

5 lectures on The Physics of Core-Collapse Supernovae









## Outline of lecture 2

Introduction to supernovae: following our common sense can a collapse bounce into an explosion ? the basics of shock waves

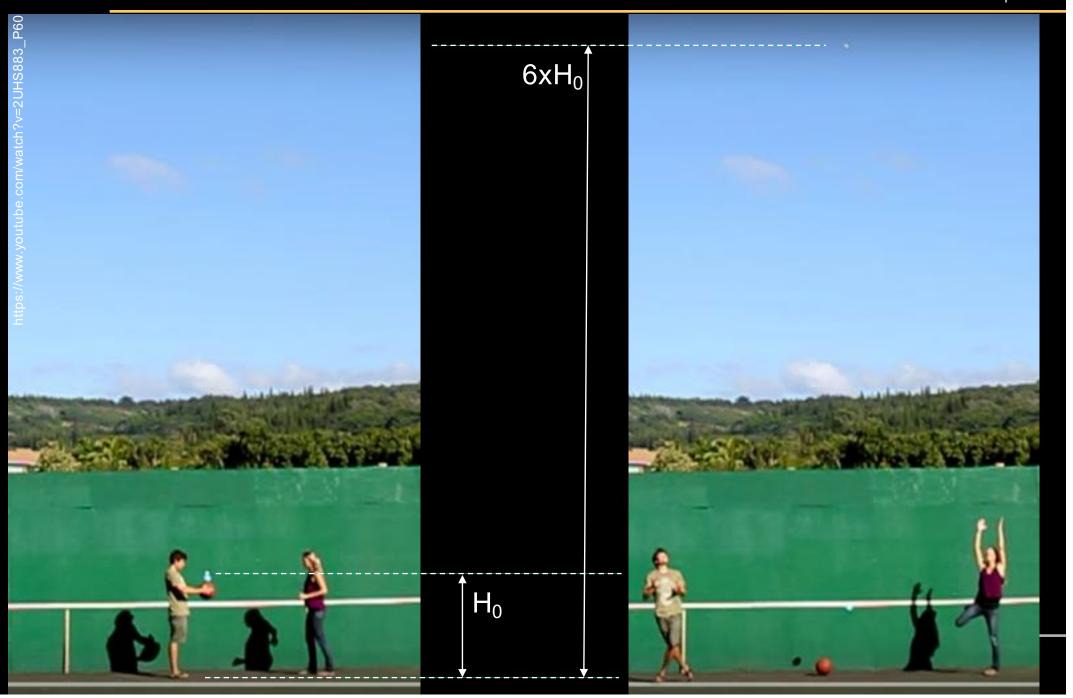
## The framework of delayed neutrino driven explosions

the 5 zones of the model by Betthe & Wilson the spherical explosion of  $10M_{sol}$  the puzzle of more massive progenitors

## Some observational clues and puzzles

the hints for asymmetric explosions constraints from the progenitor, the ejecta and the neutron star

Physics girl/ stacked ball drop



Consider two elastic balls of mass  $m_1 > m_2$ dropped in free fall from a height  $H_0$ reaching a hard surface

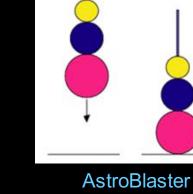
From energy conservation

$$\frac{v^2}{2} + gH = gH_0$$

their velocity just before bounce (H=0) is  $-v_0$  with  $v_0 \equiv (2GH_0)^{\frac{1}{2}}$ 

The velocity of the first ball is symmetric upon an elastic bounce is  $v_1 = +v_0$ The second ball collides the first one with a velocity  $v_2 = -v_0$ 

Momentum conservation Energy conservation  $m_2v_2'+m_1v_1'=(m_1-m_2)v_0$  $m_2v_2'^2+m_1v_1'^2=(m_1+m_2)v_0^2$ 

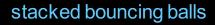


AstroBlaster invented by Stirling Colgate

so  $\frac{w_2'}{v_2'=v_1'+2v_0} = \frac{w_1'}{v_1'-v_0} = \frac{3-\frac{m_2}{m_1}}{1+\frac{m_2}{m_1}} = \frac{w_1'}{v_0} = \frac{1-3\frac{m_2}{m_1}}{1+\frac{m_2}{m_1}} = \frac{H_2'}{H_0} = 9\left(\frac{1-\frac{m_2}{3m_1}}{1+\frac{m_2}{m_1}}\right)^2$ 

Note that

 $-v_1'=0$  if  $m_1=3m_2$ . In this case,  $v_2'=2v_0 \& H_2=4H_0$ -if  $m_1=m_2$ , then  $v_2'=-v_1'=v_0$ : the lower ball "bounces a second time" and follows the first one



#### If the balls are partially elastic

#### $v_a, v_b$ : pre-bounce, $v_a', v_b'$ post-bounce

Momentum conservation $m_a$ anelastic collision $v_b$  $\epsilon$ =1: elastic bounce $\epsilon$ =0: balls are stuck together ( $v_b$ '= $v_a$ ')

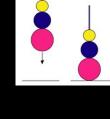
solving this system  $(m_a+m_b)v_a'=(m_a-\epsilon m_b)v_a+(1+\epsilon)m_bv_b$  $(m_a+m_b)v_b'=(1+\epsilon)m_av_a+(m_b-\epsilon m_a)v_b$ 

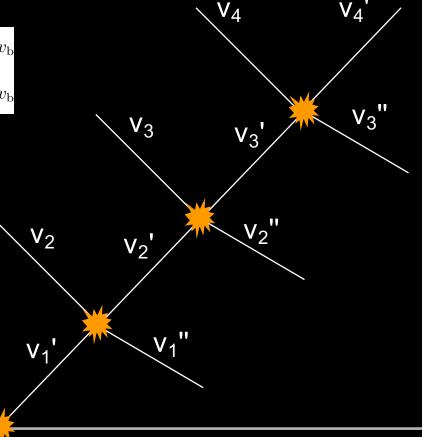
$$v_b' - v_a' = \varepsilon (v_a - v_b)$$

 $v_{\rm a}' = \frac{m_{\rm a} - \epsilon m_{\rm b}}{m_{\rm a} + m_{\rm b}} v_{\rm a} + \frac{(1+\epsilon)m_{\rm b}}{m_{\rm a} + m_{\rm b}} v_{\rm b}$  $v_{\rm b}' = \frac{(1+\epsilon)m_{\rm a}}{m_{\rm a} + m_{\rm b}} v_{\rm a} + \frac{m_{\rm b} - \epsilon m_{\rm a}}{m_{\rm a} + m_{\rm b}} v_{\rm b}$ 

