# High-Order Finite Difference Schemes for computational MHD

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## Outline

- Motivations for high-order cell-centered schemes;
- Selected formulation  $\rightarrow$  GLM-MHD equations
- Finite Difference framework:
  - Numerical Formulation
  - Third & Fifth order reconstruction techniques
- Numerical Results
- Conclusion & Future Developments

# **Motivations**

- Why High order ?
  - reduce intrinsical numerical dissipation
  - Achieving the same accuracy with fewer number of points
  - more practical for large scale simulations:
    - Complex flow / multiple waves interactions
    - ✓ Long time evolution
    - ✓ Steady state applications
- Why Cell centered ?
  - Conceptually easier
  - facilitate extension to AMR
  - adaptation to more complex physics

# **Motivations:**

• TVD schemes may intoduce excessive numerical dissipation:



- Low accuracy (2nd), smearing, clipping, squaring
- $\rightarrow$  limit the largest achievable Reynold numbers

# **High Order: Finite Volume vs Finite Difference**

$$\frac{FV:}{dt} = \frac{d \langle \mathbf{U} \rangle_{ij}}{dt} =$$

$$\frac{d\left\langle \mathbf{U}\right\rangle _{ij}}{dt}=-\frac{1}{\Delta\mathcal{V}_{ij}}\oint_{\partial_{ij}}\mathbf{F}\cdot d\mathbf{S}$$

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- Evolve average values  $\bigcirc$
- multi-D interpolation/ multiple Riemann problem solutions 0
- Complex to code/CPU-Expensive 0
- General meshes



# High Order: Finite Volume vs Finite Difference



# **Cell-Centered GLM-MHD Equations**

 In [D2] the ∇•B=0 constraint is enforced by introducing a new scalar field function or Generalized Lagrange Multiplier (GLM):

$$\begin{cases} \nabla \cdot \mathbf{B} &= 0, \\ \frac{\partial \mathbf{B}}{\partial t} &= \nabla \times (\mathbf{v} \times \mathbf{B}), \end{cases} \implies \begin{cases} \mathcal{D}(\psi) + \nabla \cdot \mathbf{B} &= 0, \\ \frac{\partial \mathbf{B}}{\partial t} + \nabla \psi &= \nabla \times (\mathbf{v} \times \mathbf{B}) \end{cases}$$

 $\Delta \psi = 0$ 

- D(ψ) is a differential operator:
  - $\mathcal{D}(\psi) = 0$ : Elliptic Correction  $\rightarrow$
  - $\mathcal{D}(\psi) = \psi/c_p^2$ : Parabolic Correction  $\rightarrow \partial_t B + \nabla \cdot (vB Bv) = c_p^2 \nabla (\nabla \cdot B)$ (errors decay in time)
  - $\mathcal{D}(\psi) = \partial_t \psi / c_h^2$ : Hyperbolic correction  $\rightarrow \partial_t \psi + c_h^2 \nabla \cdot B = 0$ (errors propagate at the max admissible speed)

# **Cell-Centered GLM-MHD Equations**

- Mixed hyperbolic/parabolic correction:
  - Offers propagation <u>and</u> dissipation of divergence errors;
  - Avoid accumulation at stagnation points;
  - preserve full conservation
  - Explicit scheme → no need for iterative solvers
- The system has 9 real eigenvalues

$$\begin{split} \frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) &= 0, \\ \frac{\partial (\rho \mathbf{v})}{\partial t} + \nabla \cdot \left[ \rho \mathbf{v} \mathbf{v}^T - \mathbf{B} \mathbf{B}^T + \mathbf{I} \left( p + \frac{\mathbf{B}^2}{2} \right) \right] &= 0, \\ \frac{\partial \mathbf{B}}{\partial t} + \nabla \cdot \left( \mathbf{v} \mathbf{B}^T - \mathbf{B} \mathbf{v}^T \right) + \nabla \psi &= 0, \\ \frac{\partial E}{\partial t} + \nabla \cdot \left[ \left( E + p + \frac{\mathbf{B}^2}{2} \right) \mathbf{v} - (\mathbf{v} \cdot \mathbf{B}) \mathbf{B} \right] &= 0, \\ \frac{\partial \psi}{\partial t} + c_h^2 \nabla \cdot \mathbf{B} &= -\frac{c_h^2}{c_p^2} \psi, \end{split}$$

