	$0.3346 \pm 0.0014$
Rainey & Aharonson (2006)	$1.334 \pm 0.006$	0.153	$78.6 \pm 0.8$	$0^{\circ}.3645 \pm 0^{\circ}.0039$
Lainey et al. (2007)	$1.270 \pm 0.015$	0.152	$79.9 \pm 0.7$	$0^{\circ}.3585 \pm 0^{\circ}.0031$
Current	$1.270 \pm 0.003$	0.152	$82.8 \pm 0.2$	$0^{\circ}.3458 \pm 0^{\circ}.0009$

Pretty good agreement since decades!

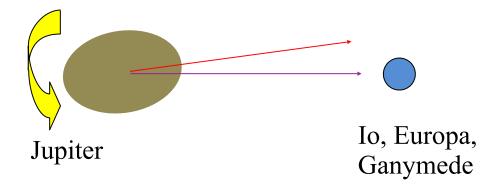
# The Jovian system



## The Jovian system

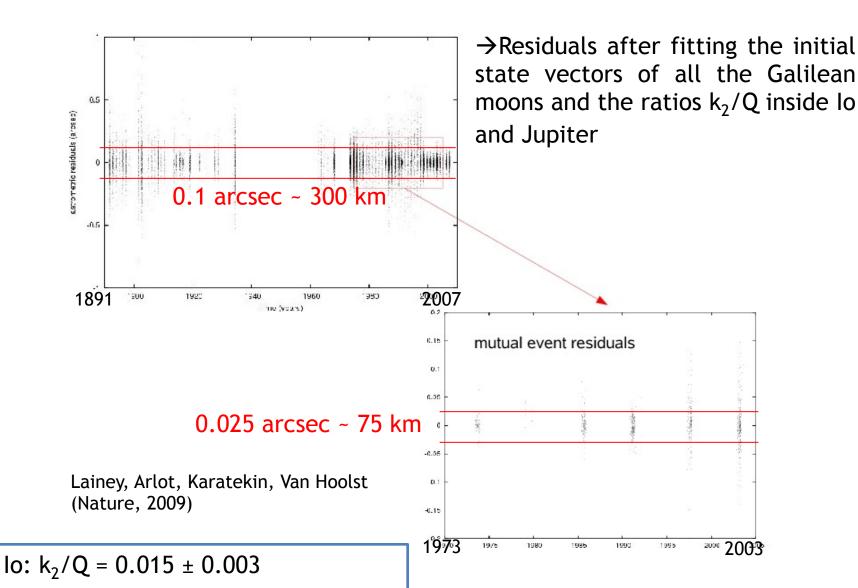


## Astrometry:



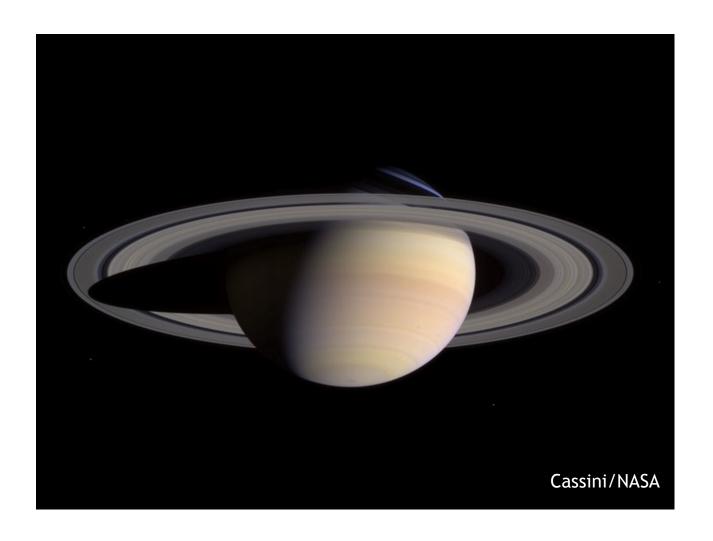
Allows the determination of  $k_2/Q$  in Jupiter and Io