 $V_1$ 

stacked bouncing balls



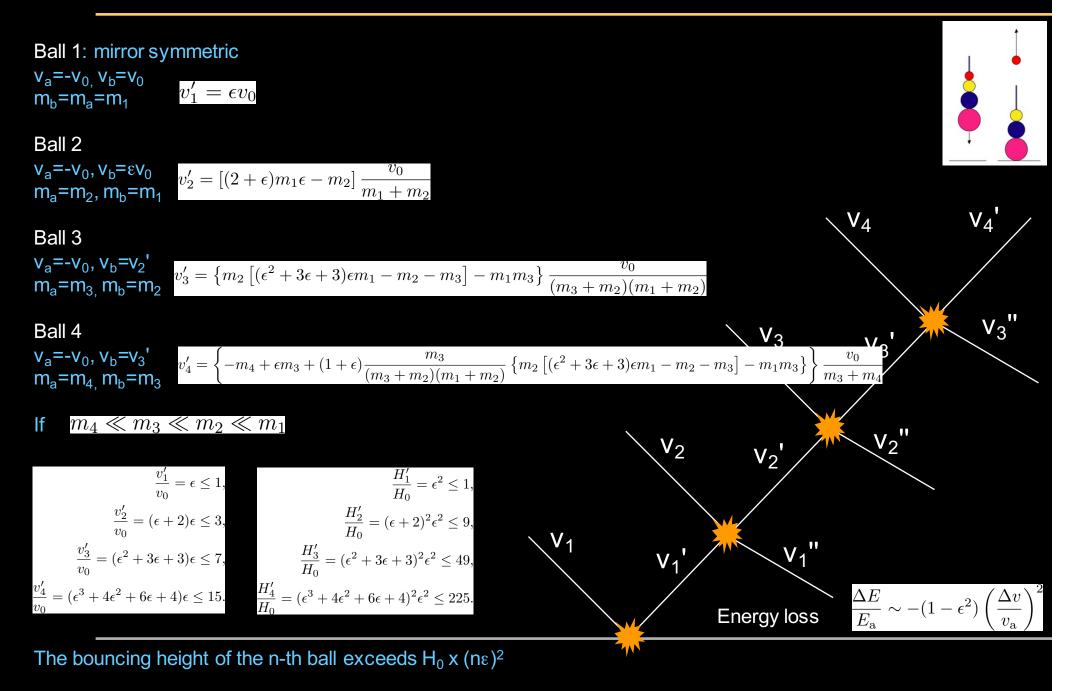


Energy loss

$$\begin{split} & m_{a}v_{a}'^{2}+m_{b}v_{b}'^{2}-(m_{a}v_{a}^{2}+m_{b}v_{b}^{2})=2\Delta E \\ & 2(m_{a}+m_{b})^{2}\Delta E=m_{a}\left((m_{a}-\epsilon m_{b})v_{a}+(1+\epsilon)m_{b}v_{b}\right)^{2} \\ & +m_{b}((1+\epsilon)m_{a}v_{a}+(m_{b}-\epsilon m_{a})v_{b})^{2}-(m_{a}+m_{b})^{2}\left(m_{a}v_{a}^{2}+m_{b}v_{b}^{2}\right) \end{split}$$

$$\Delta E = -\frac{1 - \epsilon^2}{2} \frac{m_{\rm a} m_{\rm b}}{m_{\rm a} + m_{\rm b}} (v_{\rm a} - v_{\rm b})^2$$

stacked bouncing balls



Idealized radial collapse: tranverse motions are difficult to avoid in the experiment

The formalism of point like balls ignores the adiabatic storage of energy into elasticity The time delay of elastic contraction would translate into a delayed bounce

In the collapsing stellar envelope the energy density is written as the Bernoulli parameter, which would be conserved along stationary flow lines if the flow were adiabatic

Among the many differences between stacked balls and the bounce of the stellar core:

-a shock forms

- -energy is lost in the dissociation of iron
- -energy is lost in the escape of neutrinos (Baade & Zwicky 34)
- -a fraction of the neutrino energy is re-absorbed (Cogate & White 66)
- -the emission of neutrino is delayed (Bethe & Wilson 85)
- -instabilities introduce transverse motions (Herand+92, Blondin+06)

$$\frac{v^2}{2} + \frac{E_{\rm K}(H)}{m} + gH = gH_0$$

$v^2$	$c^2$	GM	$_{-}$ $c_{0}^{2}$	GM
2	$\neg \overline{\gamma - 1}$	$-\frac{1}{r}$	$-\frac{1}{\gamma-1}$	$\overline{r_0}$

## Equations of fluid mechanics for a perfect gas

adiabatic sound speed dimensionless entropy

$$c^{2} \equiv \frac{\gamma P}{\rho},$$
  
$$S \equiv \frac{1}{\gamma - 1} \log \left( \frac{P}{\rho^{\gamma}} \frac{\rho_{0}^{\gamma}}{P_{0}} \right).$$

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho v) = 0, \quad \text{mass conservation}$$

$$\frac{\partial v}{\partial t} + (v \cdot \nabla)v + \frac{\nabla P}{\rho} + \nabla \Phi = 0, \quad \text{Euler equation}$$

$$\frac{\partial S}{\partial t} + v \cdot \nabla S = \mathcal{L}. \quad \text{entropy equation}$$

using

$$v \cdot \nabla)v = (\nabla \times v) \times v + \nabla \left(\frac{v^2}{2}\right)$$
$$\frac{\nabla P}{\rho} = \nabla \left(\frac{c^2}{\gamma - 1}\right) - \frac{c^2}{\gamma} \nabla S.$$

The Euler equation can be rewritten as follows:

$$\frac{\partial v}{\partial t} + (\nabla \times v) \times v + \nabla \left( \frac{v^2}{2} + \frac{c^2}{\gamma - 1} + \Phi \right) = \frac{c^2}{\gamma} \nabla S$$
  
Bernoulli "constant"

Idealized stationary spherical collapse of an adiabatic ideal gas: Bondi accretion (1952)

$$\frac{v^2}{2} + \frac{c^2}{\gamma - 1} - \frac{GM}{r} = B,$$
  

$$\rho v r^2 = \frac{\dot{M}}{4\pi}$$

$$S \equiv \log\left[\left(\frac{c}{c_0}\right)^{\frac{2}{\gamma - 1}} \frac{\rho_0}{\rho}\right]$$

The system of equations satisfied by v, c is  $\frac{v^2}{v}$ 

$v^2$	$c^2$	GM	$\gamma + 1$ $c^2$	GM
$\overline{2}$	$\overline{\gamma-1}$	r	$\frac{1}{2(\gamma-1)}c_{\rm son}$	$r_{\rm son}$
	$c^{\overline{\gamma}}$	$\frac{2}{v-1}vr^2 =$	$=-c_{\mathrm{son}}^{rac{\gamma+1}{\gamma-1}}r_{\mathrm{son}}^{2}$	

Differentiating this system with respect to r gives the regularity conditions at the sonic point

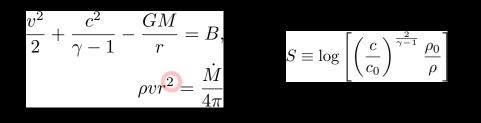
$v^2 - +$	$2c^{2}$	$\frac{\dot{c}}{\dot{c}} =$	$-\frac{GM}{r^2}$		$(c^{2} -$	$(-v^2)\frac{\dot{v}}{v} =$	$= \frac{GM}{2}$	$-\frac{2c^2}{-}$
$\dot{v}$	2	$\dot{c}$	2	2	$(2^2)$	$(-v^2)\frac{\dot{c}}{c} =$	$2v^2$	GM
$\frac{-}{v}$ +	$\overline{\gamma-1}$	$\overline{1} c^{-}$	$-\frac{1}{r}$	$\gamma - 1$	$\frac{1}{1}^{(c)}$	$(-v)^{-}_{c} = c$	$=$ $\frac{r}{r}$ -	$r^2$

$$c_{\rm son}^2 = \frac{GM}{2r_{\rm son}}$$

The Bernoulli constant relates the sound speeds at the sonic point and at "infinity", and defines the sonic radius:

$$c_{\rm son} = \left(\frac{2}{5-3\gamma}\right)^{\frac{1}{2}} c_{\infty}$$
$$r_{\rm son} = \frac{5-3\gamma}{4} \frac{GM}{c_{\infty}^2}$$

Idealized stationary spherical collapse of an adiabatic ideal gas: Bondi accretion (1952)

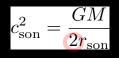


The system of equations satisfied by v, c is

$v^2$	$c^2$	GM	$\gamma + 1$ $c^2$	GM
$\overline{2}^{+}$	$\gamma - 1$	r	$\frac{1}{2(\gamma-1)}c_{\rm son}$	$r_{\rm son}$
	$c^{-1}$	$\frac{2}{v^{-1}}vr^2 =$	$= -c_{\mathrm{son}}^{\frac{\gamma+1}{\gamma-1}} r_{\mathrm{son}}^2$	

Differentiating this system with respect to r gives the regularity conditions at the sonic point

