

DE LA RECHERCHE À L'INDUSTRIE



# Towards a holistic framework for global assessments of nuclear models

Georg Schnabel

# What is it about?

## **Situation**

Models (computationally expensive)

Experimental data (possibly a lot)

## **Research question**

How can we use statistical methods and methods of machine learning in combination with modern computer infrastructure to improve our knowledge about nuclear models and experimental data?

Parameter estimation, uncertainty quantification, uncertainty propagation

# Publications

G. Schnabel “**Estimating model bias over the complete nuclide chart with sparse Gaussian processes at the example of INCL/ABLA and double-differential neutron spectra**”, submitted to EPJ-N

G. Schnabel “**Fitting and Analysis Technique for Inconsistent Nuclear Data**” Proc. of M&C 2017

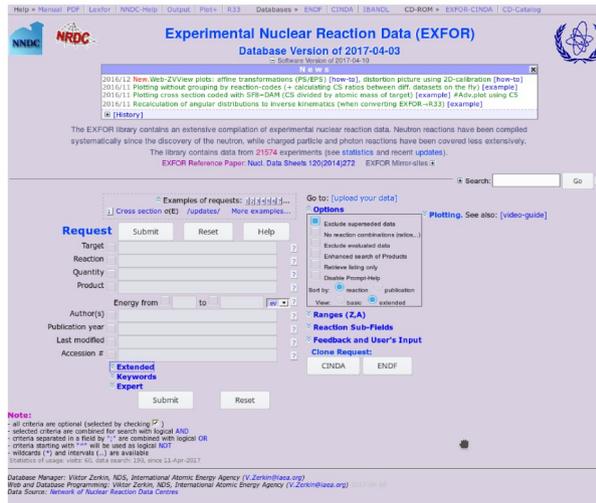
G. Schnabel, and H. Leeb. “**A Modified Generalized Least Squares Method for Large Scale Nuclear Data Evaluation**” NIMA Jan 2017

G. Schnabel “**Adaptive Monte Carlo for Nuclear Data Evaluation**” Proc. of ND 2016

G. Schnabel, and H. Leeb. “**Differential Cross Sections and the Impact of Model Defects in Nuclear Data Evaluation**” Proc. of Wonder 2015.

# "Toy" scenario

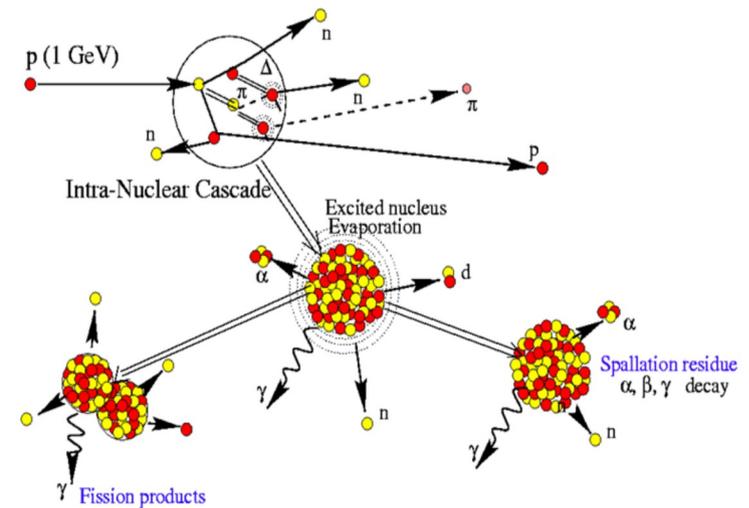
Data: EXFOR database



Database as of: 2017-04-03

Number of ENTRY	21 574	experimental works
Number of SUBENT	150 976	data tables
Number of Datasets	167 857	data tables of reactions
Number of Datapoints	<b>14 739 297</b>	total number of data points

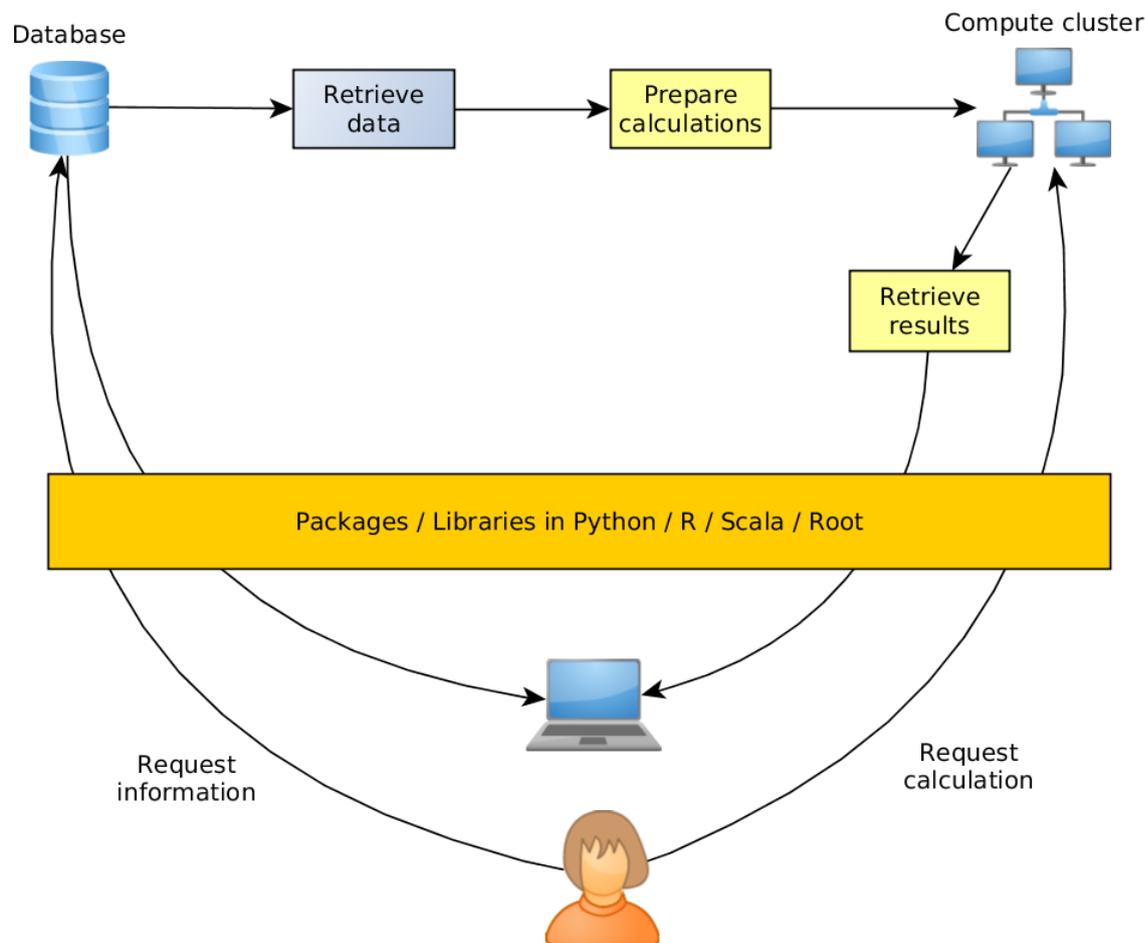
Model: INCL/ABLA



Features:

