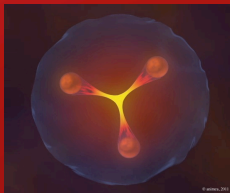


DE LA RECHERCHE À L'INDUSTRIE

cea

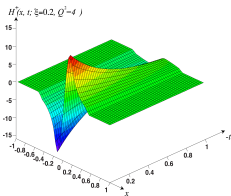
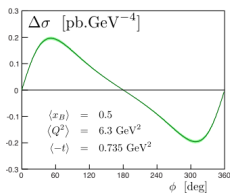
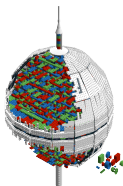


[www.cea.fr](http://www.cea.fr)

PARTONS

AGENCE NATIONALE DE LA RECHERCHE  
ANR

## The PARTONS framework: features and performances



NPQCD 2016, Sevilla | Hervé MOUTARDE

Oct. 19<sup>th</sup>, 2016

## PARTONS Framework

### Motivation

#### Imaging

Experimental access  
DVCS kinematics  
Towards 3D images

#### Modeling

Limitations  
Lorentz symmetry  
Radon transform

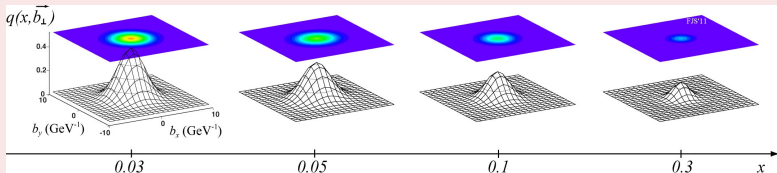
#### Computing

Design  
Features  
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Architecture  
Team

#### Conclusion

- Correlation of the **longitudinal momentum** and the **transverse position** of a parton in the nucleon.
- Insights on:
  - **Spin** structure,
  - **Energy-momentum** structure.
- **Probabilistic interpretation** of Fourier transform of  $\text{GPD}(x, \xi = 0, t)$  in **transverse plane**.

### Transverse plane density (Goloskokov and Kroll model)



## PARTONS Framework

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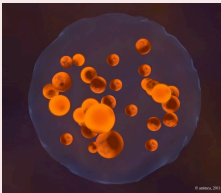
Limitations  
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#### Computing

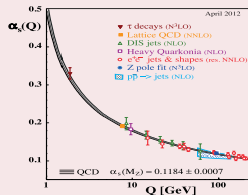
Design  
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Architecture  
Team

#### Conclusion

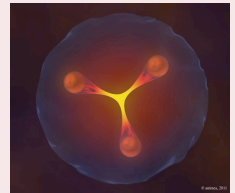
## Perturbative QCD



## Asymptotic freedom



## Nonperturbative QCD



## Perturbative AND nonperturbative QCD at work

- Define **universal** objects describing 3D nucleon structure:  
**Generalized Parton Distributions (GPD).**
- Relate GPDs to measurements using **factorization**:  
**Virtual Compton Scattering (DVCS, TCS),**  
**Deeply Virtual Meson production (DVMP).**
- Get **experimental knowledge** of nucleon structure.

## PARTONS Framework

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Architecture  
Team

#### Conclusion

## 1 The problem of 3D imaging:

*What do we want?*

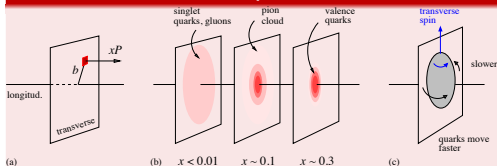
## 2 Phenomenology, GPD models, experimental images:

*What can we actually do?*

## 3 Tools to make the best from experimental data:

*What can we expect from the near future?*

Can we obtain this picture from exclusive measurements?



Weiss, AIP Conf. Proc. **1149**, 150 (2009)

# Principles of nucleon 3D imaging

## PARTONS Framework

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### Imaging

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Design

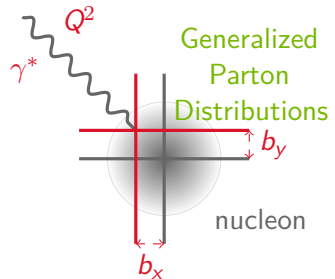
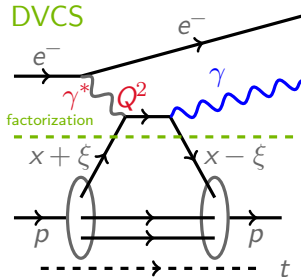
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### PARTONS Framework

#### Motivation

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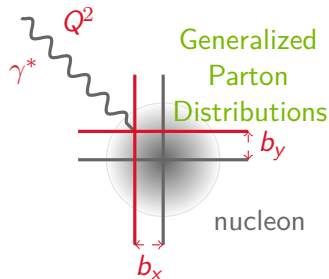
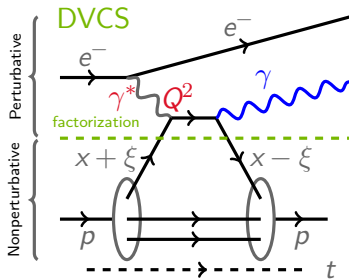
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## PARTONS Framework

### Motivation

### Imaging

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### Modeling

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Design

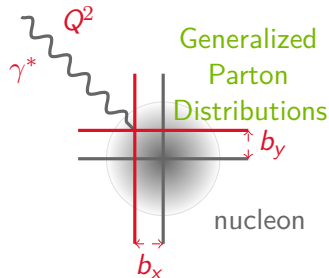
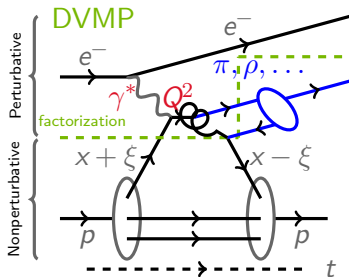
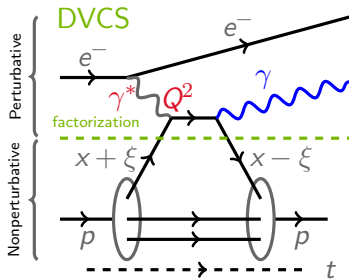
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## PARTONS Framework

### Motivation

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Design

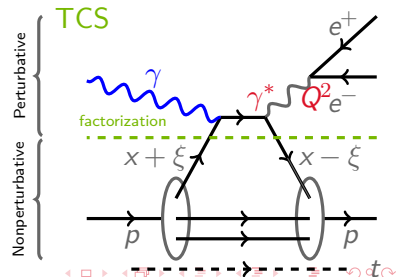
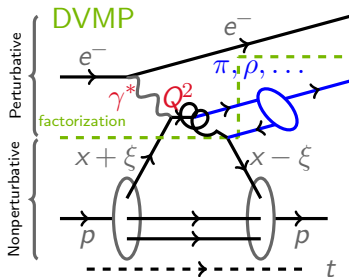
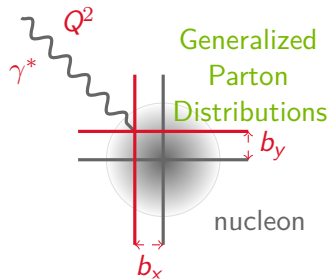
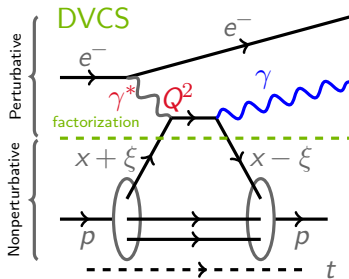
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### Conclusion



# Exclusive processes of current interest (1/2). Factorization and universality.

## PARTONS Framework

### Motivation

### Imaging

### Experimental access

DVCS kinematics

Towards 3D images

### Modeling

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Radon transform

### Computing

Design

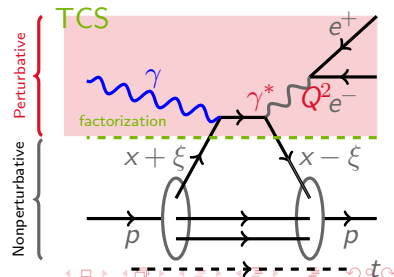
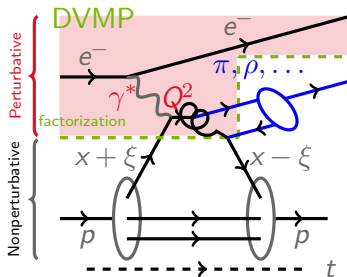
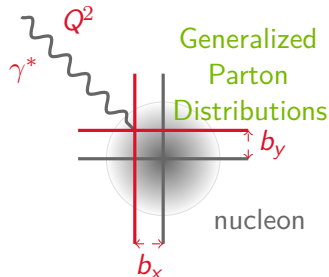
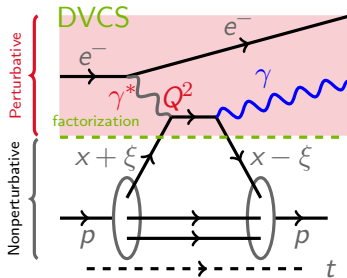
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### Conclusion