$v^{2}\frac{\dot{v}}{v} + \frac{2c^{2}}{\gamma - 1}\frac{\dot{c}}{c} = -\frac{GM}{r^{2}} \qquad (c^{2} - v^{2})\frac{\dot{v}}{v} = \frac{GM}{r^{2}} - \frac{2c^{2}}{r}$ $\frac{\dot{v}}{v} + \frac{2}{\gamma - 1}\frac{\dot{c}}{c} = -\frac{2}{r} \qquad \frac{2}{\gamma - 1}(c^{2} - v^{2})\frac{\dot{c}}{c} = \frac{2v^{2}}{r} - \frac{GM}{r^{2}}$					
$v^{-}\frac{v}{v} + \frac{\gamma - 1}{r}\frac{\dot{c}}{c} = -\frac{\gamma}{r^{2}} \qquad (c^{2} - v^{2})\frac{\dot{v}}{v} = \frac{\gamma}{r^{2}} - \frac{\gamma}{r}$ $\frac{\dot{v}}{v} + \frac{2}{v^{2}}\frac{\dot{c}}{c} = -\frac{2}{r} \qquad \frac{2}{v^{2}}\frac{(c^{2} - v^{2})\frac{\dot{c}}{c}}{v^{2}} = \frac{2v^{2}}{r} - \frac{GM}{r^{2}}$	$_{2}\dot{v}$ $_{2}c^{2}\dot{c}$	GM	$(2, 2)\dot{v}$	GM	$2c^2$
$\frac{\dot{v}}{v} + \frac{2}{v-1}\frac{\dot{c}}{c} = -\frac{2}{v}$ $\frac{2}{v-1}(c^2 - v^2)\frac{\dot{c}}{c} = \frac{2v^2}{v^2} - \frac{GM}{v^2}$	$v^{-} \frac{1}{v} + \frac{1}{\gamma - 1} \frac{1}{c} = -$	$r^2$	$(c^2 - v^2) - v = v$	$= \frac{1}{r^2}$	$-\frac{r}{r}$
$- + \frac{1}{2} = - $	$\dot{v}$ $\dot{2}$ $\dot{c}$	2 2	$\dot{c}$	$2v^2$	GM
$v  \gamma = 1 c  r  \gamma = 1  c  r  r^{-1}$	$\frac{1}{v} + \frac{1}{\gamma - 1} = -$	$\overline{r}$ $\overline{\gamma}$ –	$\frac{1}{1}(c^2 - v^2) - c =$	$=$ $\frac{r}{r}$ -	$-\frac{1}{r^2}$



The Bernoulli constant relates the sound speeds at the sonic point and at "infinity", and defines the sonic radius:

$$c_{\rm son} = \left(\frac{2}{5-3\gamma}\right)^{\frac{1}{2}} c_{\infty}$$
$$r_{\rm son} = \frac{5-3\gamma}{4} \frac{GM}{c_{\infty}^2}$$

Idealized stationary cylindrical collapse of an adiabatic ideal gas

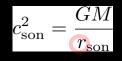
$$\frac{v^2}{2} + \frac{c^2}{\gamma - 1} - \frac{GM}{r} = B,$$
  
$$\rho v r = \frac{\dot{M}}{4\pi}$$
$$S \equiv \log\left[\left(\frac{c}{c_0}\right)^{\frac{2}{\gamma - 1}} \frac{\rho_0}{\rho}\right]$$

The system of equations satisfied by v, c is

$\frac{v^2}{-} +$	$c^2$	$-\frac{GM}{=}$	$=\frac{\gamma+1}{c_{acn}^2}c_{acn}^2$	- GM
2	$\gamma - 1$	r	$\frac{1}{2(\gamma-1)}c_{\rm son}$	$r_{\rm son}$
		$c^{\frac{2}{\gamma-1}}vr=$	$= -c_{\mathrm{son}}^{\frac{\gamma+1}{\gamma-1}}r_{\mathrm{son}}^{\gamma-1}$	

Differentiating this system with respect to r gives the regularity conditions at the sonic point

$v^2 \frac{\dot{v}}{v} +$	$\frac{2c^2}{\gamma - 1}\frac{\dot{c}}{c} =$	$=-\frac{GM}{r^2}$	$(c^2 - v^2)\frac{\dot{v}}{v} = \frac{GM}{r^2}$	$-\frac{c^2}{r}$
$\frac{\dot{v}}{-+}$	$\frac{\dot{2}}{\dot{c}}$		$\frac{2}{\gamma - 1}(c^2 - v^2)\frac{\dot{c}}{c} = \frac{v^2}{r} - $	$\frac{GM}{2}$
v '	$\gamma - 1 c$	r	$\gamma - 1$ $c$ $r$	$r^2$



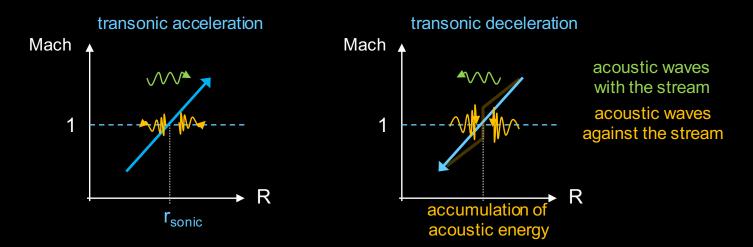
The Bernoulli constant relates the sound speeds at the sonic point and at "infinity", and defines the sonic radius:

$$c_{\rm son} = \left(\frac{2}{3-\gamma}\right)^{\frac{1}{2}} c_{\infty}$$
$$r_{\rm son} = \frac{3-\gamma}{2} \frac{GM}{c_{\infty}^2}$$

As the free falling collapsing iron gas approaches the center, the flow has to decelerate from supersonic to subsonic velocities.

A flow can accelerate continuously from subsonic to supersonic: the nozzle of a rocket, Bondi accretion onto a black hole or stellar winds are examples of transonic acceleration.

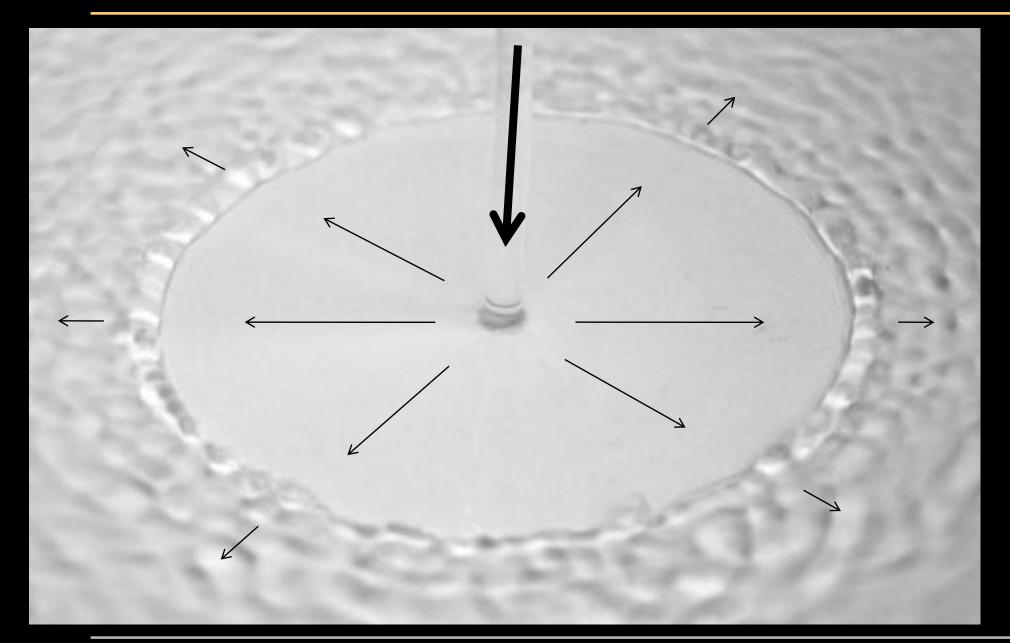
By contrast, the reverse solution  $(v \rightarrow -v)$  of a transonic deceleration cannot exist without forming a shock because of the accumulation of acoustic energy at the sonic point



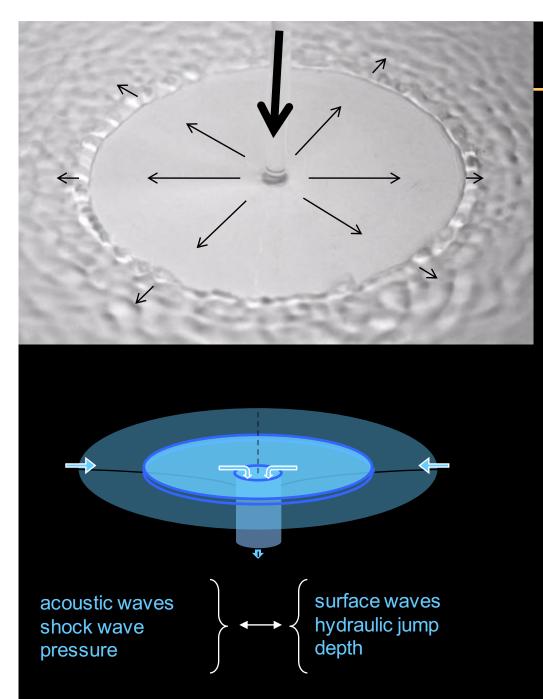
A shock is an abrupt conversion of kinetic energy into enthalpy. In a gas, the large scale kinetic energy is converted into small scale kinetic energy (heat)