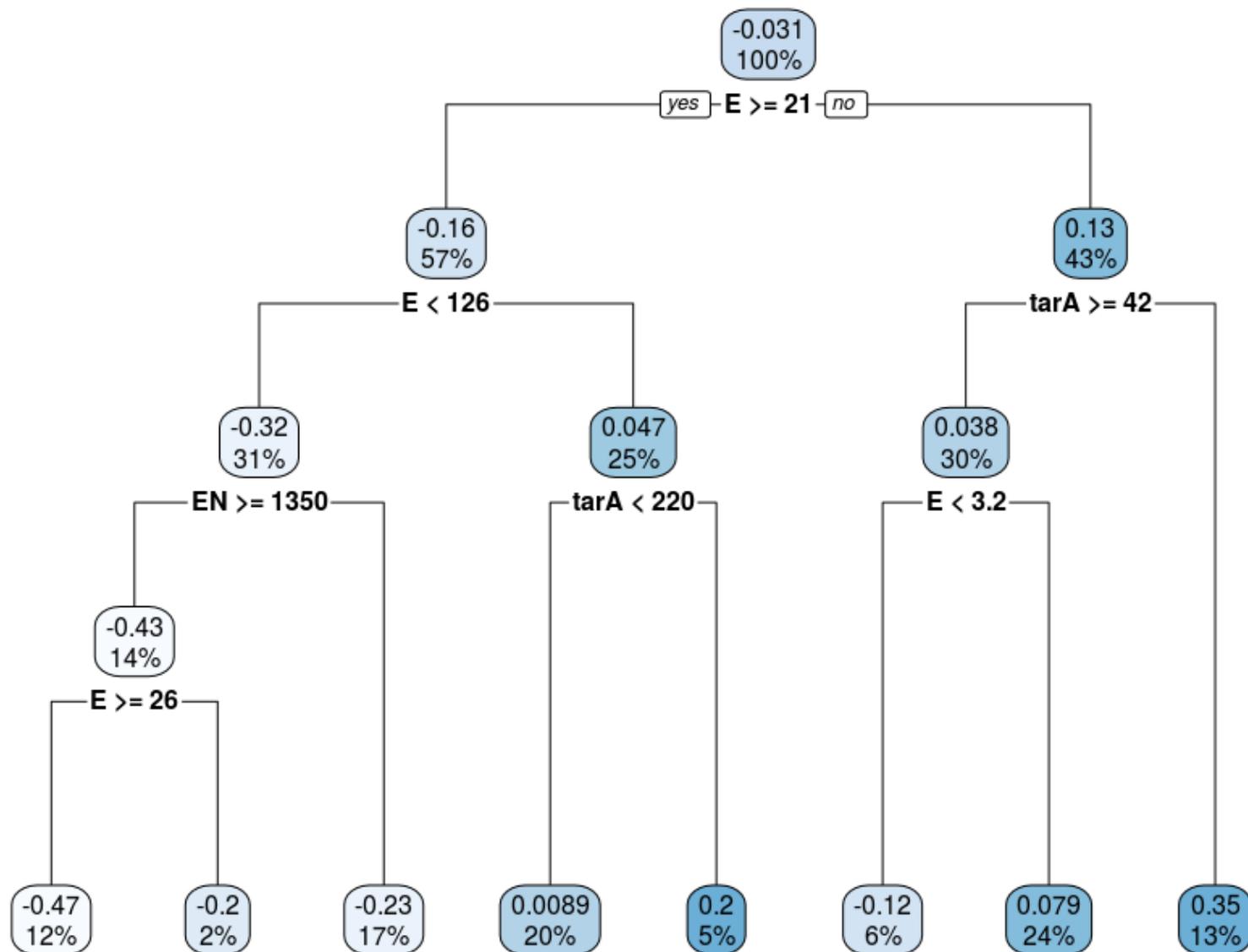
- Stochastic output
- Computational expensive
- Many parameters
- Large output

# Automatization



IDX	REAC	EN	ACCNUM	SUBACCNUM	ANG	E	DATA	PROJ.SYM	TAR.SYM	EJECT.SYM	QUANT	A	Z	MODXS	MODERR	tarA	tarZ	RELDIFF	EXPERR
1:	77048	(13-AL-27(P,X)0-NN-1,,DA/DE)	800	E1762	020 15	1.25	10.020	p	Al27		n	DDX	1 0	6.54215291	0.517202600	27	13	-0.53160590	1.0020
2:	77049	(13-AL-27(P,X)0-NN-1,,DA/DE)	800	E1762	020 15	1.75	5.963	p	Al27		n	DDX	1 0	6.74659519	0.525221723	27	13	0.11614676	0.5963
3:	77050	(13-AL-27(P,X)0-NN-1,,DA/DE)	800	E1762	020 15	2.50	6.791	p	Al27		n	DDX	1 0	6.29682218	0.717589485	27	13	-0.07848051	0.6791
4:	77051	(13-AL-27(P,X)0-NN-1,,DA/DE)	800	E1762	020 15	3.50	5.278	p	Al27		n	DDX	1 0	5.88793762	0.693900103	27	13	0.10359105	0.5278
5:	77052	(13-AL-27(P,X)0-NN-1,,DA/DE)	800	E1762	020 15	4.50	4.833	p	Al27		n	DDX	1 0	5.64260689	0.679290043	27	13	0.14348100	0.4833
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9283:	109738	(40-ZR-0(P,X)0-NN-1,,DA/DE)	1600	01170	008 150	81.00	0.190	p	Zr		n	DDX	1 0	0.13737011	0.030716891	91	40	-0.38312475	0.0190
9284:	109739	(40-ZR-0(P,X)0-NN-1,,DA/DE)	1600	01170	008 150	92.00	0.130	p	Zr		n	DDX	1 0	0.22666068	0.039456560	91	40	0.42645545	0.0130
9285:	109740	(40-ZR-0(P,X)0-NN-1,,DA/DE)	1600	01170	008 150	106.00	0.096	p	Zr		n	DDX	1 0	0.10962135	0.006222730	91	40	0.12425817	0.0096
9286:	109741	(40-ZR-0(P,X)0-NN-1,,DA/DE)	1600	01170	008 150	124.00	0.064	p	Zr		n	DDX	1 0	0.07555356	0.005270431	91	40	0.11553561	0.0064
9287:	109742	(40-ZR-0(P,X)0-NN-1,,DA/DE)	1600	01170	008 150	147.00	0.053	p	Zr		n	DDX	1 0	0.04361501	0.004144504	91	40	-0.09384990	0.0053