# Exclusive processes of current interest (1/2). Factorization and universality.

## PARTONS Framework

### Motivation

### Imaging

#### Experimental access

DVCS kinematics

Towards 3D images

### Modeling

Limitations

Lorentz symmetry

Radon transform

### Computing

Design

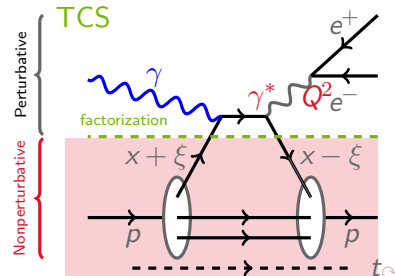
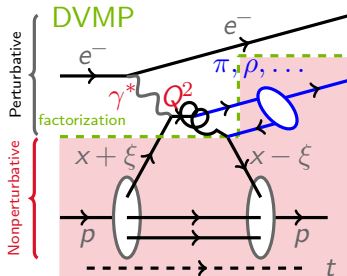
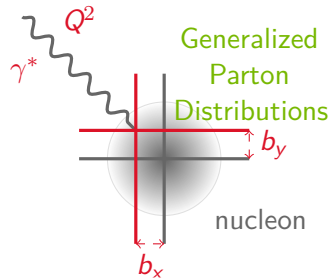
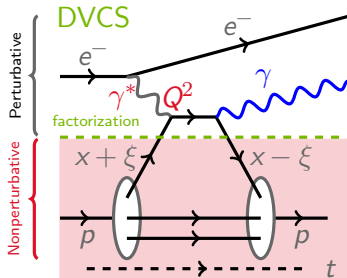
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## PARTONS Framework

### Motivation

### Imaging

### Experimental access

DVCS kinematics  
Towards 3D images

### Modeling

Limitations  
Lorentz symmetry  
Radon transform

### Computing

Design  
Features  
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Architecture  
Team

### Conclusion

Bjorken regime : large  $Q^2$  and fixed  $x_B \simeq 2\xi/(1+\xi)$

- Partonic interpretation relies on **factorization theorems**.
- All-order proofs for DVCS, TCS and some DVMP.
- GPDs depend on a (arbitrary) factorization scale  $\mu_F$ .
- **Consistency** requires the study of **different channels**.

- GPDs enter DVCS through **Compton Form Factors** :

$$\mathcal{F}(\xi, t, Q^2) = \int_{-1}^1 dx C\left(x, \xi, \alpha_S(\mu_F), \frac{Q}{\mu_F}\right) F(x, \xi, t, \mu_F)$$

for a given GPD  $F$ .

- CFF  $\mathcal{F}$  is a **complex function**.

# Need for global fits of world data.

Different facilities will probe different kinematic domains.

## PARTONS Framework

### Motivation

### Imaging

Experimental access

**DVCS kinematics**

Towards 3D images

### Modeling

Limitations

Lorentz symmetry

Radon transform

### Computing

Design

Features

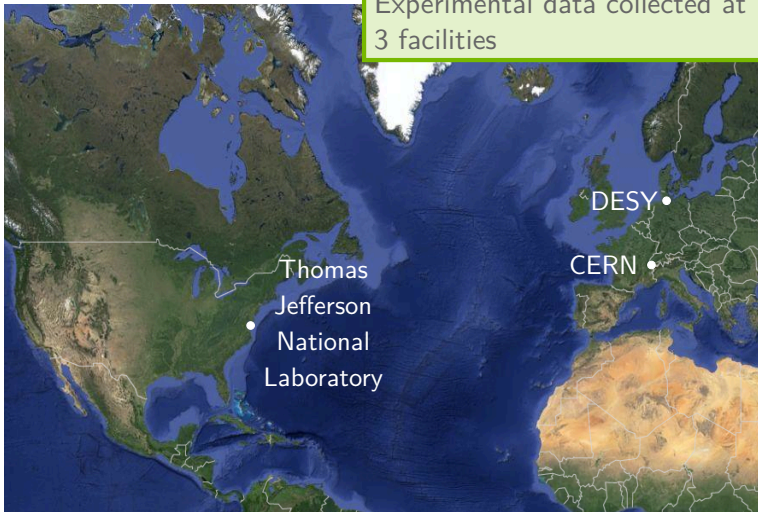
Examples

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### Conclusion

Experimental data collected at 3 facilities



## PARTONS Framework

### Motivation

### Imaging

Experimental access

DVCS kinematics

Towards 3D images

### Modeling

Limitations

Lorentz symmetry

Radon transform

### Computing

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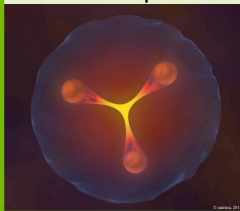
Examples

Architecture

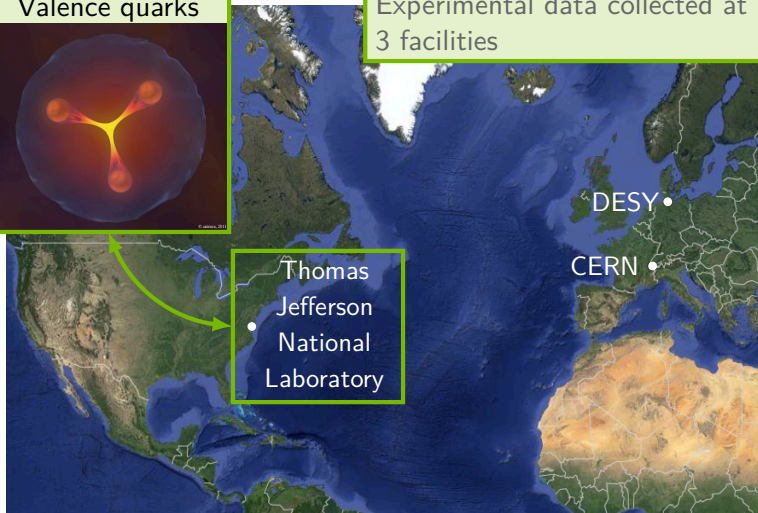
Team

### Conclusion

## Valence quarks



## Experimental data collected at 3 facilities



## PARTONS Framework

### Motivation

### Imaging

Experimental access

DVCS kinematics

Towards 3D images

### Modeling

Limitations

Lorentz symmetry

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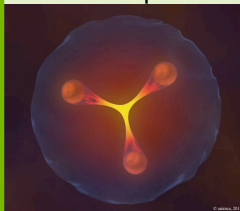
Examples

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### Conclusion

## Valence quarks



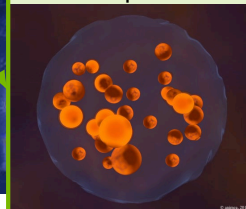
## Experimental data collected at 3 facilities

DESY •

CERN •

Thomas Jefferson National Laboratory

## Sea quarks



# Need for global fits of world data.

Different facilities will probe different kinematic domains.

## PARTONS Framework

### Motivation

### Imaging

Experimental access

DVCS kinematics

Towards 3D images

### Modeling

Limitations

Lorentz symmetry

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### Computing

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Features

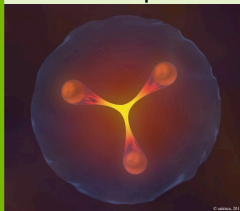
Examples

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### Conclusion

## Valence quarks



Experimental data collected at 3 facilities, soon 4: EIC !

Thomas Jefferson National Laboratory

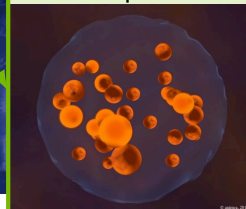
DESY

CERN

## Gluons

NSAC, Long Range Plan 2015:  
"We recommend [...] EIC as the highest priority for new facility construction"

## Sea quarks





## PARTONS Framework

### Motivation

### Imaging

Experimental access  
DVCS kinematics

Towards 3D images

### Modeling

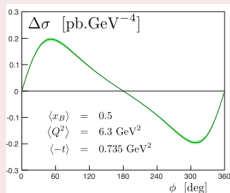
Limitations  
Lorentz symmetry  
Radon transform

### Computing

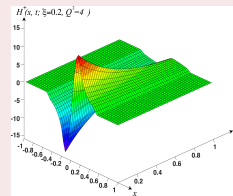
Design  
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Team

### Conclusion

## 1. Experimental data fits



## 2. GPD extraction



## 3. Nucleon imaging

Images from Guidal et al.,  
Rept. Prog. Phys. 76 (2013) 066202

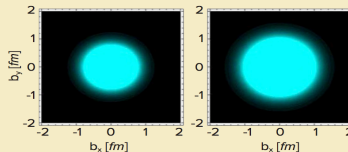
Reaching for the Horizon

The 2015 Long Range Plan for Nuclear Science

### Sidebar 2.2: The First 3D Pictures of the Nucleon

A computed tomography (CT) scan can help physicians pinpoint minute cancer tumors, diagnose tiny broken bones, and spot the early signs of osteoporosis. Now physicists are using the principles behind the procedure to peer at the inner workings of the proton. This breakthrough is made possible by a relatively new concept in nuclear physics called generalized parton distributions.

An intense beam of high-energy electrons can be used



## PARTONS Framework

### Motivation

#### Imaging

Experimental access

DVCS kinematics

Towards 3D images

#### Modeling

Limitations

Lorentz symmetry

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#### Computing

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### Conclusion

1 **Extract**  $H(x, \xi, t, \mu_F^{\text{ref}})$  from experimental data.

2 **Extrapolate** to vanishing skewness  $H(x, 0, t, \mu_F^{\text{ref}})$ .

3 **Extrapolate**  $H(x, 0, t, \mu_F^{\text{ref}})$  up to infinite  $t$ .

4 **Compute** 2D Fourier transform in transverse plane:

$$H(x, b_{\perp}) = \int_0^{+\infty} \frac{d|\Delta_{\perp}|}{2\pi} |\Delta_{\perp}| J_0(|b_{\perp}||\Delta_{\perp}|) H(x, 0, -\Delta_{\perp}^2)$$

5 **Propagate** uncertainties.

6 **Control** extrapolations with an accuracy matching that of experimental data with **sound** GPD models.