 $c_{f,s} = \sqrt{\frac{1}{2\rho} \left( \Gamma p + |\mathbf{B}|^2 \pm \sqrt{\left(\Gamma p + |\mathbf{B}|^2\right)^2 - 4\Gamma p B_x^2} \right)}, \quad c_a = \frac{|B_x|}{\sqrt{\rho}}$ 

 $\lambda^{1,9} = \mp c_h \,, \quad \lambda^{2,8} = v_x \mp c_f \,, \quad \lambda^{3,7} = v_x \mp c_a \,, \quad \lambda^{4,6} = v_x \mp c_s \,, \quad \lambda^5 = v_x \mp c_s \,,$ 

c<sub>h</sub>: is chosen to be the maximum compatible speed:

$$c_h = \frac{C_a}{\Delta t^n} \min(\Delta x, \Delta y, \Delta z)$$

See MT09 for an unsplit 2nd order implementation

• Method of lines, RK time stepping:

$$\frac{d\mathbf{U}}{dt} = \mathcal{L}\left(\mathbf{U}\right) \approx -\frac{\partial \mathbf{F}_x}{\partial x} - \frac{\partial \mathbf{F}_y}{\partial y} - \frac{\partial \mathbf{F}_z}{\partial z}$$

- Method of lines, RK time stepping:
- Identify point values of F<sub>i</sub> as cell averages of F(x)
   H(x) is the primitive function:

$$\frac{d\mathbf{U}}{dt} = \mathcal{L}\left(\mathbf{U}\right) \approx -\frac{\partial \mathbf{F}_x}{\partial x} - \frac{\partial \mathbf{F}_y}{\partial y} - \frac{\partial \mathbf{F}_z}{\partial z}$$

$$\mathbf{F}_{i} = \frac{1}{\Delta x} \int_{x_{i-\frac{1}{2}}}^{x_{i+\frac{1}{2}}} \hat{\mathbf{F}}(\xi) d\xi = \frac{1}{\Delta x} \Big[ \mathbf{H}(x_{i+\frac{1}{2}}) - \mathbf{H}(x_{i-\frac{1}{2}}) \Big]$$

$$\mathbf{H}(x) = \int_{-\infty}^{x} \hat{\mathbf{F}}(\xi) d\xi$$

- Method of lines, RK time stepping:
- Identify point values of F<sub>i</sub> as cell averages of F(x)
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- Method of lines, RK time stepping:
- Identify point values of F<sub>i</sub> as cell averages of F(x)
   H(x) is the primitive function:
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$$\frac{d\mathbf{U}}{dt} = \mathcal{L}\left(\mathbf{U}\right) \approx -\frac{\partial \mathbf{F}_{x}}{\partial x} - \frac{\partial \mathbf{F}_{y}}{\partial y} - \frac{\partial \mathbf{F}_{z}}{\partial z}$$

$$\mathbf{F}_{i} = \frac{1}{\Delta x} \int_{x_{i-\frac{1}{2}}}^{x_{i+\frac{1}{2}}} \hat{\mathbf{F}}(\xi) d\xi = \frac{1}{\Delta x} \Big[ \mathbf{H}(x_{i+\frac{1}{2}}) - \mathbf{H}(x_{i-\frac{1}{2}}) \Big]$$

$$\mathbf{H}(x) = \int_{-\infty}^{x} \hat{\mathbf{F}}(\xi) d\xi$$

$$\frac{\partial \mathbf{F}}{\partial x} = \frac{1}{\Delta x} \left( \hat{\mathbf{F}}_{i+\frac{1}{2}} - \hat{\mathbf{F}}_{i-\frac{1}{2}} \right)$$