# Example of ML approach



# Bayesian statistics

$$P(H | O) = \frac{P(O | H)P(H)}{P(O)}$$

**H** hypothesis  
**O** observation

**P(H)** probability of hypothesis to be true  
**P(O)** probability of observation to occur

**P(O|H)** probability of observation O to occur  
 if hypothesis H is true

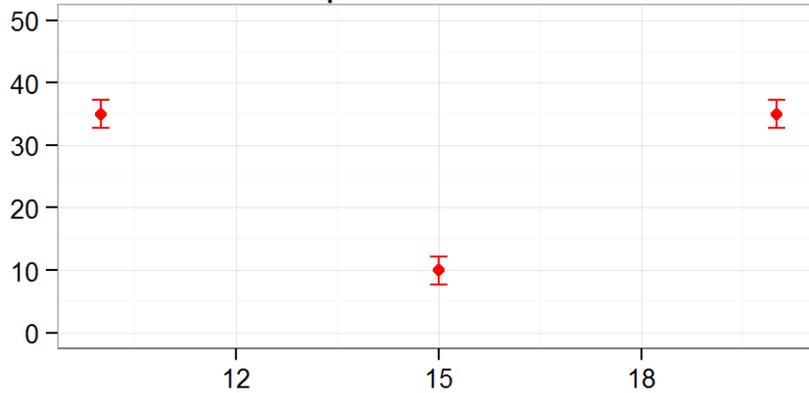
**P(H|O)** probability of hypothesis  
 after we observed O

Consistent with Aristotelian logic  
 Consistent with principles of common sense

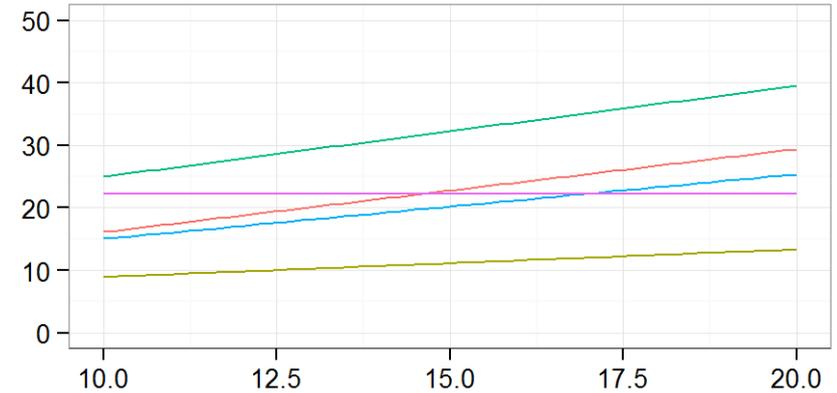


# Inappropriate assumptions

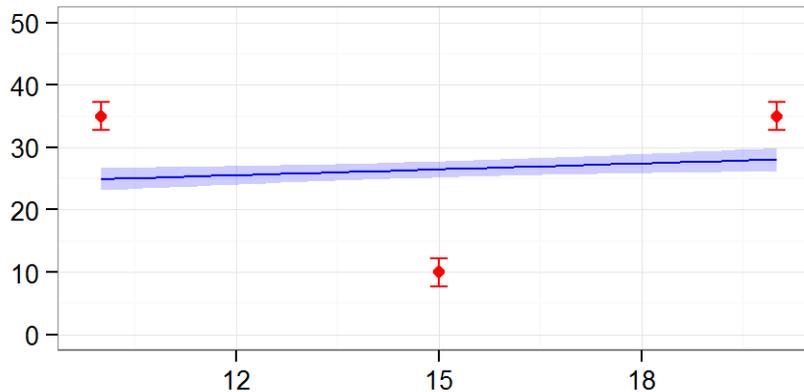
Experimental Data



Model Possibilities



Evaluated Cross Section



**GiGo principle**  
 Garbage in,  
 Garbage out  
*But also*  
 Good stuff in,  
 Good stuff out

# In practice

Negative cross sections in linearized evaluation methods

Uncertainty reductions beyond experimental limits

Model predictions in disagreement with experiment data



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## Reasons

Inappropriate prior for model parameters

Imperfect model / Not completely confident in the model

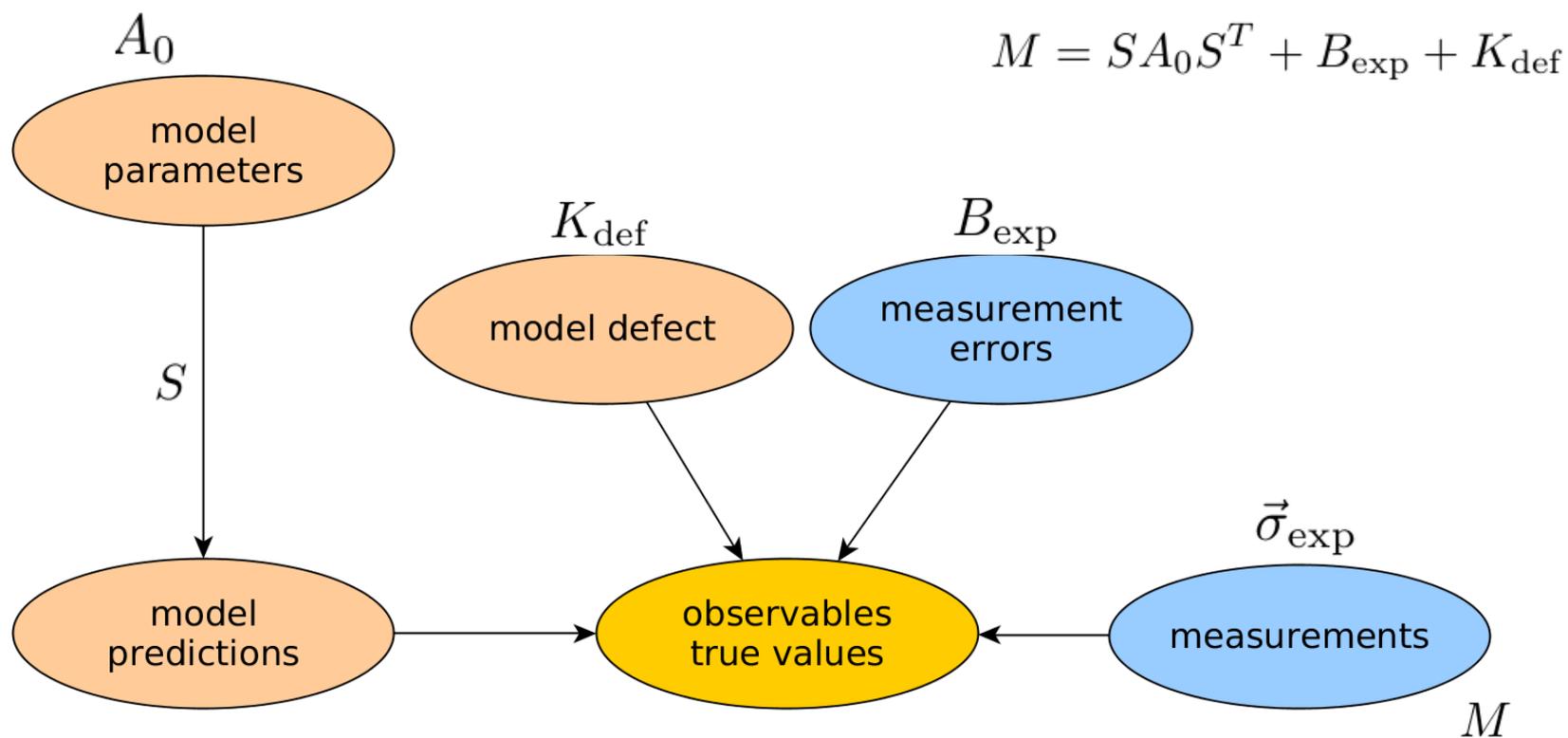
Inaccurate likelihood specification for the data