Hydraulic jumps in shallow water are analogous to shocks. The large scale kinetic energy is converted into potential energy

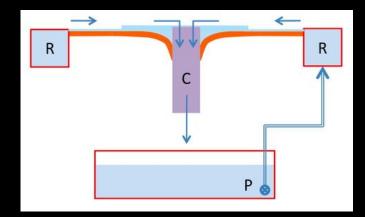
## Hydraulic jumps and shock waves



Like the deceleration shock of stellar winds, the circular hydraulic jump marks the transition between a fast and shallow inner flow and a slower deeper outer flow



## Analogy between hydraulic jumps and shock





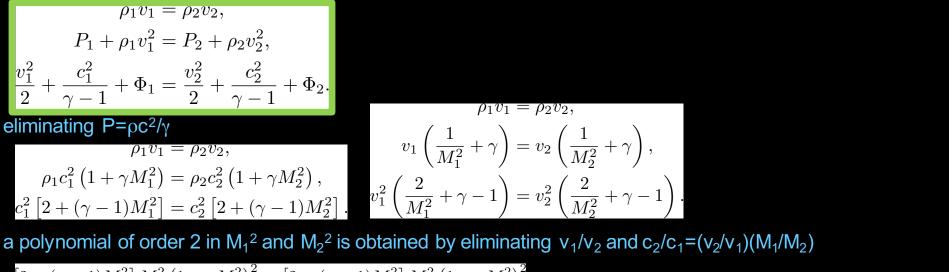
## Derivation of the Rankine Hugoniot jump conditions

The jump conditions across a shock are deduced from the conservation of

-the mass flux:  $\rho$  v -the momentum flux: P +  $\rho$  v^2

-the energy density flux:  $\rho$  v B

The jump conditions depend on the strength of the shock, measured by the incident Mach number  $M_1 = v_1/c_1$ 



 $\left[2 + (\gamma - 1)M_1^2\right]M_1^2 \left(1 + \gamma M_2^2\right)^2 = \left[2 + (\gamma - 1)M_2^2\right]M_2^2 \left(1 + \gamma M_1^2\right)^2$ 

the trivial solution  $M_1^2 = M_2^2$  can be factorized  $(M_2^2 - M_1^2) \left[ -M_2^2 (2\gamma M_1^2 - \gamma + 1) + 2 + (\gamma - 1) M_1^2 \right] = 0$ 

2 important equations

$$M_2^2 = \frac{2 + (\gamma - 1)M_1^2}{2\gamma M_1^2 - \gamma + 1}$$

$$\frac{v_2}{v_1} = \frac{2 + (\gamma - 1)M_1^2}{(\gamma + 1)M_1^2}$$

the other jump conditions are easily deduced:  $S_2$  -

$$\frac{\rho_2}{\rho_1} = \left(\frac{v_2}{v_1}\right)^{-1},$$

$$\frac{c_2^2}{c_1^2} = \left(\frac{v_2}{v_1}\right)^2 \frac{M_1^2}{M_2^2} = \frac{(2 + (\gamma - 1)M_1^2)(2\gamma M_1^2 - \gamma + 1)}{(\gamma + 1)^2 M_1^2},$$

$$-S_1 = \frac{1}{\gamma - 1} \left[ \log\left(\frac{M_1^2}{M_2^2}\right) + (\gamma + 1)\log\left(\frac{v_2}{v_1}\right) \right].$$

-Entropy is produced across a shock: non reversible process

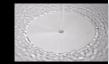
$$S_2 - S_1 \equiv \frac{1}{\gamma - 1} \log \left[ \frac{P_2}{P_1} \left( \frac{\rho_1}{\rho_2} \right)^{\gamma} \right] \sim \frac{2}{\gamma - 1} \log M_1$$

temporal variations of shock strength produce entropy gradients, which are a source of convective instability

-the compression ratio  $\rho_2/\rho_1$  reaches ( $\gamma$ +1)/( $\gamma$ -1) for a strong shock

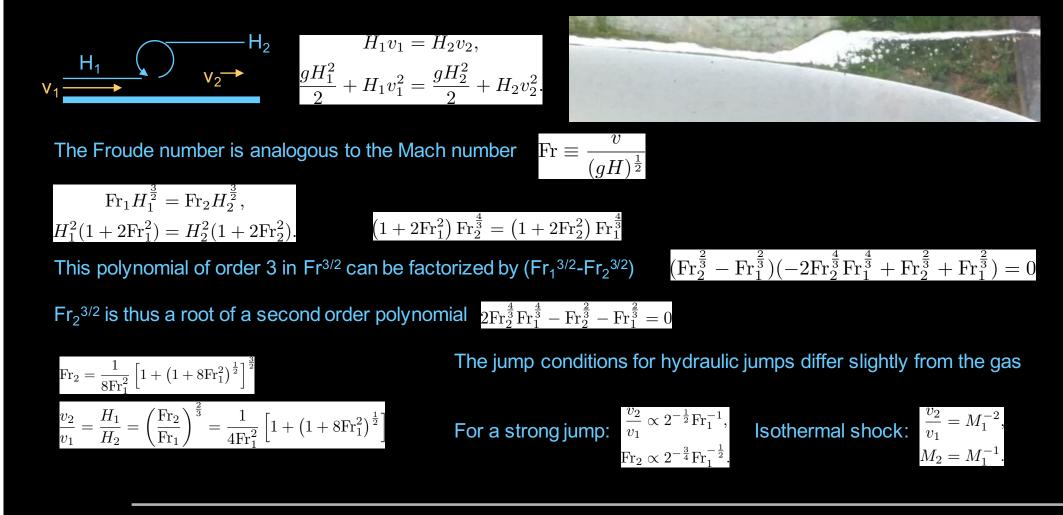
A isothermal gas is characterized by only 2 physical quantities: e.g. velocity and density

A isothermal shock cannot conserve the energy flux: energy is implicitely radiated away



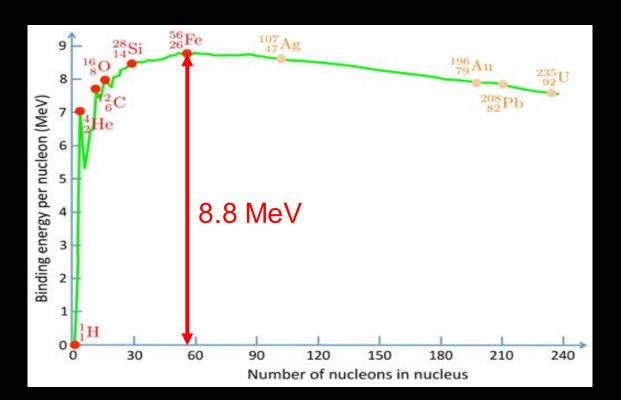
The shallow water flow is also described by 2 physical quantities: velocity and depth (no entropy analogue). Depth plays the same role as the compressibility of a gas (i.e. surface density).

The jump conditions for a hydraulic jump are deduced from the conservation of mass flux and momentum flux. Energy is dissipated in a viscous roller within the width of the hydraulic jump.



#### The binding energy of iron is 8.8 MeV/nucleon

The kinetic energy of free fall in the gravitational potential of the proto-neutron star is sufficient to dissociate the iron nuclei into alpha particles, protons and neutrons if the shock radius is smaller than 220km:



$$\frac{\frac{1}{2}m_{\rm p}v_{\rm ff}^2}{8.8\text{MeV}} \sim \frac{220\text{km}}{r} \left(\frac{M_{\rm ns}}{1.4M_{\rm sol}}\right)$$

-For a shock radius ~150km, the full dissociation of <sup>56</sup>Fe would absorb 150/220=68% of the gravitational energy

-The nucleons which are not accreted onto the neutron star may return a fraction of this energy upon expansion, if the shock is launched The composition of the infalling gas changes:

-across the shock, heavy nuclei are dissociated into nucleons

 ${}^{56}{
m Fe} + 56 \times 8.8{
m MeV} \rightarrow 26p + 30n + 26e$ 

-in the gain region, neutrons and protons intercept some neutrinos

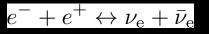
 $n + \nu_{\rm e} \to p^+ + e^ p^+ + \bar{\nu}_{\rm e} \to n + e^+$ 