## The Jovian system



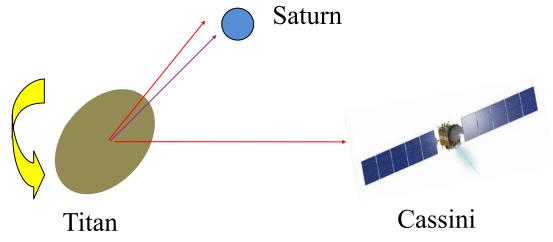
Jupiter:  $k_2/Q = (1.102 \pm 0.203) \times 10^{-5}$ 

# The Saturnian system



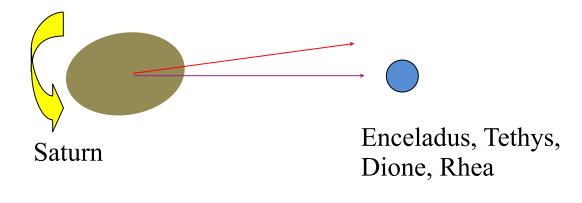
## The Saturn's system

## Space geodesy:



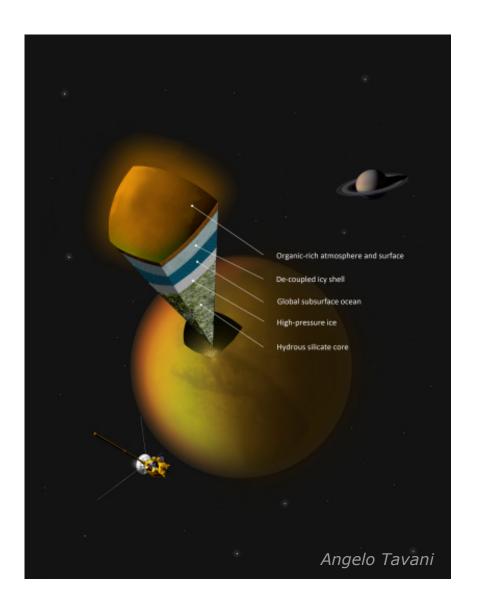
Allows the determination of Titan's k<sub>2</sub>

## Astrometry:



Allows the determination of  $k_2/Q$  in Saturn

## The Saturn's system



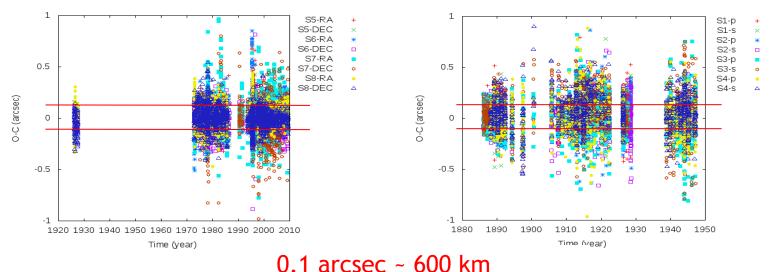
Using six flybys of Titan by Cassini (devoted to radio-science experiment) allowed to quantify Titan's gravity field and Love number k<sub>2</sub>

$$k_2 = 0.589 \pm 0.150$$

less et al. Science 2012

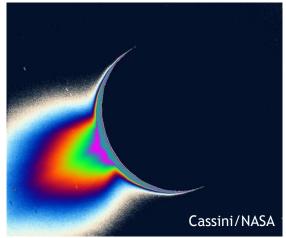
## The Saturn's system

 $\rightarrow$ Residuals after fitting the initial state vectors of all the eight main Saturn moons, the ratio  $k_2/Q$  inside Saturn.



Lainey et al. (2012) finds a much higher value for  $k_2/Q$  in Saturn than expected...

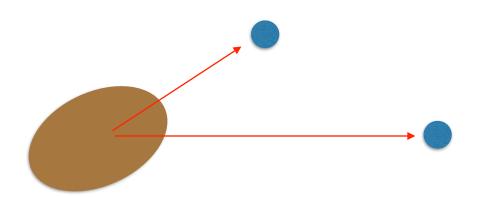
$$k_2/Q = (2.3 \pm 0.7) \times 10^{-4}$$



New results...