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## Solutions

Prior rescaling, likelihood broadening, model defects, removing suspicious experimental data sets

# Bayesian network



$$M = SA_0S^T + B_{\text{exp}} + K_{\text{def}}$$

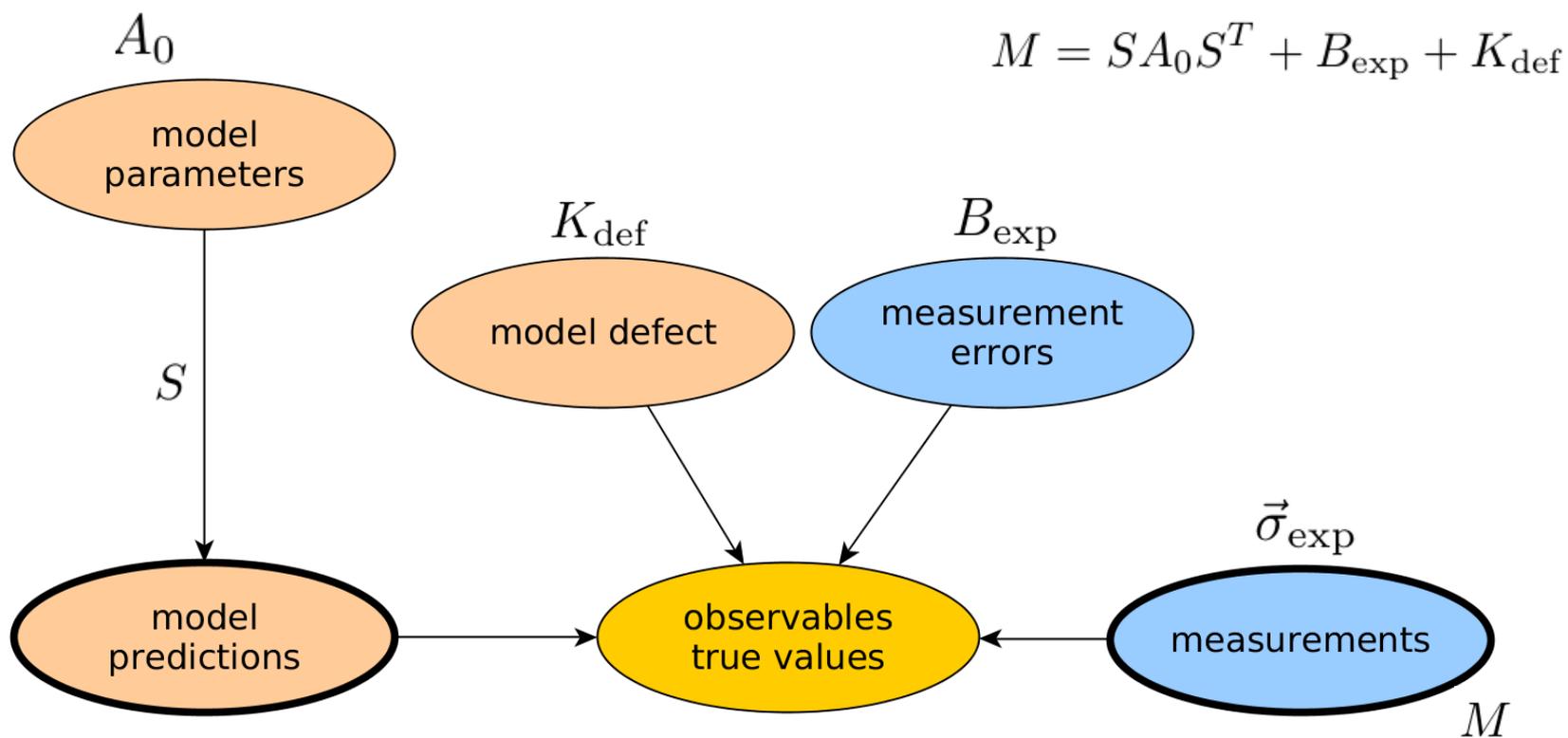
$$\vec{p}_1 = \vec{p}_0 + A_0S^T M^{-1}(\vec{\sigma}_{\text{exp}} - S\vec{p}_0)$$

$$\vec{\epsilon}_{\text{exp},1} = B_{\text{exp}}M^{-1}(\vec{\sigma}_{\text{exp}} - S\vec{p}_0)$$