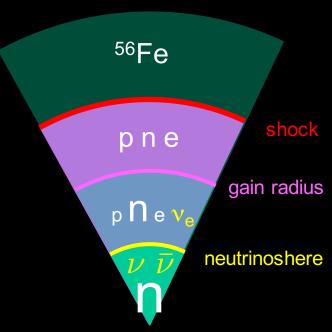
-below the gain radius, protons & electrons turn into to neutrons & neutrinos near the proto-neutron star,

$$p^+ + e^- \to n + \nu_{\rm e}$$

lectrons turn into oto-neutron star,  $n + \nu_{e}$ 

- inside the neutrinosphere, a thermal bath of neutrons, neutrinos and anti-neutrinos





## neutrino interactions

Dominant heating and cooling reactions

Heating by neutrino absorption:

 $n + \nu_{\rm e} \rightarrow p + e^{-}$ 

## Neutrino Reactions in Supernovae

	• $e^- + p \rightleftharpoons n + v_e$	$p + \bar{\nu}_{\rm e} \rightarrow n + e^+$
Beta processes:	• $e^+ + n \rightleftharpoons p + \bar{v}_e$	$Q_{heat} \sim L_{v}/R^{2}$
	• $e^- + A \rightleftharpoons v_e + A^*$	Cooling by electron capture:
	• $v + n, p \rightleftharpoons v + n, p$	$p + e \rightarrow n + \nu_e$
Neutrino scattering:		$Q_{cool}$ ~T <sup>6</sup> ~1/R <sup>6</sup>
	• $v + e^{\pm} \rightleftharpoons v + e^{\pm}$	-cooling is dominant near the NS surface
Thermal pair	• $N + N \rightleftharpoons N + N + \nu + \bar{\nu}$	-cooling decreases radially faster than heating
processes:	• $e^+ + e^- \rightleftharpoons v + \bar{v}$	
Neutrino-neutrino reactions:	• $v_x + v_e, \bar{v}_e \rightleftharpoons v_x + v_e, \bar{v}_e$ $(v_x = v_\mu, \bar{v}_\mu, v_\tau, \text{ or } \bar{v}_\tau)$	the gain radius R <sub>gain</sub> (Bethe & Wilson 85) is defined by the balance between cooling and heating
	• $v_e + \bar{v}_e \rightleftharpoons v_{\mu,\tau} + \bar{v}_{\mu,\tau}$	$R_{gain} \sim (L_v)^{1/4}$

Neutrino interactions with nuclei are sensitive to the accuracy of their description in the equation of state

150

100

 $15M_{sol}$ Marek & Janka 09

HW-1D

LS-1D

shock

rate

300

time [ms]

400

200

100

2.0

1.5

1.0

0.5

0.0

600

500

accretion rate@shock| [M<sub>©</sub>/s]

The size of the neutrinosphere depends on the nuclear equation of state. It shrinks as neutrino energy diffuses out.

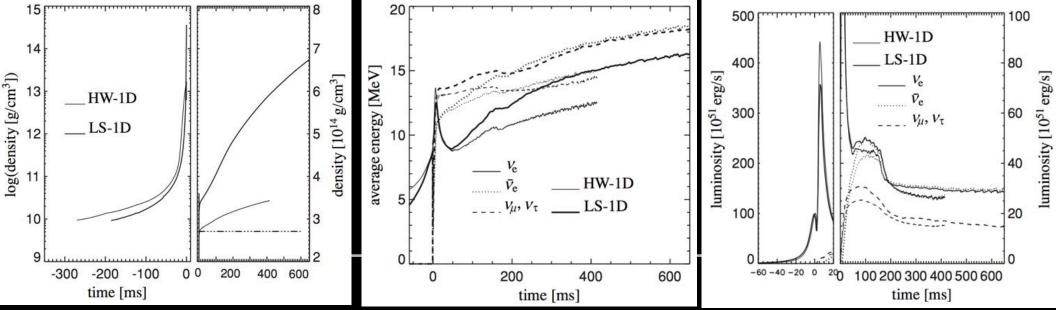
The neutrino energy and luminosity are larger if the neutrinosphere is deeper in the gravitational potential.

-The gravitational accretion power of the collapse decreases dramatically as the oxygen rich layer reaches the neutrinosphere, (from  $2M_{sol}/s$  to  $0.3M_{sol}/s$ ):

> $\frac{G\dot{M}M}{R} = 6.5 \times 10^{52} \left(\frac{M}{1.4M_{\rm sol}}\right)$  $\left(\frac{\dot{M}}{0.35M_{\rm sol}{\rm s}^{-1}}\right)$  $\overline{20 \mathrm{km}}$

-The total neutrino luminosity decreases from 15x10<sup>52</sup> erg/s to 8x10<sup>52</sup> erg/s in the first 200ms after bounce, exceeding the incoming gravitational accretion power of the collapse for t>200ms

# radius [km] 50 erg s 0



The time (t) dependent transport of neutrinos in each of point of the 3D space (x,y,z) requires an integration of all incoming particles from every direction ( $\theta$ , $\phi$ ), for every neutrino species for any energy (E): this calculation in 6+1 dimensions is beyond the power of existing supercomputers

-adiabatic simulations neglect neutrino heating and evacuate matter at the inner boundary (Blondin & Mezzacappa 07, Foglizzo+12, Endeve+12)

-light bulb+heating/cooling functions (everyone)

-leakage scheme (Ott, O'Connor, Couch) estimate an optical depth to mimick neutrino losses

-multi group flux limited diffusion=MGFLD energy E, flux F (Burrows)

-Isotropic Diffusion Source Approximation=IDSA: 2 v-distributions, diffusive and free streaming, 2D (Liebendörfer+09, Takiwaki, Suwa)

-M1 closure: radiative energie E, radiative flux F, radiation pressure P, closure P=D E the Eddington tensor D(F/cE) defines an interpolation between the diffusion and the transport limits (Audit+02, Obergaulinger & Janka, Kuroda, Kotake & Takiwaki, Skinner & Burrows)

-ray by ray plus (Janka, Müller, Mezzacappa): Boltzmann transport along rays

-full Boltzmann 6+1 (Sumiyoshi+15): only on short timescales so far

Numericl simulations of core-collapse supernovae almost always use a restricted set of EOS: Lattimer & Swesty 91, and H. Shen+98 with one degree of freedom, their compressibility or "softness"

Softer EOS lead to easier explosions: more compressible =deeper gravitational potential.

Some recent updates G. Shen+11, Hempel+11

Updated modern EOS are freely available through the internet, e.g. the Compstar database Compose (Typel+15) compose.obspm.fr

Improved EOS include:

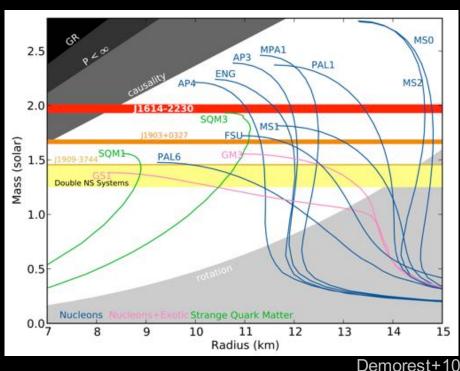
-intermediate nuclei: a single heavy nucleus or an explicit distribution -light nuclei in addition to p, n, alpha: deuteron, triton...

-exotic particles such as pions, hyperons (Oertel+12) or even a quark phase (Sagert+09, Fisher+11)

Softness is limited by the observed mass of neutron stars. The parameter space shrinked in 2010 (Demorest+10) with M<sub>NS</sub>~2 M<sub>sol</sub> Gravitational waves from coalescing NS may further constrain the EOS (Bauswein+14)

 PSR J1614-2230
 M=1.97+-0.04M<sub>sol</sub> (Demorest+10) updated to  $M=1.928+-0.017M_{sol}$  (Fonseca+16)

 PSR J0348+0432
 M=2.01+-0.04 M<sub>sol</sub> (Antoniadis+12)



#### Progress in supernova theory is limited by the progress in stellar structure and stellar evolution

Most of the progenitors are computed by very few groups:

Woosley & Weaver (1995), Woosley, Heger & Weaver (2002), Woosley & Heger (2007)

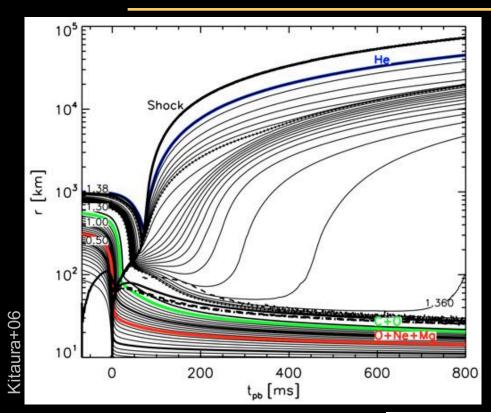
The mass on the main sequence is a very indirect and non monotonous tag for the structure of the progenitor (mass loss and unstable burning history). The impact of the diversity of radial structures on the explosion mechanism has been discovered only recently (O'Connor & Ott 11, Ugliano+12, Sukhbold & Woosley 14)

The stellar structure of the progenitor is spherical, resulting from stellar evolution with 1D presciptions for transport processes (e.g. Mixing Length Theory) with uncertain distribution of angular momentum and magnetic fieds.