# Practice of nucleon 3D imaging

## PARTONS Framework

### Motivation

### Imaging

Experimental access  
DVCS kinematics  
Towards 3D images

### Modeling

#### Limitations

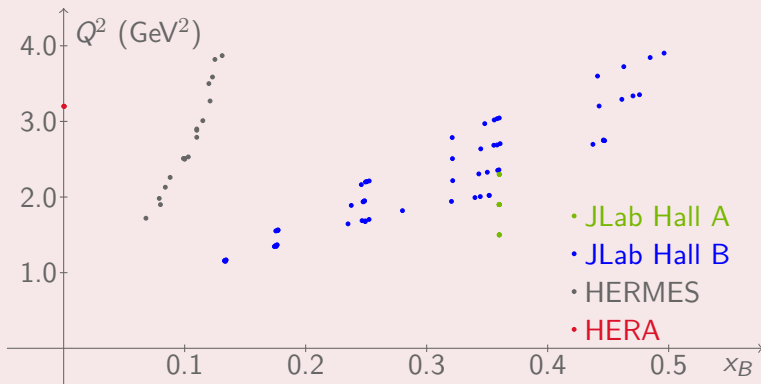
Lorentz symmetry  
Radon transform

### Computing

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### Conclusion

## What is large $Q^2$ ? Measurements before 2015...



■ World data cover **complementary kinematic regions.**

## PARTONS Framework

### Motivation

### Imaging

Experimental access  
DVCS kinematics  
Towards 3D images

### Modeling

### Limitations

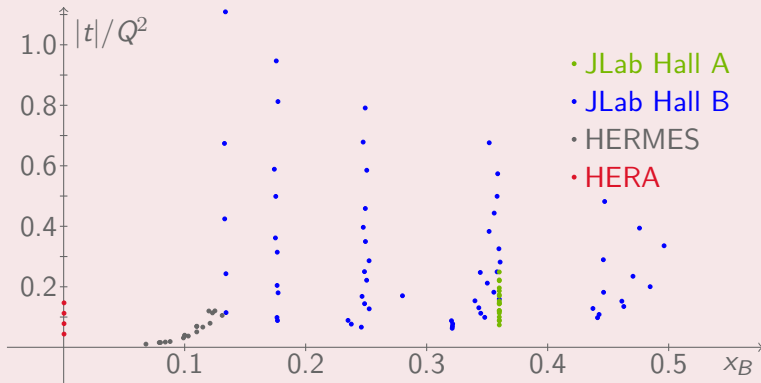
Lorentz symmetry  
Radon transform

### Computing

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### Conclusion

## What is large $Q^2$ ? Measurements before 2015...



- World data cover **complementary kinematic regions**.
- $Q^2$  is **not so large** for most of the data.

## PARTONS Framework

### Motivation

### Imaging

Experimental access  
DVCS kinematics  
Towards 3D images

### Modeling

### Limitations

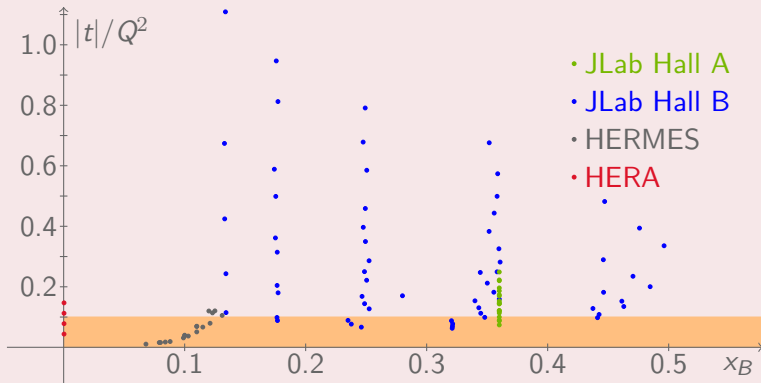
Lorentz symmetry  
Radon transform

### Computing

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### Conclusion

## What is large $Q^2$ ? Measurements before 2015...



- World data cover **complementary kinematic regions**.
- $Q^2$  is **not so large** for most of the data.
- **Higher twists? Finite- $t$  and target mass corrections?**

## PARTONS Framework

### Motivation

### Imaging

Experimental access  
DVCS kinematics  
Towards 3D images

### Modeling

### Limitations

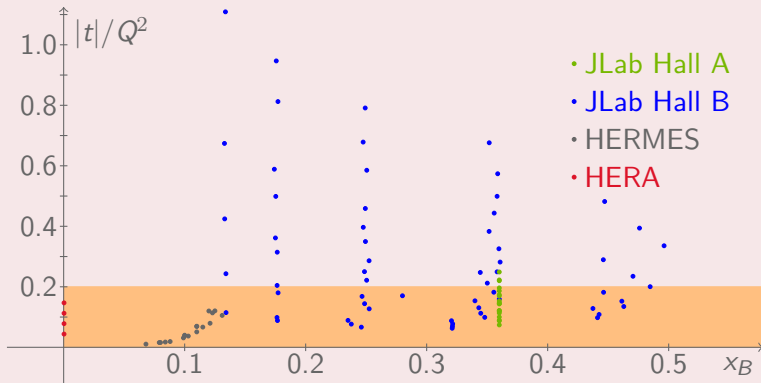
Lorentz symmetry  
Radon transform

### Computing

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### Conclusion

## What is large $Q^2$ ? Measurements before 2015...



- World data cover **complementary kinematic regions**.
- $Q^2$  is **not so large** for most of the data.
- **Higher twists? Finite- $t$  and target mass corrections?**

## PARTONS Framework

GPD  $H$  at  $t = -0.23 \text{ GeV}^2$  and  $Q^2 = 2.3 \text{ GeV}^2$ .

### Motivation

### Imaging

Experimental access  
DVCS kinematics  
Towards 3D images

### Modeling

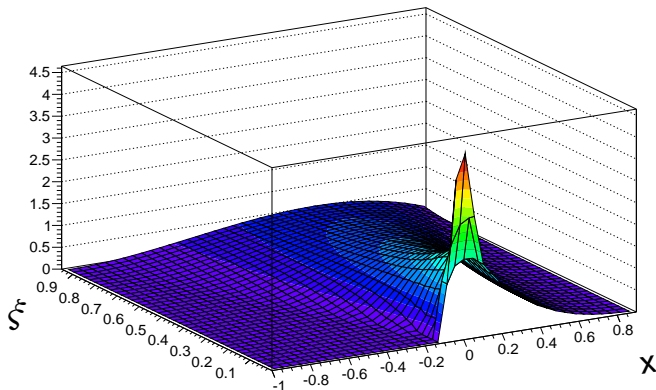
#### Limitations

Lorentz symmetry  
Radon transform

### Computing

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### Conclusion



GPD model: see Kroll *et al.*, Eur. Phys. J. **C73**, 2278 (2013)



## PARTONS Framework

Need to know  $H(x, \xi = 0, t)$  to do transverse plane imaging.

### Motivation

### Imaging

Experimental access  
DVCS kinematics  
Towards 3D images

### Modeling

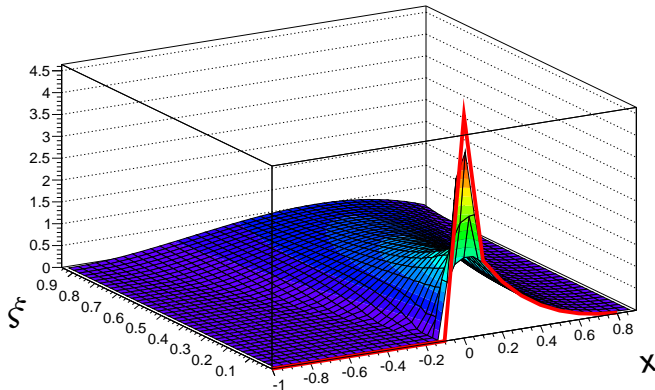
#### Limitations

Lorentz symmetry  
Radon transform

### Computing

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GPD model: see Kroll *et al.*, Eur. Phys. J. **C73**, 2278 (2013)

## PARTONS Framework

### Motivation

### Imaging

Experimental access  
DVCS kinematics  
Towards 3D images

### Modeling

#### Limitations

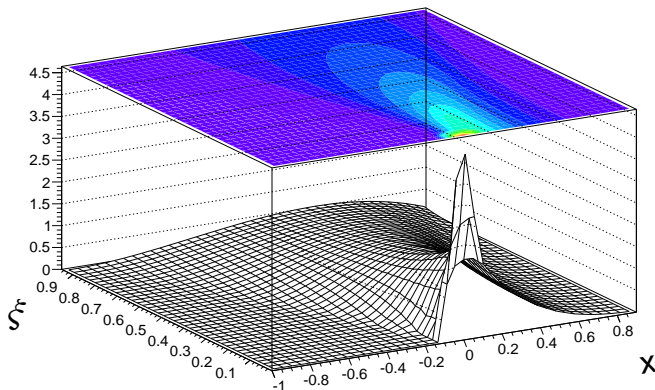
Lorentz symmetry  
Radon transform

### Computing

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### Conclusion

## What is the physical region?



GPD model: see Kroll *et al.*, Eur. Phys. J. **C73**, 2278 (2013)

## PARTONS Framework

$\xi_{\min}$  from finite beam energy.

### Motivation

### Imaging

Experimental access  
DVCS kinematics  
Towards 3D images

### Modeling

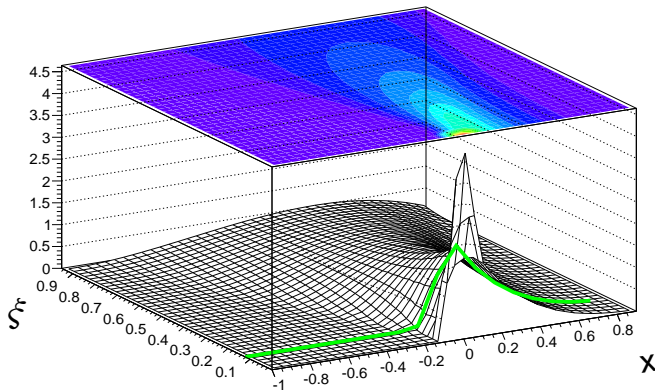
#### Limitations

Lorentz symmetry  
Radon transform

### Computing

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### Conclusion



GPD model: see Kroll *et al.*, Eur. Phys. J. **C73**, 2278 (2013)

## PARTONS Framework

$\xi_{\max}$  from kinematic constraint on 4-momentum transfer.