$$A_1 = A_0 - A_0S^T M^{-1}SA_0$$

$$B_{\text{exp},1} = B_{\text{exp}} - B_{\text{exp}}M^{-1}B_{\text{exp}}$$

# Deterministic codes



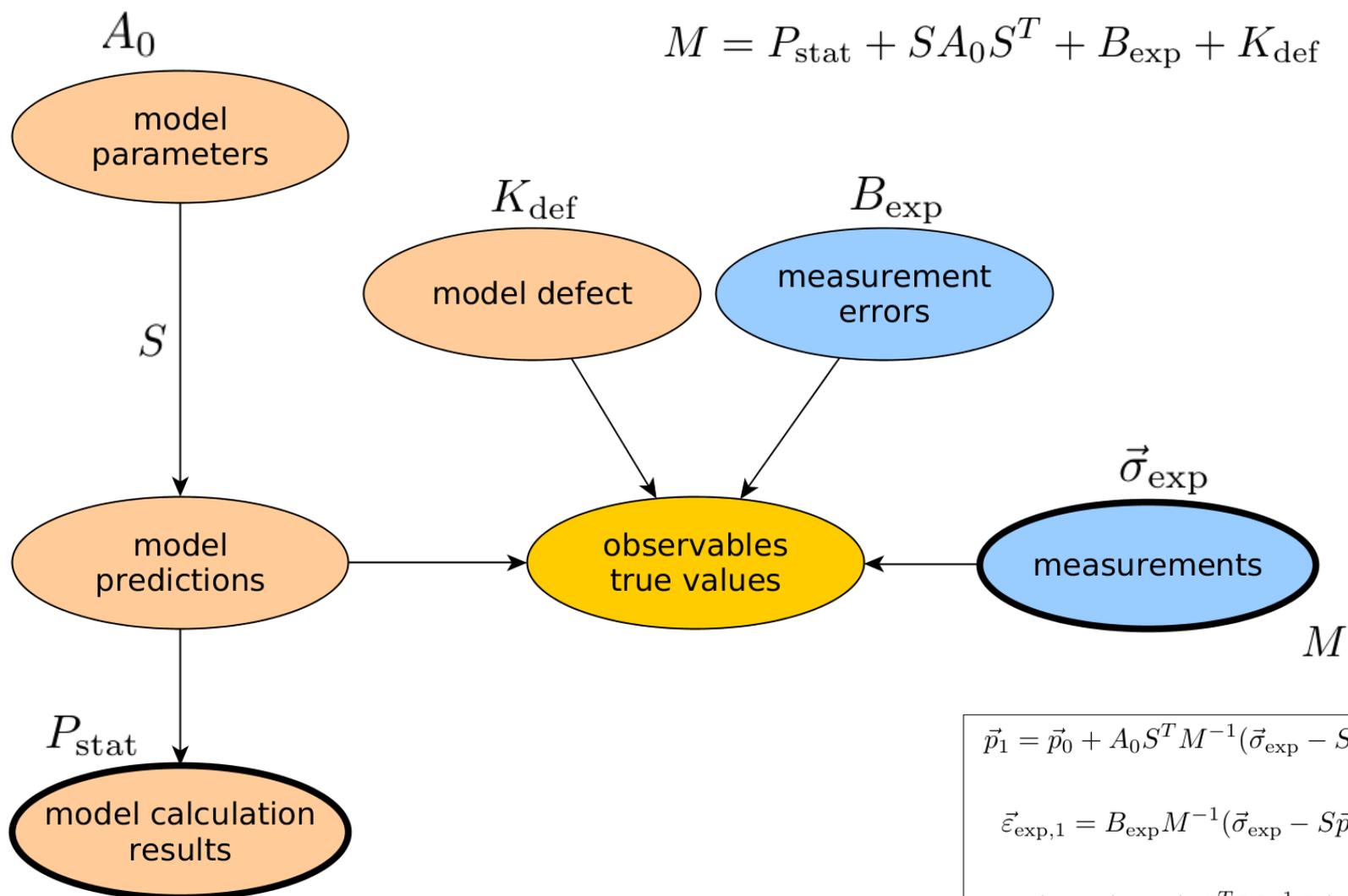
$$\vec{p}_1 = \vec{p}_0 + A_0S^T M^{-1}(\vec{\sigma}_{\text{exp}} - S\vec{p}_0)$$

$$\vec{\epsilon}_{\text{exp},1} = B_{\text{exp}}M^{-1}(\vec{\sigma}_{\text{exp}} - S\vec{p}_0)$$

$$A_1 = A_0 - A_0S^T M^{-1}SA_0$$

$$B_{\text{exp},1} = B_{\text{exp}} - B_{\text{exp}}M^{-1}B_{\text{exp}}$$

# Stochastic codes



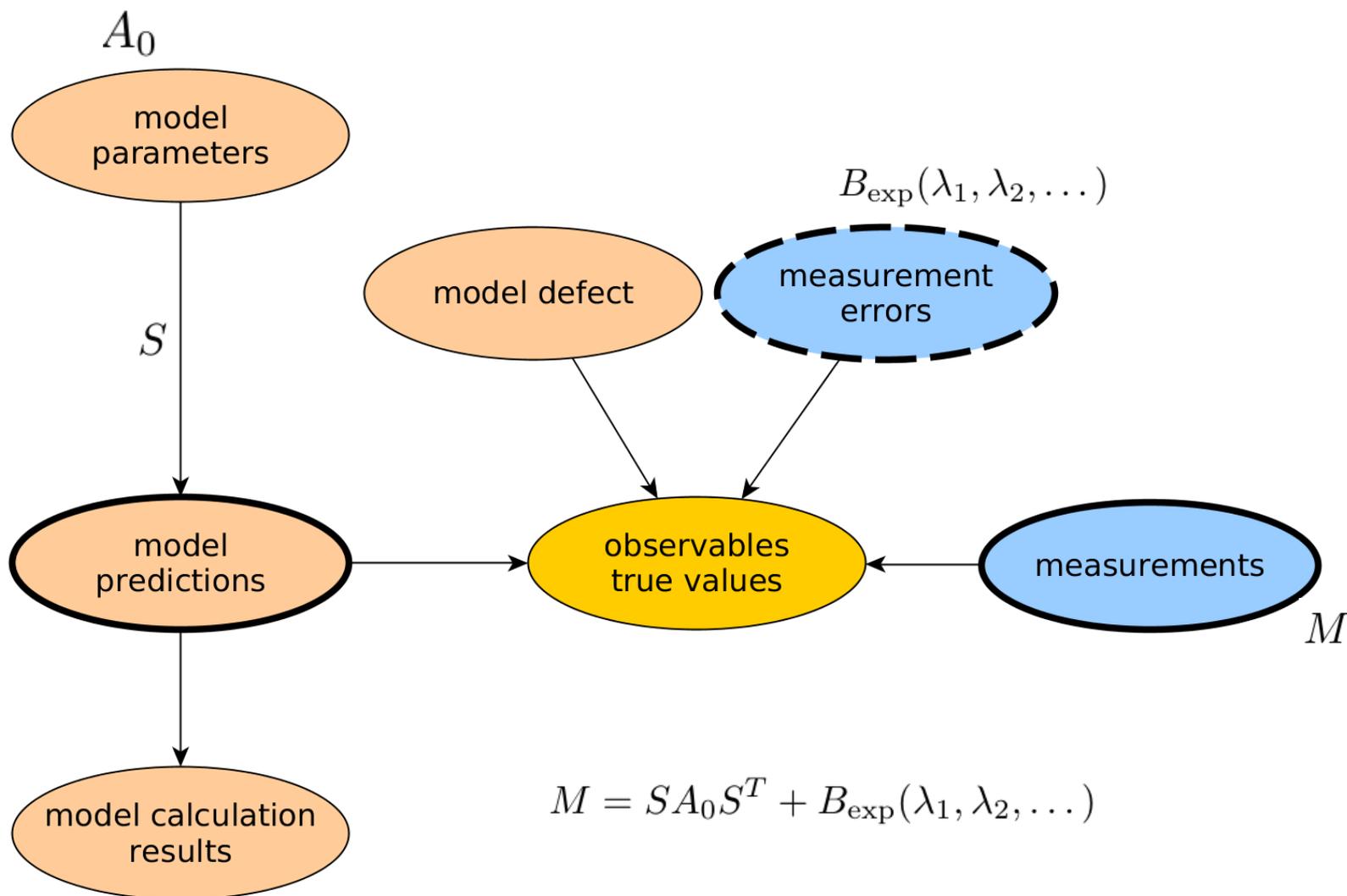
$$\vec{p}_1 = \vec{p}_0 + A_0S^T M^{-1}(\vec{\sigma}_{\text{exp}} - S\vec{p}_0)$$