The turbulent convective structure of the oxygen, silicon layers was ignored until recently (Arnett & Meakin 11, Arnett+15, Couch & Ott 13, 15, Müller+16)

The impact of binary interactions is most often ignored (Podsiadlowski+04, Sana+12)

## The spherical <u>delayed</u> explosion of a 8.8M<sub>sol</sub> progenitor



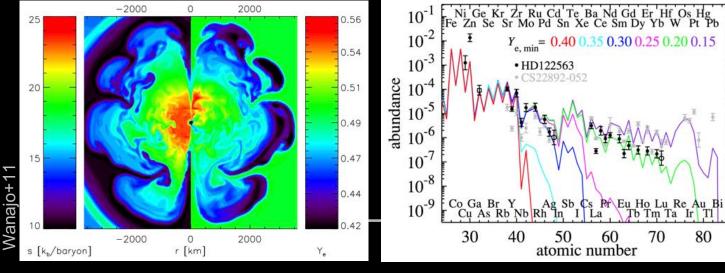
O-Ne-Mg core  $\tau_{expl}$ ~200ms after bounce

 $\begin{array}{l} M(^{56}\text{Ni}) < 0.015 M_{sol} \\ \text{E} \sim 0.1 \times 10^{51} \text{ erg depending on the EOS} \\ M_{\text{NS}} \sim 1.36 M_{sol} \end{array}$ 

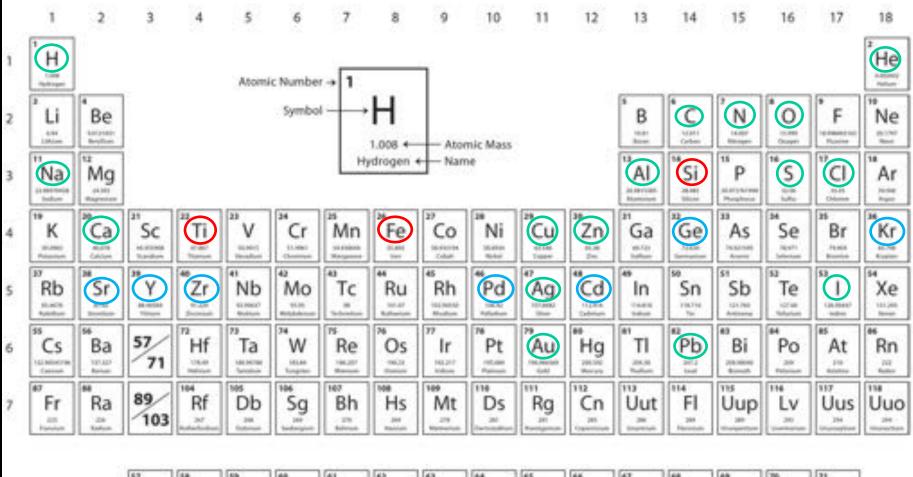
possible model for subluminous SN including the Crab supernova E~0.6-1.5x10<sup>50</sup> erg,  $M_{ej}$ =4.6+-1.8 $M_{sol}$ 

Nucleosynthesis of <sup>64</sup>Zn: <30% of core collapse originate from electron capture SN (Wanajo+09)

2D update (Wanajo+11): neutron rich convective lumps are favourable to the r-process up to Zr, possibly up to Ag Ratio  ${}^{86}$ Kr/ ${}^{16}$ O $\rightarrow$ ECSN are 4% of CCSN

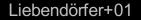


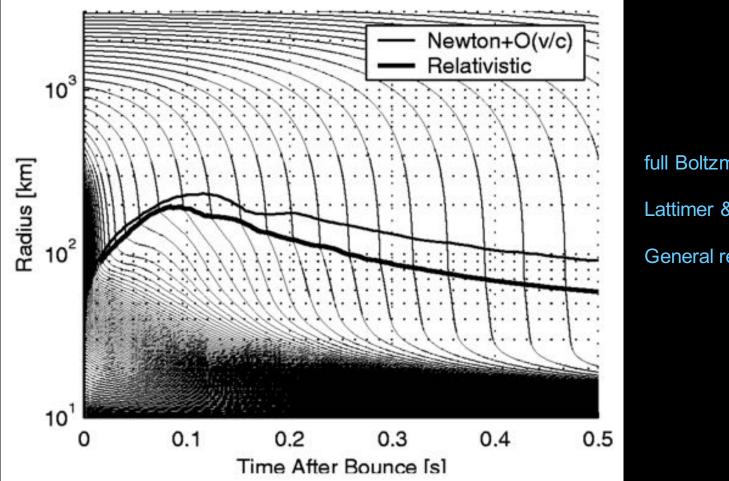
## Classification of the elements

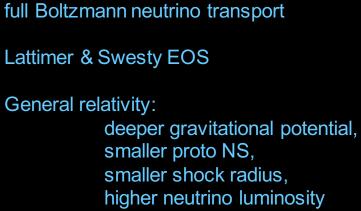


Lanthanide Series	La	Ce	Pr	Nd Internet	Pm	Sm	Eu Eu Inter	Gd	Tb Tb	Dy	Ho	Er	Tm	Yb	Lu
Actinide Series	"Ac	Th	Pa		Np	Pu	*S Am	Cm	Bk	Cf	Es 	Fm	Md	No	Lr

## The failure of spherical explosions for M=13M<sub>sol</sub>







## Outline of lecture 2

Introduction to supernovae: following our common sense can a collapse bounce into an explosion ? the basics of shock waves

The framework of delayed neutrino driven explosions the 5 zones of the model by Betthe & Wilson the spherical explosion of 10M<sub>sol</sub> the puzzle of more massive progenitors

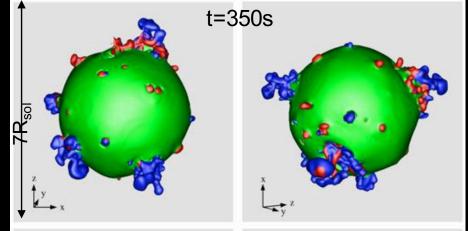
## Some observational clues and puzzles

the hints for asymmetric explosions constraints from the progenitor, the ejecta and the neutron star

### Hints of aspherical explosion of 1987A

H/He mixing and Ni clumps are required to explain the light curve of 1987A, and the early emergence of X and  $\gamma$  rays (Woosley 88, Utrobin 04)

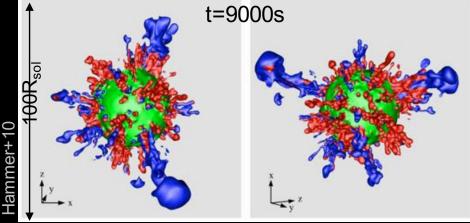
blue: 7% nickel green: 3% carbon red: 3% oxygen



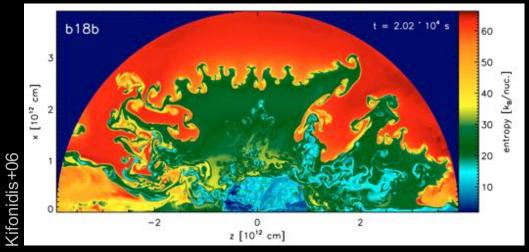
t=0.5s

4000km

Scheck



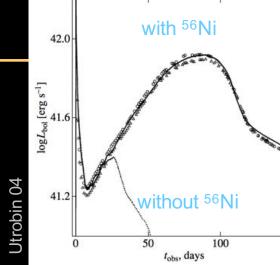
blue: nickel green: He core red: H rich



2D simulation with large intial asymmetry (Kifonidis+06) → efficient H/He mixing by the RMi