### Motivation

### Imaging

Experimental access  
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### Modeling

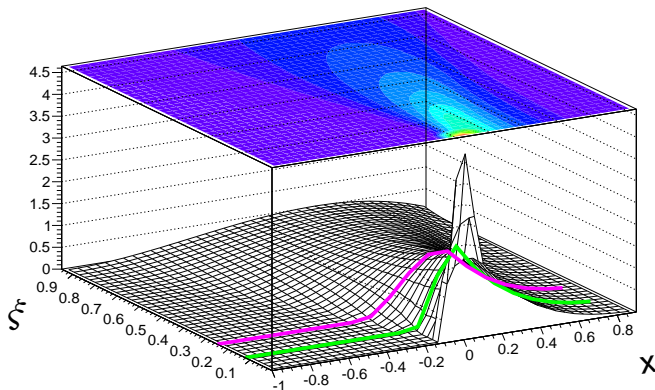
#### Limitations

Lorentz symmetry  
Radon transform

### Computing

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### Conclusion



GPD model: see Kroll *et al.*, Eur. Phys. J. **C73**, 2278 (2013)

## PARTONS Framework

### The cross-over line $x = \xi$ .

#### Motivation

#### Imaging

Experimental access  
DVCS kinematics  
Towards 3D images

#### Modeling

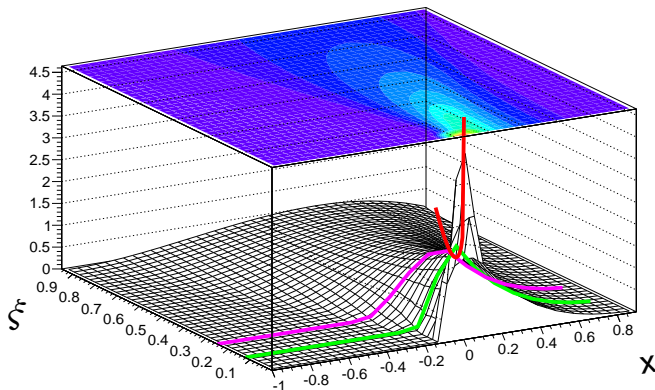
#### Limitations

Lorentz symmetry  
Radon transform

#### Computing

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#### Conclusion



GPD model: see Kroll *et al.*, Eur. Phys. J. **C73**, 2278 (2013)

## PARTONS Framework

The black curve is what is needed for transverse plane imaging!

### Motivation

### Imaging

Experimental access  
DVCS kinematics  
Towards 3D images

### Modeling

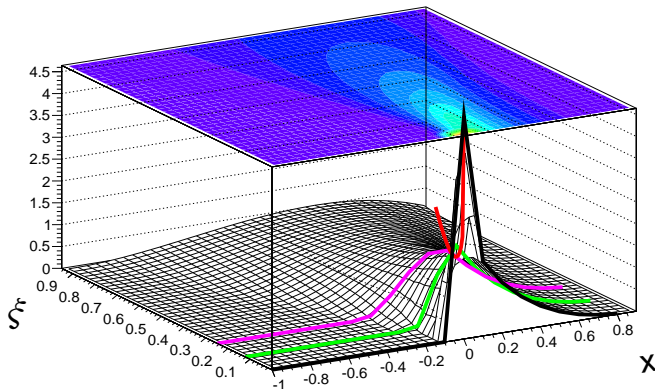
#### Limitations

Lorentz symmetry  
Radon transform

### Computing

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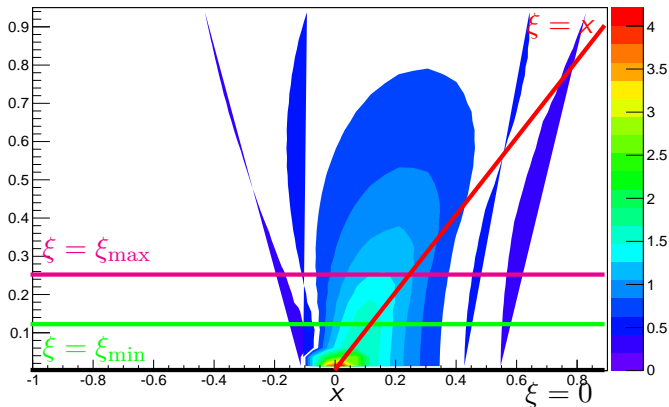
### Conclusion



GPD model: see Kroll *et al.*, Eur. Phys. J. **C73**, 2278 (2013)

## PARTONS Framework

Density plot of  $H$  at  $t = -0.23 \text{ GeV}^2$  and  $Q^2 = 2.3 \text{ GeV}^2$



GPD model: see Kroll *et al.*, Eur. Phys. J. **C73**, 2278 (2013)

### Motivation

### Imaging

Experimental access  
DVCS kinematics  
Towards 3D images

### Modeling

#### Limitations

Lorentz symmetry  
Radon transform

### Computing

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# Spin-0 Generalized Parton Distribution.

Definition and simple properties.

## PARTONS Framework

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### Imaging

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DVCS kinematics  
Towards 3D images

### Modeling

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Lorentz symmetry  
Radon transform

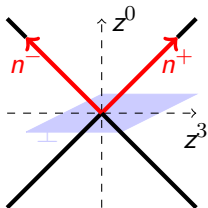
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$$H_{\pi}^q(x, \xi, t) = \frac{1}{2} \int \frac{dz^-}{2\pi} e^{ixP^+z^-} \left\langle \pi, P + \frac{\Delta}{2} \left| \bar{q} \left( -\frac{z}{2} \right) \gamma^+ q \left( \frac{z}{2} \right) \right| \pi, P - \frac{\Delta}{2} \right\rangle_{\substack{z^+=0 \\ z_{\perp}=0}}$$

with  $t = \Delta^2$  and  $\xi = -\Delta^+/(2P^+)$ .



■ PDF forward limit

## References

Müller *et al.*, Fortschr. Phys. **42**, 101 (1994)  
Ji, Phys. Rev. Lett. **78**, 610 (1997)  
Radyushkin, Phys. Lett. **B380**, 417 (1996)

$$H^q(x, 0, 0) = q(x)$$



# Spin-0 Generalized Parton Distribution.

Definition and simple properties.

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$$H_{\pi}^q(x, \xi, t) = \frac{1}{2} \int \frac{dz^-}{2\pi} e^{ixP^+z^-} \left\langle \pi, P + \frac{\Delta}{2} \left| \bar{q} \left( -\frac{z}{2} \right) \gamma^+ q \left( \frac{z}{2} \right) \right| \pi, P - \frac{\Delta}{2} \right\rangle_{z_{\perp}=0}^{z_{\perp}=0}$$

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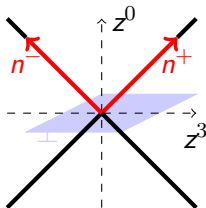
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with  $t = \Delta^2$  and  $\xi = -\Delta^+/(2P^+)$ .



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Radyushkin, Phys. Lett. **B380**, 417 (1996)

- PDF forward limit
- Form factor sum rule

$$\int_{-1}^{+1} dx H^q(x, \xi, t) = F_1^q(t)$$

# Spin-0 Generalized Parton Distribution.

Definition and simple properties.

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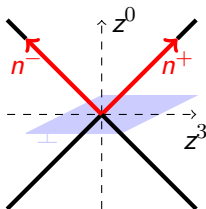
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$$H_{\pi}^q(x, \xi, t) = \frac{1}{2} \int \frac{dz^-}{2\pi} e^{ixP^+z^-} \left\langle \pi, P + \frac{\Delta}{2} \left| \bar{q} \left( -\frac{z}{2} \right) \gamma^+ q \left( \frac{z}{2} \right) \right| \pi, P - \frac{\Delta}{2} \right\rangle_{\substack{z^+=0 \\ z_{\perp}=0}}$$

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Müller *et al.*, Fortschr. Phys. **42**, 101 (1994)  
Ji, Phys. Rev. Lett. **78**, 610 (1997)  
Radyushkin, Phys. Lett. **B380**, 417 (1996)

- PDF forward limit
- Form factor **sum rule**
- $H^q$  is an **even function** of  $\xi$  from time-reversal invariance.

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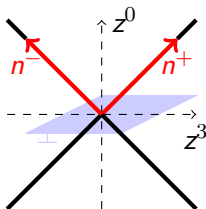
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## References

Müller *et al.*, Fortschr. Phys. **42**, 101 (1994)  
Ji, Phys. Rev. Lett. **78**, 610 (1997)  
Radyushkin, Phys. Lett. **B380**, 417 (1996)

- PDF forward limit
- Form factor **sum rule**
- $H^q$  is an **even function** of  $\xi$  from time-reversal invariance.
- $H^q$  is **real** from hermiticity and time-reversal invariance.