$$\vec{\epsilon}_{\text{exp},1} = B_{\text{exp}}M^{-1}(\vec{\sigma}_{\text{exp}} - S\vec{p}_0)$$

$$A_1 = A_0 - A_0S^T M^{-1}SA_0$$

$$B_{\text{exp},1} = B_{\text{exp}} - B_{\text{exp}}M^{-1}B_{\text{exp}}$$

# Inconsistent data



# Marginal likelihood

$$\log \rho(\vec{\sigma}_{\text{exp}} | \vec{p}_0, S, M) = -\frac{N}{2} \log(2\pi) - \frac{1}{2} \log |M| - \frac{1}{2} (\vec{\sigma}_{\text{exp}} - S\vec{p}_0)^T M^{-1} (\vec{\sigma}_{\text{exp}} - S\vec{p}_0)$$



Entropy



$\chi^2$  term



$$M = SA_0S^T + B_{\text{exp}}(\lambda_1, \lambda_2, \dots)$$

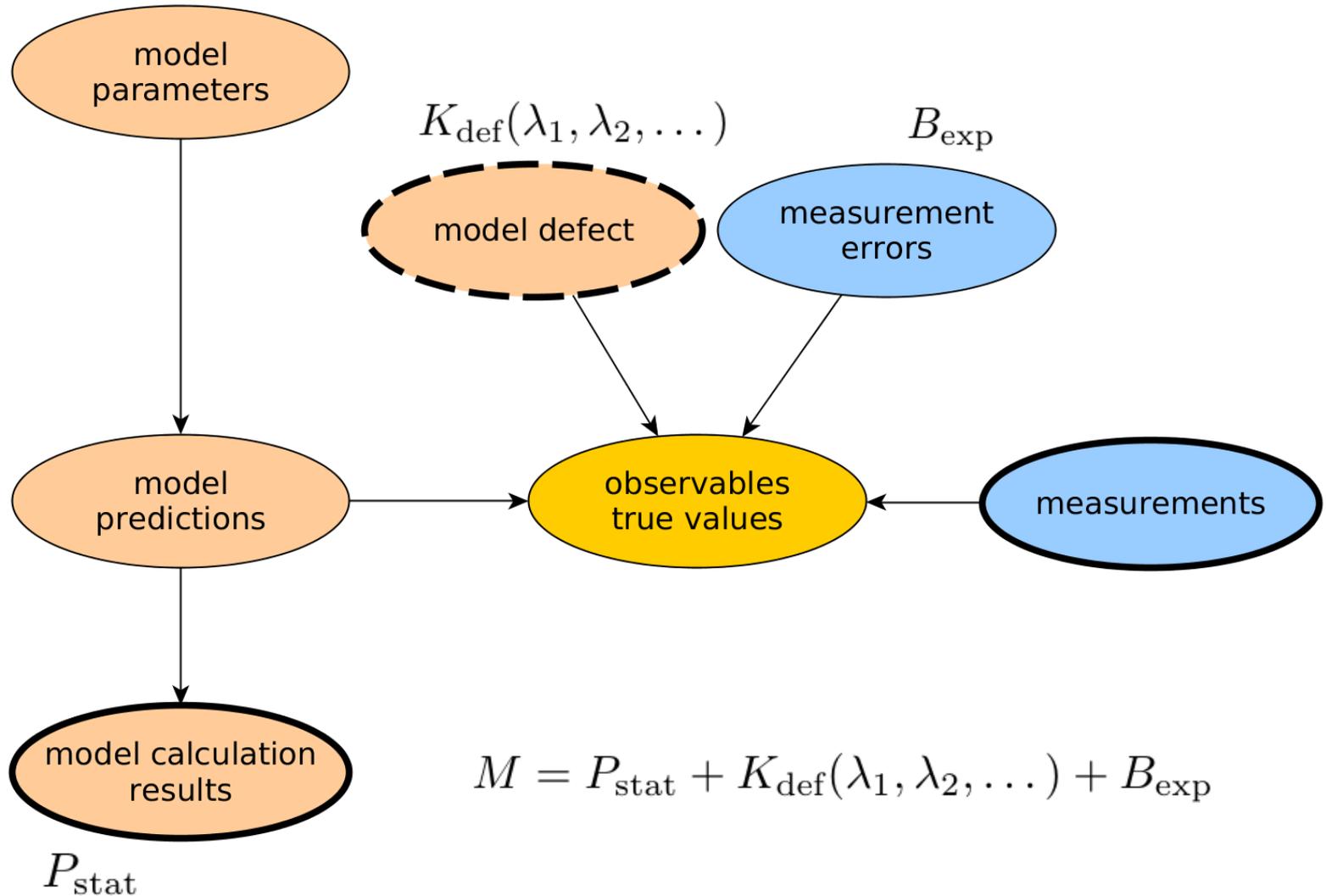
## Questions

Is it computationally feasible?



Can we efficiently maximize this expression?