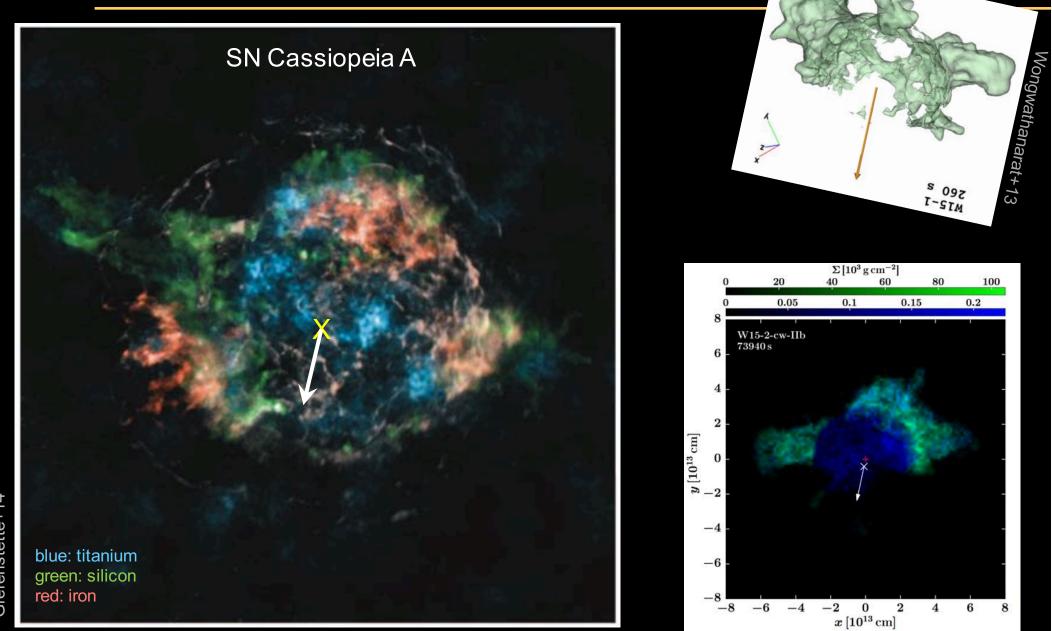
3D simulation with smaller initial asymmetry (Hammer+10) → high velocity nickel clumps 4500km/s → more efficient RT mixing than in 2D

However no satisfactory pre-supernova model yet (Utrobin+15)



150

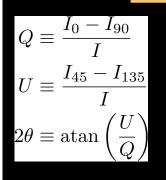
## Inhomogeneous nucleosynthesis



Wongwathanarat+16

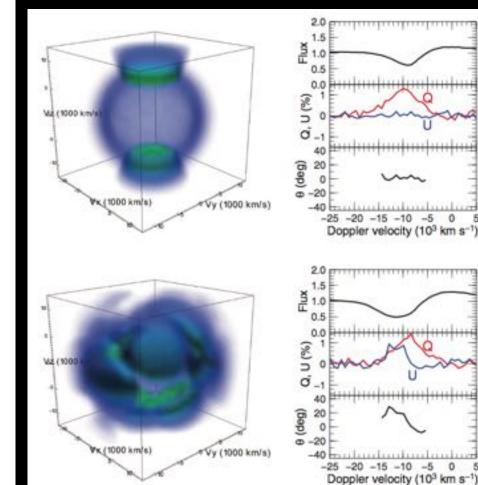
## 3D structure of stripped supernovae from spectropolarimetry

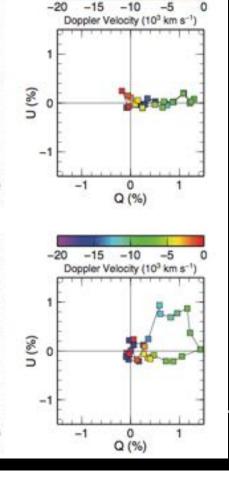
Tanaka+12

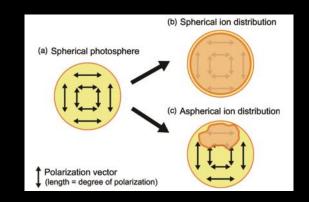


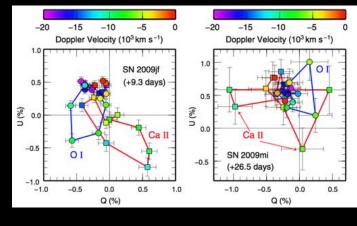
An axisymmetric structure transates into a 1D distribution of the Stokes parameter Q,U

A non axisymmetric structure produces a loop in the Q,U diagram









Type lb

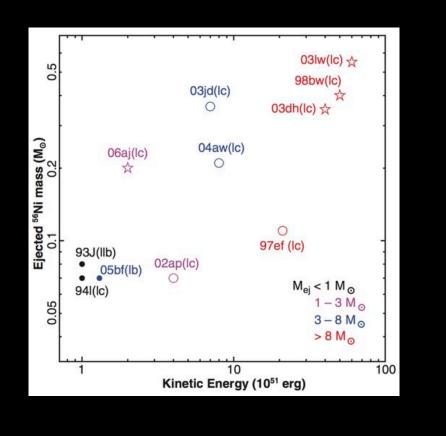
Type Ic

5 out of 6 stripped enveloppe SN have a 3D non axisymmetric structure

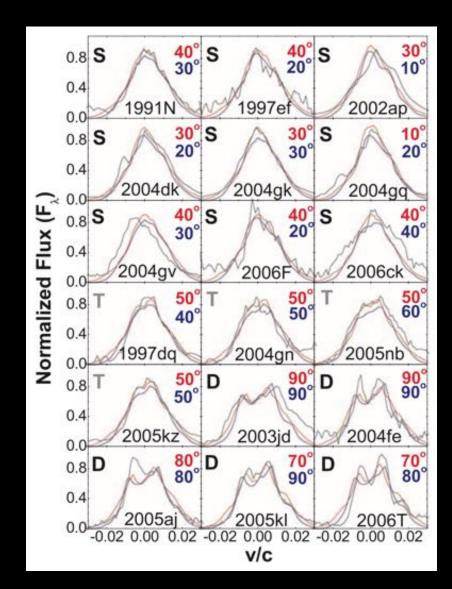
 $\rightarrow$ A 2D theory of stellar explosions may be insufficient

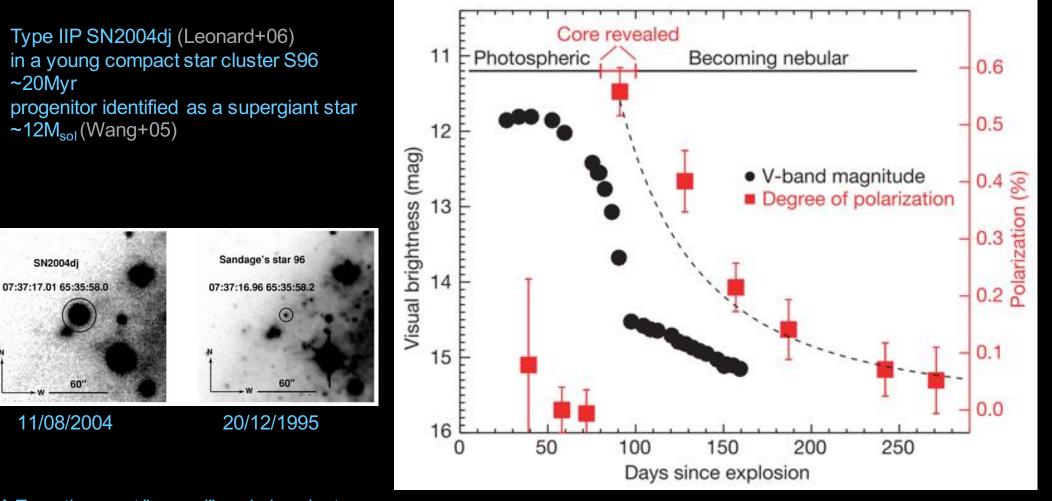
## Aspherical explosions: continuity among stripped SN from spherical to strongly bipolar

Maeda+08



Oxygen doublet 6300, 6363 S: single peaked T: transition D: double peaked red: bipolar model blue: less aspherical model





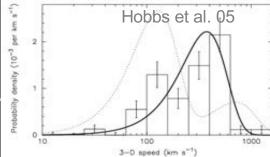
→Even the most "normal" and abundant supernovae have an asymmetric structure