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- Express Mellin moments of GPDs as **matrix elements**:

$$\int_{-1}^{+1} dx x^m H^q(x, \xi, t) = \frac{1}{2(P^+)^{m+1}} \left\langle P + \frac{\Delta}{2} \left| \bar{q}(0) \gamma^+ (i \overleftrightarrow{D}^+)^m q(0) \right| P - \frac{\Delta}{2} \right\rangle$$

- Identify the **Lorentz structure** of the matrix element:

linear combination of  $(P^+)^{m+1-k} (\Delta^+)^k$  for  $0 \leq k \leq m+1$

- Remember definition of **skewness**  $\Delta^+ = -2\xi P^+$ .
- Select **even powers** to implement time reversal.
- Obtain **polynomiality condition**:

$$\int_{-1}^1 dx x^m H^q(x, \xi, t) = \sum_{\substack{i=0 \\ \text{even}}}^m (2\xi)^i C_{mi}^q(t) + (2\xi)^{m+1} C_{m+1}^q(t).$$

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### Motivation

- Choose  $F^q(\beta, \alpha) = 3\beta\theta(\beta)$  and  $G^q(\beta, \alpha) = 3\alpha\theta(\beta)$ :

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$$H^q(x, \xi) = 3x \int_{\Omega} d\beta d\alpha \delta(x - \beta - \alpha\xi)$$

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- Simple analytic expressions for the GPD:

$$H(x, \xi) = \frac{6x(1-x)}{1-\xi^2} \text{ if } 0 < |\xi| < x < 1,$$

$$H(x, \xi) = \frac{3x(x+|\xi|)}{|\xi|(1+|\xi|)} \text{ if } -|\xi| < x < |\xi| < 1.$$

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■ Compute first Mellin moments.

$n$	$\int_{-\xi}^{+\xi} dx x^n H(x, \xi)$	$\int_{+\xi}^{+1} dx x^n H(x, \xi)$	$\int_{-\xi}^{+1} dx x^n H(x, \xi)$
0	$\frac{1+\xi-2\xi^2}{1+\xi}$	$\frac{2\xi^2}{1+\xi}$	1
1	$\frac{1+\xi+\xi^2-3\xi^3}{2(1+\xi)}$	$\frac{2\xi^3}{1+\xi}$	$\frac{1+\xi^2}{2}$
2	$\frac{3(1-\xi)(1+2\xi+3\xi^2+4\xi^3)}{10(1+\xi)}$	$\frac{6\xi^4}{5(1+\xi)}$	$\frac{3(1+\xi^2)}{10}$
3	$\frac{1+\xi+\xi^2+\xi^3+\xi^4-5\xi^5}{5(1+\xi)}$	$\frac{6\xi^5}{5(1+\xi)}$	$\frac{1+\xi^2+\xi^4}{5}$
4	$\frac{1+\xi+\xi^2+\xi^3+\xi^4+\xi^5-6\xi^6}{7(1+\xi)}$	$\frac{6\xi^6}{7(1+\xi)}$	$\frac{1+\xi^2+\xi^4}{7}$

■ Expressions get more complicated as  $n$  increases... But they always yield polynomials!

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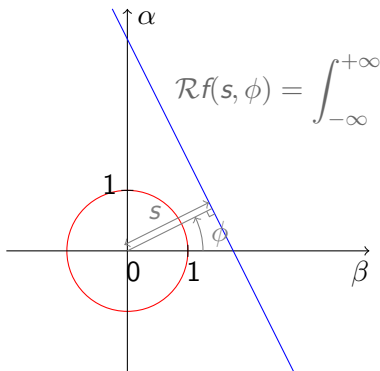
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$$\mathcal{R}f(s, \phi) = \int_{-\infty}^{+\infty} d\beta d\alpha f(\beta, \alpha) \delta(s - \beta \cos \phi - \alpha \sin \phi)$$

For  $s > 0$  and  $\phi \in [0, 2\pi]$ :

and:

$$\mathcal{R}f(-s, \phi) = \mathcal{R}f(s, \phi \pm \pi)$$

Relation to GPDs:

$$x = \frac{s}{\cos \phi} \text{ and } \xi = \tan \phi$$

Relation between GPD and DD in Belitsky *et al.* gauge

$$\frac{\sqrt{1 + \xi^2}}{x} H(x, \xi) = \mathcal{R}f_{\text{BMKS}}(s, \phi) ,$$

## PARTONS Framework

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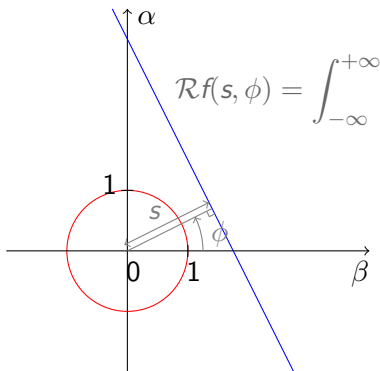
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$$\mathcal{R}f(s, \phi) = \int_{-\infty}^{+\infty} d\beta d\alpha f(\beta, \alpha) \delta(s - \beta \cos \phi - \alpha \sin \phi)$$

For  $s > 0$  and  $\phi \in [0, 2\pi]$ :

and:

$$\mathcal{R}f(-s, \phi) = \mathcal{R}f(s, \phi \pm \pi)$$

Relation to GPDs:

$$x = \frac{s}{\cos \phi} \text{ and } \xi = \tan \phi$$

Relation between GPD and DD in Pobylitsa gauge

$$\frac{\sqrt{1 + \xi^2}}{1 - x} H(x, \xi) = \mathcal{R}f_P(s, \phi),$$



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- The Mellin moments of a Radon transform are **homogeneous polynomials** in  $\omega = (\sin \phi, \cos \phi)$ .
- The converse is also true:

### Theorem (Hertle, 1983)

*Let  $g(s, \omega)$  an even compactly-supported distribution. Then  $g$  is itself the Radon transform of a compactly-supported distribution if and only if the **Ludwig-Helgason consistency condition** hold:*

- (i)  $g$  is  $C^\infty$  in  $\omega$ ,
- (ii)  $\int ds s^m g(s, \omega)$  is a homogeneous polynomial of degree  $m$  for all integer  $m \geq 0$ .

- Double Distributions and the Radon transform are the **natural solution** of the polynomiality condition.

## PARTONS Framework

## Extrapolations...

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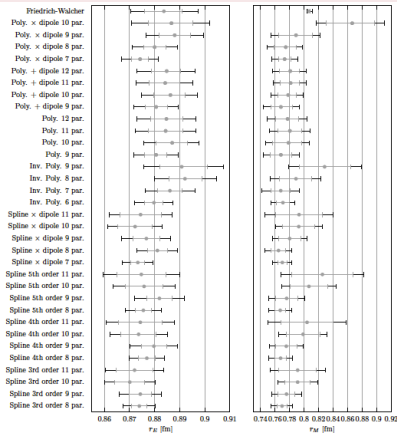
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Bernauer *et al.*(A1 Coll.), Phys. Rev. **C90**, 015206 (2014)

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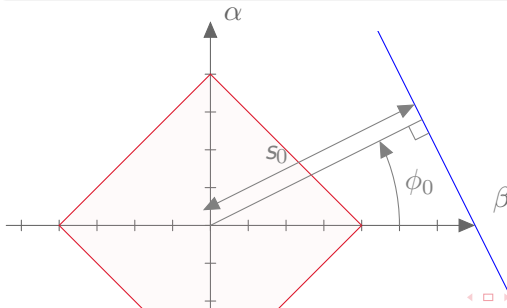
### Conclusion

## Theorem

Let  $f$  be a compactly-supported summable function defined on  $\mathbb{R}^2$  and  $\mathcal{R}f$  its Radon transform.

Let  $(s_0, \omega_0) \in \mathbb{R} \times S^1$  and  $U_0$  an open neighborhood of  $\omega_0$  s.t.:  
for all  $s > s_0$  and  $\omega \in U_0$   $\mathcal{R}f(s, \omega) = 0$ .

Then  $f(\aleph) = 0$  on the half-plane  $\langle \aleph | \omega_0 \rangle > s_0$  of  $\mathbb{R}^2$ .



- $\omega_0 = (\cos \phi_0, \sin \phi_0)$ .
- $\aleph = (\beta, \alpha)$ .

# Support theorem.

We don't need to know the GPD everywhere to image the proton!

## PARTONS Framework

- Assume deconvolution of CFF achieved.
- Data:  $H(x, \xi)$  for all  $x \in [-1, +1]$  and  $\xi \in [\xi_{\min}, \xi_{\max}]$ .

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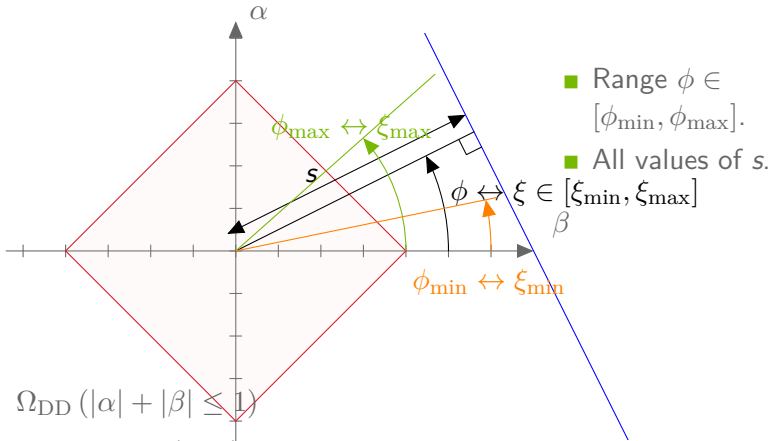
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$$\Omega_{DD} (|\alpha| + |\beta| \leq 1)$$

- The DD  $f(\beta, \alpha)$  can be **uniquely** determined.
- $H(x, \xi = 0)$  **uniquely** constrained by **Lorentz covariance**!

# Building the tools for high precision: the PARTONS project



**PAR**tonic  
Tomography  
Of  
Nucleon  
Software

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- Evaluation of the impact of **higher order** effects.
- Evaluation of the impact of **target mass and finite- $t$**  corrections.
- Evaluation of the contribution of **higher twist** GPDs.
- DVMP: sensitivity to **DA models**.
- Extrapolations with **GPD models**.