# Imperfect model



# (In)finite Covariance Matrix

Covariance matrices can represent a variety of things such as normalization uncertainties, linear trends, splines, Fourier series, polynomial expansions, white noise, etc.



$$y(x) = kx + d, \quad k \sim \mathcal{N}(0, \delta_k^2), \quad d \sim \mathcal{N}(0, \delta_d^2)$$

Observations  $(\vec{y}_{\text{exp}}, \vec{x}_{\text{exp}})$

$$\vec{p} = \begin{pmatrix} k \\ d \end{pmatrix} = AS^T (SAS^T + B)^{-1} \vec{y}_{\text{exp}}$$

$$\vec{y}_{\text{pred}} = S_{\text{pred}} \vec{p} = \begin{pmatrix} \vec{x}_{\text{pred}}, \vec{1} \end{pmatrix} \begin{pmatrix} k \\ d \end{pmatrix}$$

$$S_{\text{exp}} = \begin{pmatrix} \vec{x}_{\text{exp}}, \vec{1} \end{pmatrix}$$

$$A = \begin{pmatrix} \delta_k^2 & 0 \\ 0 & \delta_d^2 \end{pmatrix}$$

$$B = \begin{pmatrix} \varepsilon_1^2 & 0 & 0 \\ 0 & \varepsilon_2^2 & 0 \\ 0 & 0 & \ddots \end{pmatrix}$$

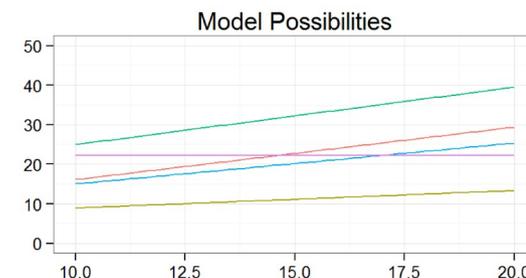
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$$\kappa(x_1, x_2) := \text{Cov}[y(x_1), y(x_2)] = \delta_k^2 x_1 x_2 + \delta_d^2$$

$$K_{\text{pred}, \text{exp}} = \kappa(\vec{x}_{\text{pred}}, \vec{x}_{\text{exp}}) \quad K_{\text{exp}, \text{exp}} = \kappa(\vec{x}_{\text{exp}}, \vec{x}_{\text{exp}})$$

$$\vec{y}_{\text{pred}} = K_{\text{pred}, \text{exp}} K_{\text{exp}, \text{exp}}^{-1} \vec{y}_{\text{exp}}$$


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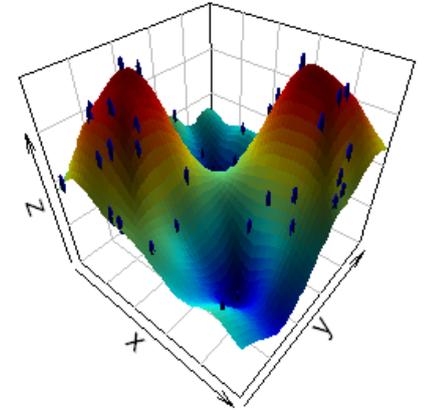


# Gaussian processes

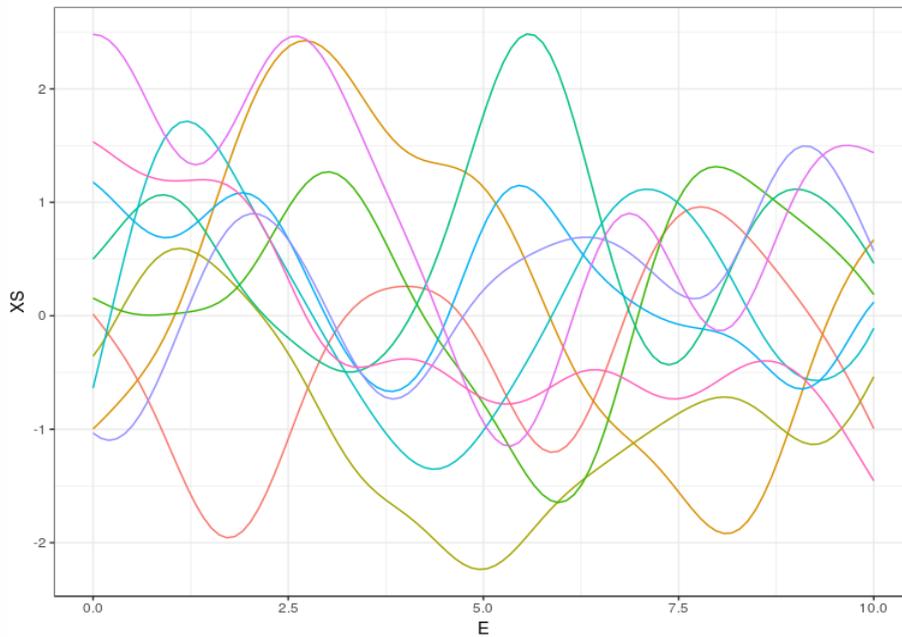
## Powerful concept

Directly parametrize covariance matrix and work implicitly with an infinite number of parameters/basis functions!

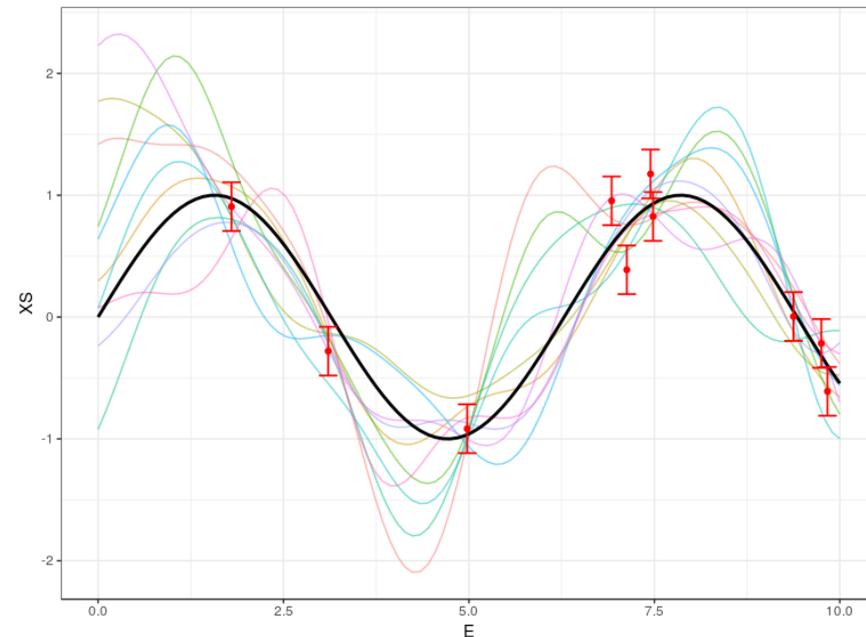
$$\kappa(\mathbf{x}_1, \mathbf{x}_2) = \delta^2 \exp\left(-\frac{(\mathbf{x}_1 - \mathbf{x}_2)^2}{2\lambda^2}\right)$$