## New result...

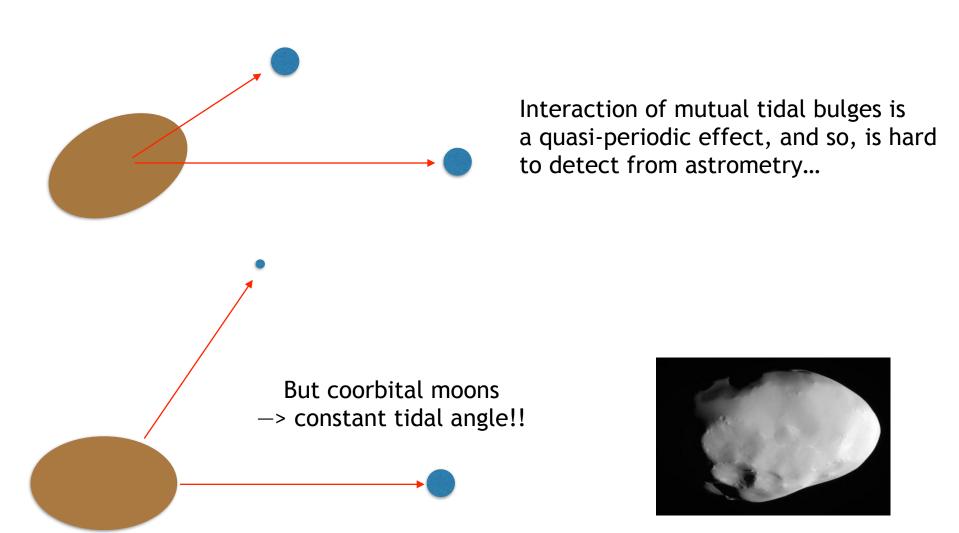
# Separating k<sub>2</sub> and Q!



Interaction of mutual tidal bulges is a quasi-periodic effect, and so, is hard to detect from astrometry...

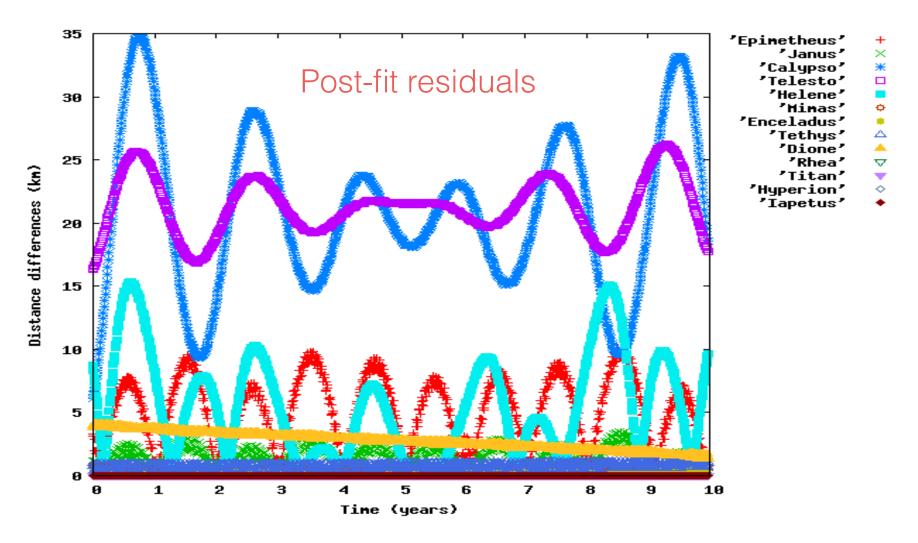
## New result...

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Thanks to coorbital satellites, Saturn's  $k_2$  and Q can be separated!

## **Conclusion:**

- 1- There are not so many objects for which we have measured k2 and Q
- 2- Space geodesy and astrometry are two complementary techniques to characterize the tidal dissipation and Love numbers inside a solar system body
- 3- Cassini imaging data opens the door to a lot of exciting possible new results (direct quantification of tidal dissipation in Enceladus, separation of k<sub>2</sub> and Q in Saturn...)
- 4- Future missions like JUNO and JUICE or projects like Europa clipper, PhoDex and many more will for sure increase our knowledge of tides in solar system bodies