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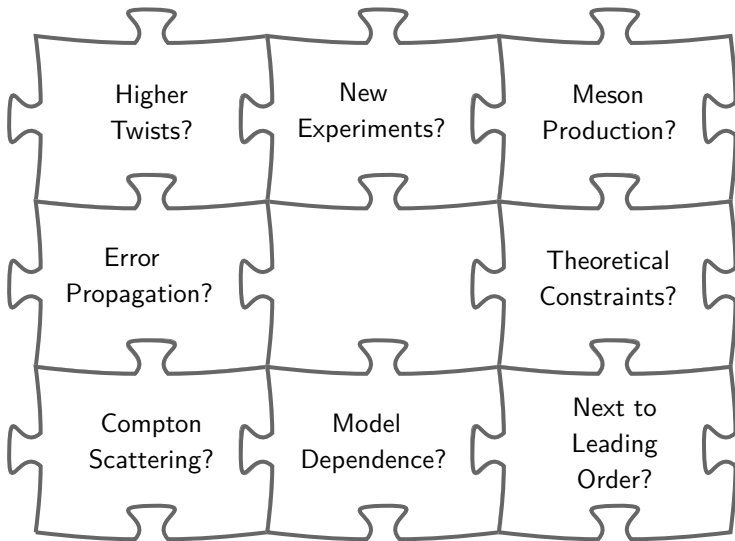
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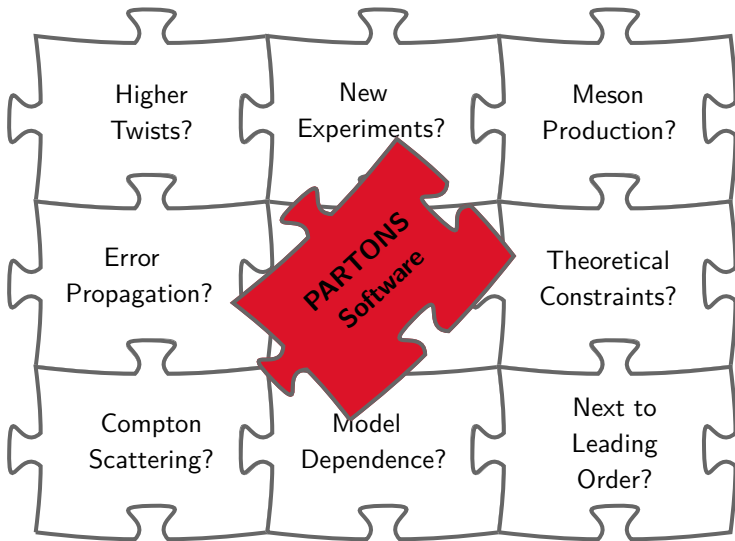
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contributions

First  
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Large distance  
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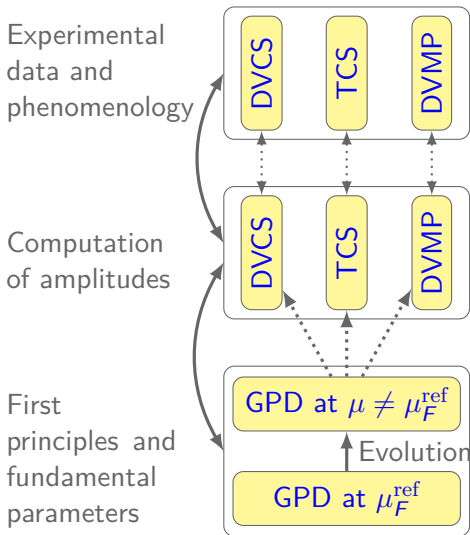
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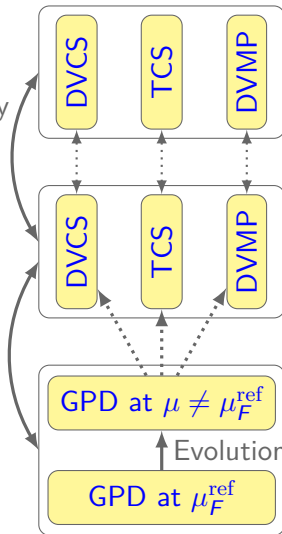
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Experimental data and phenomenology

Computation of amplitudes

First principles and fundamental parameters



- Many observables.
- Kinematic reach.

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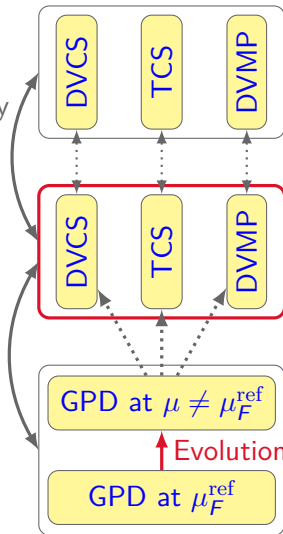
### Conclusion

Experimental data and phenomenology

Need for modularity

Computation of amplitudes

First principles and fundamental parameters



- Many observables.
- Kinematic reach.

- **Perturbative approximations.**
- Physical models.
- Fits.
- Numerical methods.
- Accuracy and speed.

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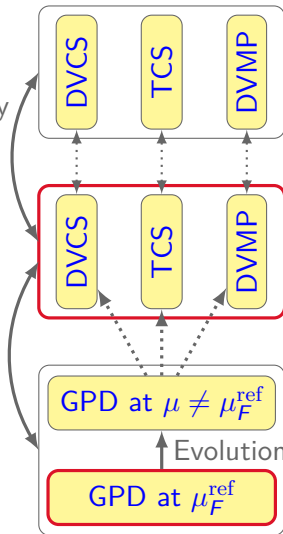
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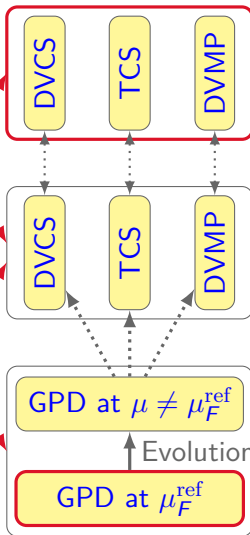
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Experimental data and phenomenology

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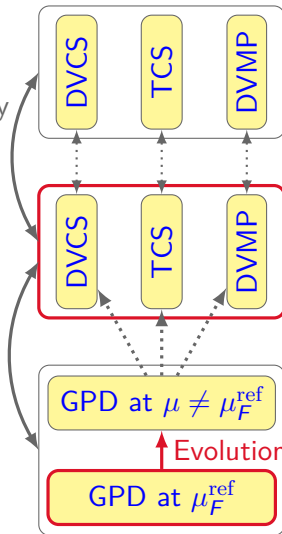
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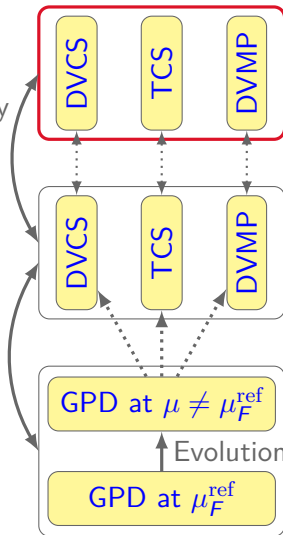
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## ■ 3 stages:

- 1 Design.
- 2 Integration and validation.
- 3 Benchmarking and production.

## ■ Flexible software architecture.

B. Berthou *et al.*, *PARTONS: a computing platform for the phenomenology of Generalized Parton Distributions*  
arXiv:1512.06174, to appear in *Eur. Phys. J. C*.

## ■ 1 new physical development = 1 new module.

## ■ Aggregate **knowledge** and **know-how**:

- Models
- Measurements
- Numerical techniques
- Validation

## ■ What *can* be automated *will be* automated.

Automation allows...:

- to run **numerous computations** with various physical assumptions,
- to run **nonregression** tests.
- to perform **fits** with various models.
- physicists to **focus on physics!**

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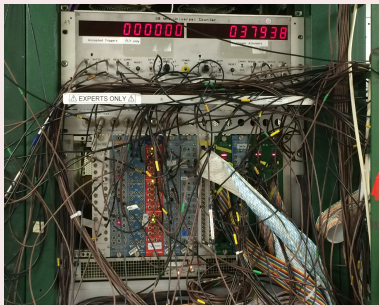
Design

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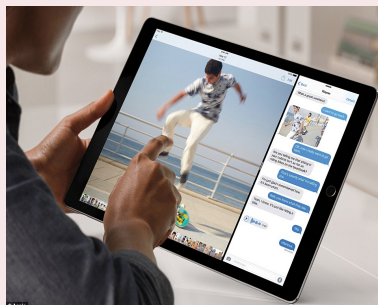
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## Without PARTONS



## With PARTONS



## PARTONS Framework

## GPD computations with or without threads

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The screenshot shows a Slack channel named #general with 12 members. The channel is part of the PARTONS workspace, managed by Hervé MOUTARDE. The channel list on the left includes #collaboration, #database, #elementary\_utils, #general (selected), #large\_distance, #numa, #numa\_tests, #observables, #partons, #partons\_exe, #partons\_fits, #partons\_tests, #partons\_v0, #partons\_visualization, #radon-inverse, #random, #short\_distance, #slack\_test, #trello, #virtual\_machine, and #svn.