• <u>Problem</u>: find high-order interface values  $\hat{\mathbf{F}}_{i+\frac{1}{2}}$  knowing undivided differences of primitive function  $\Delta H \rightarrow Same$  as F.V. reconstructions

$$\hat{\mathbf{F}}_{i+\frac{1}{2}} = \mathcal{R}(\mathbf{F}_s)$$
,  $s = i - S, \dots, i + S + 1$ 

# **Finite difference schemes**

- Reconstruction step better carried using characteristic variables to ensure robustness and oscillation-free results
- Split the flux into negative and positive contributions:

$$\begin{cases} V_{[i+\frac{1}{2}],s}^{\kappa,+} = \mathbf{L}_{i+\frac{1}{2}}^{\kappa} \cdot (\mathbf{F}_s + \alpha^{\kappa} \mathbf{U}_s) \\ V_{[i+\frac{1}{2}],s}^{\kappa,-} = \mathbf{L}_{i+\frac{1}{2}}^{\kappa} \cdot (\mathbf{F}_{s'} - \alpha^{\kappa} \mathbf{U}_{s'}) \end{cases}$$

• Reconstruct each characteristic field

$$\hat{V}_{i+\frac{1}{2}}^{\kappa,\pm} \equiv \mathcal{R}\left(V_{[i+\frac{1}{2}],s}^{\kappa,\pm}\right)$$

- On 1-D stencils, Bx and  $\psi$  decouple from the remaining equations and can be solved preliminary;
- Use the 7x7 standard MHD wave decomposition;
- $\rightarrow$  FD formulation available in future releases of the PLUTO code [M07].

# **3<sup>rd</sup> and 5<sup>th</sup>-order Accurate Schemes**

- Third-order: based on a 3 point local stencil:
  - <u>WENO+3</u>: 3rd order WENO with new weights [YC] providing faster convergence and improved accuracy near critical points,
  - <u>LimO3</u>: New third-order limited polynomial reconstruction by Cada Torrilhon [CT] based on nonlinear functions
- Fifth-order: based on a 5 point local stencil:
  - <u>WENO-Z</u>: 5th order WENO with improved weights [BCCD] providing less dissipation and higher resolution than the classical 5th order method;

 <u>MP5</u>: Monotonicity Preserving (MP) fifth-order scheme of Suresh-Huynh [SH]: interface value must lie in a certain interval to preserve monotonicity near discontinuities and accuracy in smooth regions;

[YC]: Yamaleev & Carpenter, "Third-order energy stable WENO scheme", JCP (2009), 228, 3025
[CT]: Cada & Torrilhon, "Compact third-order limiter functions for finite volume methods", JCP (2009), 228, 4118
[BCCD]: Borges, Carmona, Costa & Don, "An improved WENO scheme for hyperbolic conservation laws", JCP (2008), 227, 3191
[SH]: Suresh & Huynh, "Accurate Monotonicity Preserving Schemes with Runge-Kutta Time Stepping", JCP (1997),136, 83

# **Circularly Polarized Alfven Waves**

- CP Alfven waves propagate oscillations of the transverse components of velocity vector and magnetic induction;
- CP waves are exact nonlinear solutions of the MHD equations;
- Useful benchmark in 1, 2 and 3D using rotated configurations



# **Circularly Polarized Alfven Waves**

#### 3D Propagation [GS08]

- $k_y / k_x = k_z / k_x = 2$
- ability to retain planar sym
- Order of accuracy





[GS08]: Gardiner & Stone, "An unsplit Godunov method for ideal MHD via constrained transport in 3D", JCP (2008), 227, 4123

# **Dissipation & Long Term Decay in 2D**

• Long term propagation (100 wave periods) in a 2D domain



small inclination angle, tan  $\alpha$  = 6 [B04]