## The high velocities of neutron stars

## suggest an asymmetric supernova explosion



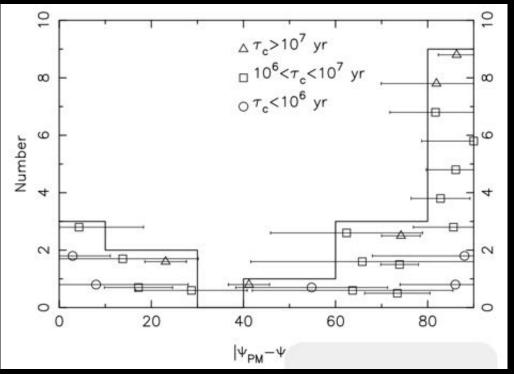
pulsar in the guitar nebula: >1000km/s

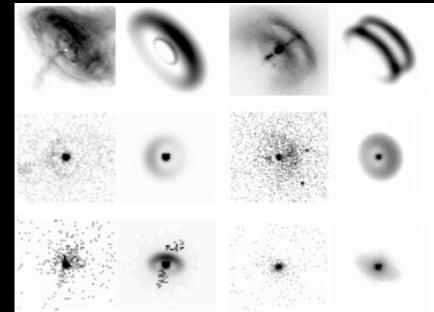


## Is there a kick spin correlation?

The spin axis is deduced from 2 methods polarization from 24 pulsars (Wang+06), 56 pulsars (Noutsos+12) +-90° uncertainty from polarization measures: no correlation rejected with 99% confidence

axis of pulsar wind nebulae from 6 pulsars (Ng & Romani 04, Wang+06), A contribution from binary orbital kicks is expected The initial kick direction is affected by the galactic potential (Noutsos+13)

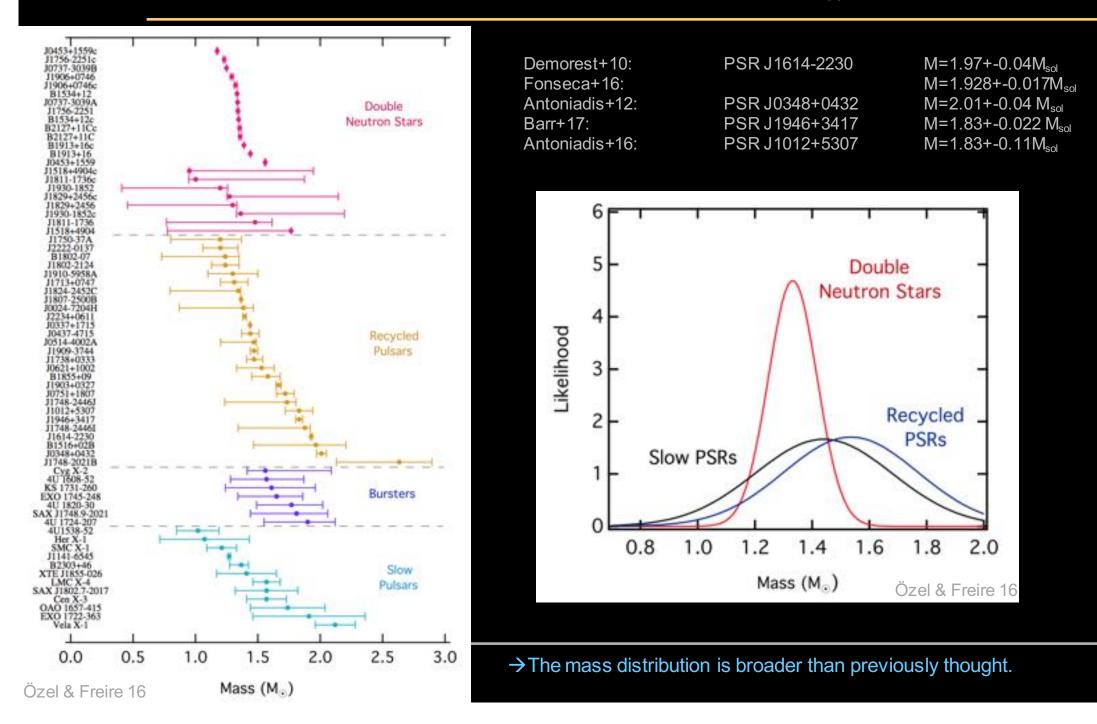




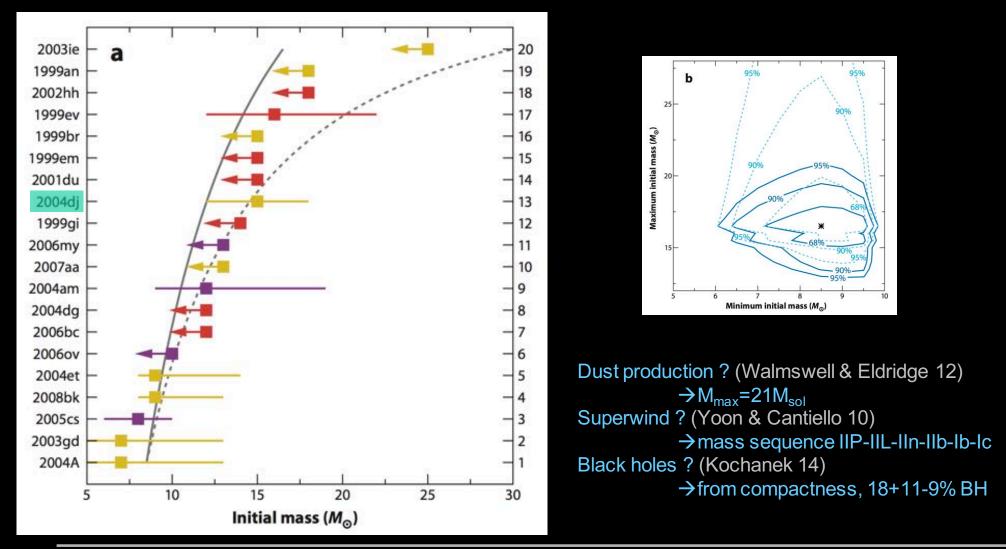
Ng & Romani 04

PSR	$\Psi_{\rm rot}$ (deg)	$\Psi_{\rm PM}$ (deg)	$ \Delta \Psi_{\Omega v} $ (deg)	
B0531+21(Crab)	$124.0\pm0.1$	292 ± 10	$12 \pm 10$	
J0538+2817	$155 \pm 8$	$328 \pm 4$	$7\pm9$	
B0833-45. (Vela)	$130.6 \pm 0.1$	$301 \pm 2$	$8.6 \pm 4$	
B1706-44	$163.6 \pm 0.7$	$160 \pm 10$	$3.6 \pm 11$	
B1951+32	$85 \pm 5$	$252 \pm 7$	$13 \pm 9$	
J1124-5916			$22 \pm 7$	

#### Are neutron star masses clustered around 1.4M<sub>sol</sub>?



Surprising lack of progenitors with M>16 $M_{sol}$  for type IIP SN (Smartt 09) most probable Salpeter IMF (solid line)  $\alpha$ =-2.35,  $M_{min}$ =8.5 $M_{sol}$ ,  $M_{max}$ =16.5 $M_{sol}$ 



#### Selected milestones of mainstream supernova theory: towards 3D ab-initio models

Baade & Zwicky 1934: coins the term "supernova" and suggests the stellar collapse to a neutron star

Gamow & Schönberg 41: energy removal through neutrinos Colgate & White 66: energy deposition by neutrinos



Bethe & Wilson 85: delayed neutrino-driven explosion SN1987A Herant+92: simulation of neutrino-driven convection in 2D

Liebendörfer+01: failed explosion for 13 M<sub>sol</sub> 1D ab-initio with Boltzman transport

Scheck+04: pulsar kicks explained by asymmetric explosions in 2D

Kitaura+06: subluminous explosion from a 8-10  $M_{sol}$  1D ab-initio

Blondin+06: discovery of the Standing Accretion Shock Instability in 2D

Marek & Janka 09: explosion of 15 M<sub>sol</sub> 2D ab-initio

O'Connor & Ott 11: impact of the stellar core compactness in 1D

Müller+12: explosion of 27 M<sub>sol</sub> 2D ab-initio: two different explosion paths

Hanke+13: failed explosion of 27 M<sub>sol</sub> 3D ab-initio

Couch & Ott 13: impact of precollapse turbulence in 3D

Sukhbold +16: SN outcomes from 9 to 120 M<sub>sol</sub> in 1D