The conversation history shows:

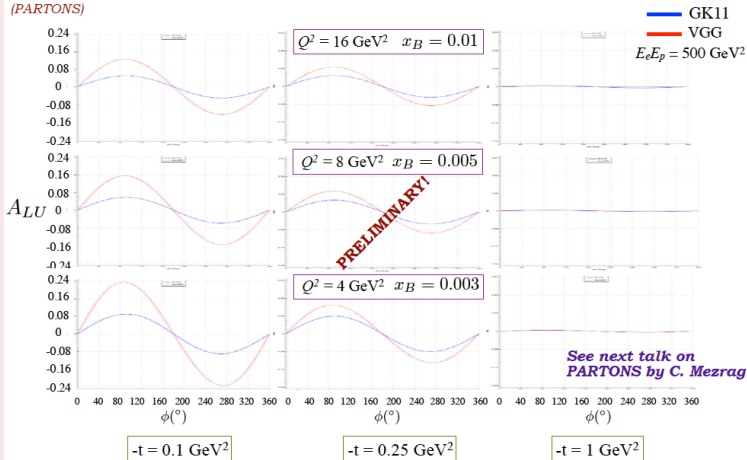
- A message from Bryan BERTHOU (15:02) stating: "also I still have to 'clean' it, get rid of the old code". Below this is a list of performance metrics for a Virtual Machine with 1000 kinematics:
  - GK11: 740 GPDResult/sec (H, Ht, E, Et)
  - GK11Test: 200 GPDResult/sec (H, Ht, E, Et) (edited)
  - MMS13: 75 GPDResult/sec (H, E)
  - MPSSW13: 40 GPDResult/sec (H) (edited)
- A message from Nabil Chouika (15:03) saying "nice".
- A message from Bryan BERTHOU (15:10) stating: "In my own computer with 3 threads there is no errors and it take only 2sec for 1000 kinematics -> 500 results/sec.".
- A message from Cédric (16:33) saying: "Very good! I will have plenty of good news to give at the EIC collaboration meeting. So your 500 results per second means that you can compute 500 given kinematics of  $H(x, xi, t, Q^2)$  per second, is that correct? or is it that you can compute 500 given kinematics for every GPDs per second?"
- A message from Hervé MOUTARDE (17:14) replying to Cédric: "Hi Cédric! With 2+1 threads (1 for the logger, 2 for the computation) Bryan computes H, Ht, E and Et for u, d, s and g on 500 different (x, xi, t, MuF2, Mur2) kinematic configurations in an

## PARTONS Framework

From D. Sokhan's talk, EIC User Group Meeting, ANL, 2016

Luca Colaneri,  
Nabil Chouika  
(PARTONS)

## DVCS beam-spin asymmetries at EIC



## PARTONS Framework

## First fit of pseudo DVCS data, Sep. 26<sup>th</sup>, 2016

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Mattermost

@herve PARTONS

partons\_fits

partons\_tests

partons\_v0

partons\_visualization

radon-inverse

short\_distance

Town Square

trelo

virtual\_machine

More...

PRIVATE GROUPS

Gitlab

Seville

DIRECT MESSAGES

bryan

cedric

dbinosi

jakub

luca

nchouika

pawel

partons\_fits

partons\_fits

7

Search

Mon, Sep 26, 2016

pawel 3:16 PM

EXT NO.	PARAMETER	VALUE	ERROR	STEP SIZE	ERROR MATRIX FIRST DERIVATIVE	ACCURATE
1	fit_CFF_H_Re	6.67247e-02	1.34241e+00	2.92531e-05	-7.02262e-07	
2	fit_CFF_H_Im	1.24231e+01	1.07342e+00	1.80608e-05	1.71071e-04	
3	fit_CFF_E_Re	-3.94789e+00	fixed			
4	fit_CFF_E_Im	-1.64116e-01	fixed			
5	fit_CFF_Ht_Re	1.54183e+00	fixed			
6	fit_CFF_Ht_Im	2.59017e+00	fixed			
7	fit_CFF_Et_Re	5.41102e+01	fixed			
8	fit_CFF_Et_Im	3.79052e+01	fixed			

FCN=1.00128e-11 FROM MIGRAD STATUS=CONVERGED 44 CALLS 45 TOTAL

EDM=2.00186e-11 STRATEGY= 1

EXTERNAL ERROR MATRIX. NDIM= 25 NPAR= 2 ERR DEF=1

PARAMETER	CORRELATION	COEFFICIENTS
NO.	GLOBAL	1 2
1	0.00552	1.000 0.006
2	0.00552	0.006 1.000

The first reasonable fit with PARTONS\_Fits! 12 AUL and 12 ALU asymmetries fitted together.

The true values of fit\_CFF\_H\_Re and fit\_CFF\_H\_Im are 0.06672466940113253 and 12.423114181138908

Write a message...

Help

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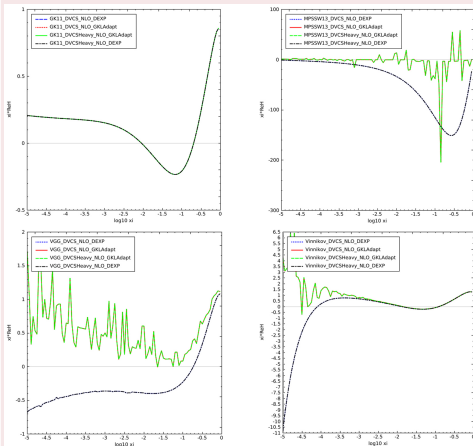
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## Coefficient functions, from EIC to Jefferson Lab kinematics



- Previous tests of integration routines.
- Preparation of nonregression tools.
- Flexibility at work: **physical** models and **numerical** techniques.
- $\simeq 2 \times 10^4$  GPD computed in  $\lesssim 1'$ .

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```

_____ gpdExample() _____
1  // Lots of includes
2  #include <src/Partons.h>
3  ...
4  // Retrieve GPD service
5  GPDService* pGPDService = Partons::getInstance()->getServiceObjectRegistry
   ()->getGPDService();
6  // Load GPD module with the BaseModuleFactory
7  GPDModule* pGK11Model = Partons::getInstance()->getModuleObjectFactory
   ()->newGPDModule(GK11Model::classId);
8  // Create a GPDKinematic(x, xi, t, MuF, MuR) to compute
9  GPDKinematic gpdKinematic(0.1, 0.00050025, -0.3, 8., 8.);
10 // Compute data and store results
11 GPDResult gpdResult = pGPDService->
   computeGPDModelRestrictedByGPDType(gpdKinematic, pGK11Model,
   GPDType::ALL);
12 // Print results
13 std::cout << gpdResult.toString() << std::endl;
14
15 delete pGK11Model;
16 pGK11Model = 0;

```



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```

computeOneGPD.xml
1 <?xml version="1.0" encoding="UTF-8" standalone="yes" ?>
2 <scenario id="01" date="" description="Example of computation of one GPD
   model (GK11) without evolution">
3   <!-- Select type of computation -->
4   <task service="GPDSERVICE" method="computeGPDModel">
5     <!-- Specify kinematic -->
6     <kinematics type="GPDKinematic">
7       <param name="x" value="0.1" />
8       <param name="xi" value="0.00050025" />
9       <param name="t" value="-0.3" />
10      <param name="MuF2" value="8" />
11      <param name="MuR2" value="8" />
12    </kinematics>
13    <!-- Select GPD model and set parameters -->
14    <computation_configuration>
15      <module type="GPDModule">
16        <param name="className" value="GK11Model" />
17      </module>
18    </computation_configuration>
19  </task>
20 </scenario>

```

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## computeOneGPD.xml

```

1 <?xml version="1.0" encoding="UTF-8" stand
2 <scenario id="01" date="" description="Exam
   _model_(GK11)_without_evolution">
3   <!-- Select type of computation -->
4   <task service="GPDSERVICE" method="con
5   <!-- Specify kinematic -->
6   <kinematics type="GPDKinematic">
7     <param name="x" value="0.1" />
8     <param name="xi" value="0.000
9     <param name="t" value="-0.3" />
10    <param name="MuF2" value="8" />
11    <param name="MuR2" value="8" />
12  </kinematics>
13  <!-- Select GPD model and set parameter
14  <computation_configuration>
15    <module type="GPDModule">
16      <param name="className" va
17    </module>
18  </computation_configuration>
19 </task>
20 </scenario>

```

$$H^u = 0.822557$$

$$H^{u(+)} = 0.165636$$

$$H^{u(-)} = 1.47948$$

$$H^d = 0.421431$$

$$H^{d(+)} = 0.0805182$$

$$H^{d(-)} = 0.762344$$

$$H^s = 0.00883408$$

$$H^{s(+)} = 0.0176682$$

$$H^{s(-)} = 0$$

$$H^g = 0.385611$$

$$\text{and } E, \tilde{H}, \tilde{E}, \dots$$

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## computeOneCFF.xml

```

1 <?xml version="1.0" encoding="UTF-8" standalone="yes" ?>
2 <scenario id="03" date="" description="Example of one
   convol coeff function model (DVCS CFF) with GPD model (GK11)">
3   <task service="ConvolCoeffFunctionService" method="
      computeWithGPDModel"
4     <kinematics type="DVCSConvolCoeffFunctionKinematic">
5       <param name="xi" value="0.5" />
6       <param name="t" value="-0.1346" />
7       <param name="Q2" value="1.5557" />
8       <param name="MuF2" value="4" />
9       <param name="MuR2" value="4" />
10    </kinematics>
11    <computation_configuration>
12      <module type="GPDModule">
13        <param name="className" value="GK11Model" />
14      </module>
15      <module type="DVCSConvolCoeffFunctionModule">
16        <param name="className" value="DVCS CFF Model" />
17        <param name="qcd_order_type" value="LO" />
18      </module>
19    </computation_configuration>
20  </task>