 $Log(max(v, /\epsilon))$  $Log(max(B_{*}/\epsilon))$ 5<sup>th</sup> order dissipation mechanism 0 <sup>3rd</sup> order is solely numerical in nature  $\rightarrow$  direct measure of numerical 2nd order 0.10 resistivity [RJF95] WENO-Z MP5 WENO-3 LIMO3 TVD 0.01 5 10 15 0 5 10 15 0

[B04]: Balsara, "Second-order-accurate schemes for MHD with divergence-free reconstruction", ApJ (2004), 151,149 [RJF95]: Ryu, Jones & Frank, "Numerical MHD in Astrophysics: algorithm and tests for multi-D flows", ApJ (1995), 452:785

# **Rotated Shock Tubes**

Riemann problem involving propagation of discontinuities, [GS08]; 0 2.0 B<sub>2</sub> B<sub>3</sub> в, 0.580 р 0.8 1.6 1.8 0.575 0.7 WENO+3 1.6 0.570 1.4 0.565 1.4 0.6 1.2 0.560 1.2 0.5 0.555 1.0 1.0 0.4 0.5 -0.50.0 0.5 -0.5 0.0 0.5 -0.5 0.0 0.5 -0.5 0.0 2.0 Β₃ B<sub>2</sub> Β, 0.580 р 0.8 1.6 1.8 0.575 0.7 1.6 0.570 1.4 MP5 п 1.4 0.565 0.6 1.2 0.560 1.2 0.5 0.555 1.0 1.0 0.4 -0.50.0 0.5 -0.50.0 0.5 -0.50.0 0.5 -0.50.0 0.5

[GS08]: Gardiner & Stone, "An unsplit Godunov method for ideal MHD via constrained transport in 3D", JCP (2008), 227, 4123

# **Field Loop Advection**

 Advection of a weakly magnetized field loop traversing the computational domain diagonally [GS05, LD09];



- For  $\beta >> 1 \rightarrow$  equivalent to advection of a passive scalar;
- Check the correct discretization of multi-D term in the numerical method;

[GS05]: Gardiner & Stone, "An unsplit Godunov method for ideal MHD via constrained transport", JCP (2005), 205,509 [LD09]: Lee, Deane, "An unsplit staggered mesh scheme for multidimensional MHD", JCP (2009), 228, 952

# **Field Loop Advection**

- Results at t=2 (two loop periods) for 128x64 grid points;
- Third-order schemes show more dissipation;
- All reconstruction preserve the circular shape of the loop;



# **3D Field Loop Advection**

• 3D oblique propagation, res = 128x128x256 grid points



- Single magnetized planar velocity shear layer [J97];
- 2.5 Dimensions;
- $\Delta M_s = 1$ ,  $\Delta M_A = 20$ ,  $\phi = \pi/3$ ;
- Scheme & Resolution study:
  - 64x128
  - 128x256
  - 256x512



[J97]: Jones et al, "MHD KH Instability. II. The roles of a weak and oblique fields in planar flows", ApJ (1997), 482:230



- Field amplification proceed faster for smaller numerical resistivity
- For t > 8 tearing mode instabilities lead to reconnection event → prevent field amplification





Growth rate computed as  $\Delta v^{y} = (v_{y,max}-v_{y,min})/2$ , related to poloidal field amplification

#### **CPU cost**

	WENO+3	LimO3	WENO-Z	MP5	PPM-CT
KH (256x128)	3.09	2.89	3.83	3.44	-
CP3D (128x64 <sup>2</sup> )	2.26	2.04	2.70	2.30	-
OT3D (48 <sup>3</sup> )	3.02	2.92	4.08	3.58	1.49

- WENO-Z most expensive
- Small additional cost (~10-20 %) when moving from 3<sup>rd</sup> → 5<sup>th</sup> order
   → Better off going to higher order !
- FD schemes are ~2.4-3 slower than second-order TVD/PPM schemes