```

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## computeOneCFF.xml

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6       <param name="t" value="-0.1346" />
7       <param name="Q2" value="1.5557" />
8       <param name="MuF2" value="4" />
9       <param name="MuR2" value="4" />
10    </kinematics>
11    <computation_configuration>
12      <module type="GPDModule">
13        <param name="className" value="GK11Model" />
14      </module>
15      <module type="DVCSConvolCoeffFunctionModel">
16        <param name="c" value="1.47722 + 1.76698 i" />
17        <param name="q" value="0.12279 + 0.512312 i" />
18      </module>
19    </computation_configuration>
20  </task>

```

$$\begin{aligned}
 \mathcal{H} &= 1.47722 + 1.76698 i \\
 \mathcal{E} &= 0.12279 + 0.512312 i \\
 \tilde{\mathcal{H}} &= 1.54911 + 0.953728 i \\
 \tilde{\mathcal{E}} &= 18.8776 + 3.75275 i
 \end{aligned}$$

## PARTONS Framework

### computeManyKinematicsOneModel.xml

```

1 <scenario date="2016-10-18" description="Use_kinematics_list">
2   <task service="ObservableService" method="
computeManyKinematicOneModel" storeInDB="1">
3     <kinematics type="ObservableKinematic">
4       <param name="file" value="observable_kinematics.dat" />
5     </kinematics>
6     <computation_configuration>
7       <module type="Observable">
8         <param name="className" value="Alu" />
9       </module>
10      <module type="DVCSModule">
11        <param name="className" value="BMJ2012Model" />
12        <param name="beam_energy" value="1066" />
13      </module>
14      <module type="DVCSConvolCoeffFunctionModule">
15        <param name="className" value="DVCSFFModel" />
16        <param name="qcd_order_type" value="LO" />
17      </module>
18      <module type="GPDModule">
19        <param name="className" value="GK11Model" />
20      </module>
21    </computation_configuration>

```

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## QueryDatabaseObservablePlotFile.xml

```

1 <?xml version="1.0" encoding="UTF-8" standalone="yes" ?>
2 <scenario date="2016-10-18" description="...">
3   <!-- Generate plot file from database for GK model-->
4   <task service="ObservableService" method="generatePlotFile">
5     <task_param type="output">
6       <param name="filePath" value="observable_GK11_plot.csv" /
7     </task_param>
8     <!-- Variables of 2d plot -->
9     <task_param type="select">
10       <param name="xPlot" value="phi" />
11       <param name="yPlot" value="observable_value" />
12     </task_param>
13     <!-- Select results in database -->
14     <task_param type="where">
15       <param name="xB" value="0.1763" />
16       <param name="t" value="-0.1346" />
17       <param name="Q2" value="1.3651" />
18       <param name="computation_id" value="2" />
19     </task_param>
20   </task>
21 </scenario>

```

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## QueryDatabaseObservablePlotFile.xml

```

1 <?xml version="1.0" encoding="UTF-8" standalone="yes" ?>
2 <scenario date="2016-10-18" description="...">
3   <!-- Generate plot file from database for GK model -->
4   <task service="ObservableService" method="generatePlotFile">
5     <task_param type="output">
6       <param name="filePath" value="observable_GK11_plot.csv" /
7     </task_param>
8   <!-- Variables of 2d plot -->
9   <task_param type="variables">
10     <param name="phi" value="0. 10. 20. 30. ... 350. 360." /
11     <param name="ALU" value="0. 0.024736075012605108 0.048810639423911277 0.071572336121144678 ... -0.024736075012605111 -9.0547874403168658e-17" /
12   </task_param>
13   <!-- Select re
14   <task_param type="select"
15     <param name="phi" value="0. 10. 20. 30. ... 350. 360." /
16     <param name="ALU" value="0. 0.024736075012605108 0.048810639423911277 0.071572336121144678 ... -0.024736075012605111 -9.0547874403168658e-17" /
17   </task_param>
18   </task>
19 </scenario>

```

$\phi$ [deg]	$A_{LU}$
0.	0.
10.	0.024736075012605108
20.	0.048810639423911277
30.	0.071572336121144678
...	...
350.	-0.024736075012605111
360.	-9.0547874403168658e-17

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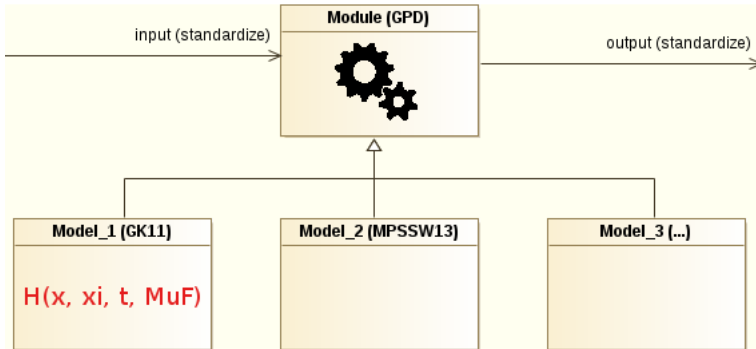
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- Steps of logic sequence in parent class.
- Model description and related mathematical methods in daughter class.



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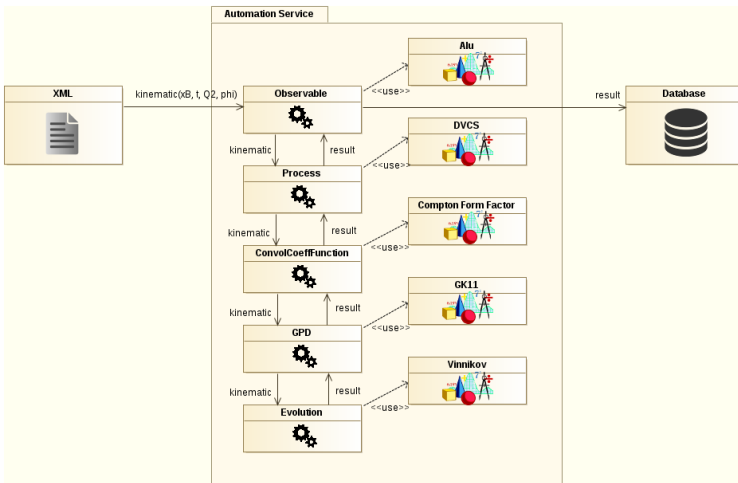
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Pivotal year  
for GPDs

2011 situation  
GPDs and DVCS  
Leading twist,  
leading order  
Selected data

Status of GPD  
analysis

Extraction  
methods  
Universality  
Key results

Future  
orientations  
COMPASS-II  
JLab's 12 GeV  
upgrade  
Spin observables  
on an EIC

The PROPHET  
package

Conclusions

## PROPHET.

Platform for Representing the Organization of Partons inside Hadrons and Experimental Tomographies.

- ① Comprehensive **database of experimental results**.
- ② Comprehensive **database of theoretical predictions**.
- ③ **Fitting engine**.
- ④ **Propagation** of statistic and systematic **uncertainties**.
- ⑤ **Visualizing software** to compare experimental results and model expectations.
- ⑥ Connection to **experimental set-up descriptions** to design new experiments.
- ⑦ **Interactive website** providing free access to model and experimental values.

## PARTONS Framework

Many (unfortunately not all!) problems can be solved fast

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**PARTONS** - Hervé MOUTARDE

**CHANNELS** (21)

- # collaboration
- # database
- # elementary\_utils
- # general**
- # large\_distance
- # numa
- # numa\_tests
- # observables
- # partons
- # partons\_exe
- # partons\_fits
- # partons\_tests
- # partons\_v0
- # partons\_visualization
- # radon-inverse
- # random
- # short\_distance
- # slack\_test
- # trello
- # virtual\_machine
- # svn

**DIRECT MESSAGES** (23)

- slackbot
- Hervé MOUTARDE (you)
- Bryan BERTHOU
- Bryan, Luca, Pawel, Na...
- Luca Colaneri
- Luca, Bryan, Nabil
- Nabil Chouika
- Pawel Sznajder
- Pawel, Bryan
- Pepe Rodríguez Quintero
- Trello
- Invite people

**#general**  
12 members | Company-wide announcements and work-based matters

June 29th

if you reverse that part of the curve

**Nabil Chouika** 11:21  
very clearly

**Daniele Binosi** 11:21  
you get it right

**Luca Colaneri** 11:32  
yes I already did that  
it works now

**Daniele Binosi** 11:33  
mmm apparently one time more than enough

**Luca Colaneri** 11:34  
uploaded a file

**plot.pdf**  
PDF

**Pawel Sznajder** 11:35  
<https://youtu.be/y5ibJ9UOGPA>

YouTube | Reikka Alexiel  
Kung Fury - Favorite Lines - Teamwork is very important

Kung Fury - Favorite Lines - Teamwork is...

**Kung Fury**  
Favorite Scenes  
Power Move

**Jakub Wagner** 11:42  
Wow, guys I am impressed. Four guys in four places in three countries, solved the problem in less than an hour. Congratulations!

# 1 multidisciplinary team over 5 countries

Theorists, experimentalists, 1 mathematician + 1 software engineer

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## U. Paris-Saclay



Berthou



Chouika



Guidal



Lafitte



Moutarde



Sabatié



Sznajder

## NCBJ



Wagner

## ANL



Mezrag

ANL

U. Conn

U. Paris  
Saclay

NCBJ

ECT\*

U. Huelva

## U. Conn



Colaneri



Joo

## U. Huelva



Rodríguez-Quintero

## ECT\*/FBK



Binosi



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- **Challenging constraints** expected from Jefferson Lab in valence region and later from EIC in gluon sector.
- **Good theoretical control** on the path between GPD models and experimental data.
- Success of physics program requires new GPD models with **proper implementations of symmetries**.
- Development of the PARTONS framework for **phenomenology** and **theory** purposes.
- **Fitting engine** ready for local fits. Global fits *in progress*.
- **First release** of PARTONS by the end of 2016!