# **Conclusions & Perspectives**

- FD, Cell-centered schemes offer simplicity and ease of implementation;
- Results show high level of accuracy for both smooth and discontinuous flow features
- Preferred Scheme: MP5
- More accurate and less dissipative than traditional 2nd order Godunov schemes;
- Cost-effective, easy to incorporate additional physics (e.g. viscosity)
- More convenient in terms of accuracy vs. CPU time, specially for 3D problems;
  - $\rightarrow$  Comparison with F.V. schemes
  - $\rightarrow$  Extension to higher accuracy in time
  - $\rightarrow$  Applications to turbulence (Molecular cloud fragmentation, MRI, etc...)
- Available in next releases of the PLUTO code.

#### ~ THANK YOU ~









# **Divergence of B**

- In time for KH ?
- For ST ?
- As integral average ?

#### **Third-order accurate schemes**

- Based on a 3 point local stencil:
  - <u>WENO+3</u>: 3rd order WENO with new weights [YC] providing faster convergence and improved accuracy near critical points,

$$\mathcal{R}\left(f_{s}\right) = \omega_{0} \frac{f_{i} + f_{i+1}}{2} + \omega_{1} \frac{-f_{i-1} + 3f_{i}}{2}$$

<u>LimO3</u>: New third-order limited polynomial reconstruction by Cada Torrilhon [CT]

$$\mathcal{R}(f_s) = f_i + \frac{\Delta_{i+\frac{1}{2}}}{2} \left[ P_3(\theta) + \alpha \left( \hat{\phi}(\theta) - P_3(\theta) \right) \right] \quad \theta = \Delta_{i-\frac{1}{2}} / \Delta_{i+\frac{1}{2}}$$

based on the accuracy and shape-preserving third-order limiter

$$\hat{\phi}(\theta) = \begin{cases} \max\left[0, \min\left(P_3(\theta), 2\theta, 1.6\right)\right] & \text{if } \theta \ge 0\\ \max\left[0, \min\left(P_3(\theta), -\frac{\theta}{2}\right)\right] & \text{if } \theta < 0 \end{cases}$$

[YC]: Yamaleev & Carpenter, "Third-order energy stable WENO scheme", JCP (2009), 228, 3025 [CT]: Cada & Torrilhon, "Compact third-order limiter functions for finite volume methods", JCP (2009), 228, 4118

#### **Fifth-order accurate schemes**

Based on a 5 point local stencil:

<u>WENO-Z</u>: 5th order WENO [JS] with improved weights [BCCD] providing faster convergence and improved accuracy near critical points,

$$\mathcal{R}(f_s) = \omega_0 P_{i-1}^{(3)} + \omega_1 P_i^{(3)} + \omega_2 P_{i+1}^{(3)}$$

<u>MP5</u>: Monotonicity Preserving (MP) fifth-order scheme of Suresh-Huynh [SH]:

$$f_{i+\frac{1}{2}} = \frac{2f_{i-2} - 13f_{i-1} + 47f_i + 27f_{i+1} - 3f_{i+2}}{60}$$

interface value must lie in a certain interval to preserve monotonicity near discontinuities and accuracy in smooth regions:

$$\mathcal{R}\left(f_{s}\right) = \begin{cases} f_{i+\frac{1}{2}} & \text{if } (f_{i+\frac{1}{2}} - f_{i})(f_{i+\frac{1}{2}} - f^{\text{MP}}) < 0, \\ \text{Median}\left(f^{\min}, f_{i+\frac{1}{2}}, f^{\max}\right) & \text{otherwise} \end{cases}$$

[JS]: Jiang, Wu, "Efficient Implementation of WENO schemes", JCP (1996), 126, 202 [BCCD]: Borges, Carmona, Costa & Don, "An improved WENO scheme for hyperbolic conservation laws", JCP (2008), 227, 3191 [SH]: Suresh & Huynh, "Accurate Monotonicity Preserving Schemes with Runge-Kutta Time Stepping", JCP (1997),136, 83