Sample from prior ( $\delta=\lambda=1$ )



Sample from posterior

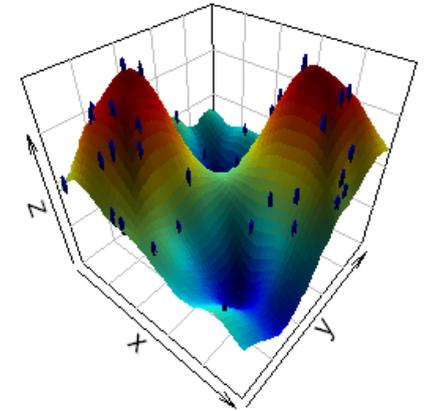


# Gaussian processes

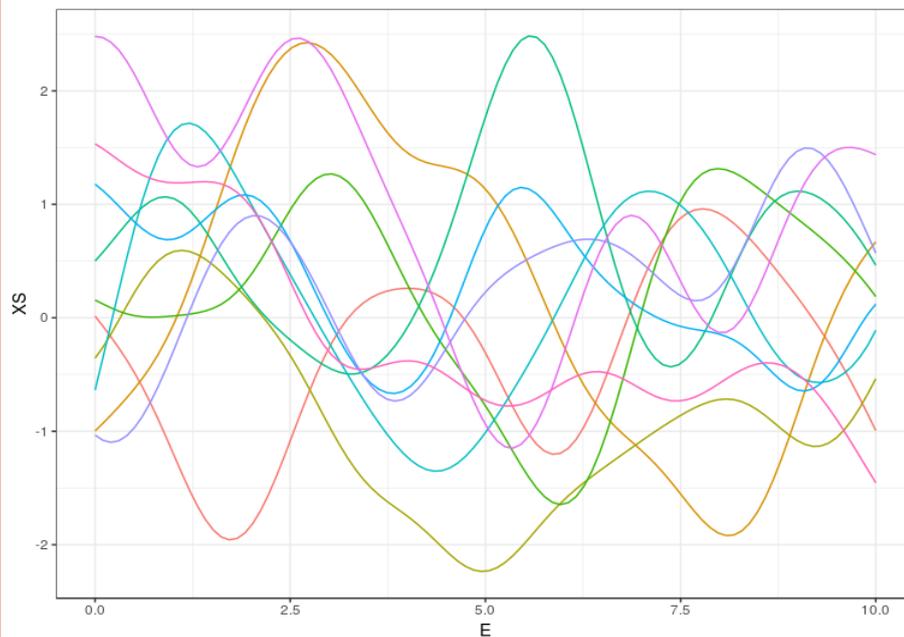
## Powerful concept

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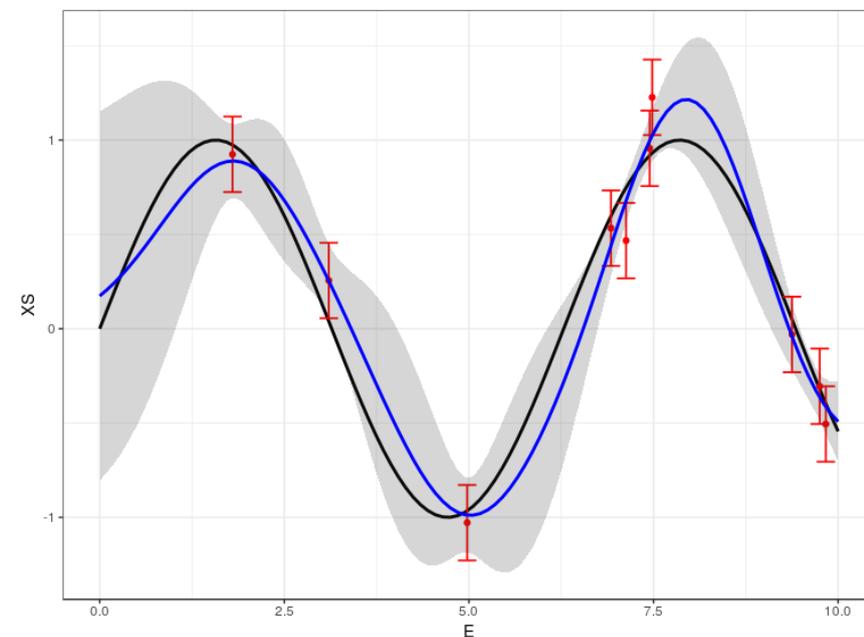
$$\kappa(\mathbf{x}_1, \mathbf{x}_2) = \delta^2 \exp\left(-\frac{(\mathbf{x}_1 - \mathbf{x}_2)^2}{2\lambda^2}\right)$$



Sample from prior ( $\delta=\lambda=1$ )

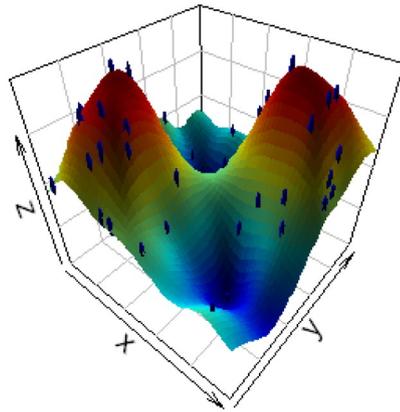


Posterior uncertainty

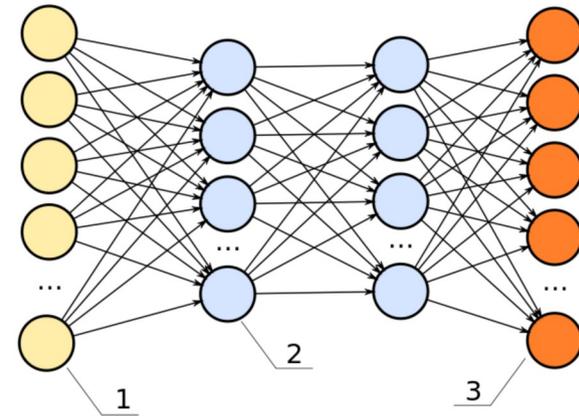


# Comparison to neural networks

GP processes



artificial neural networks



## Both approaches ...

- ... are methods for classification and regression
- ... are universal function approximators

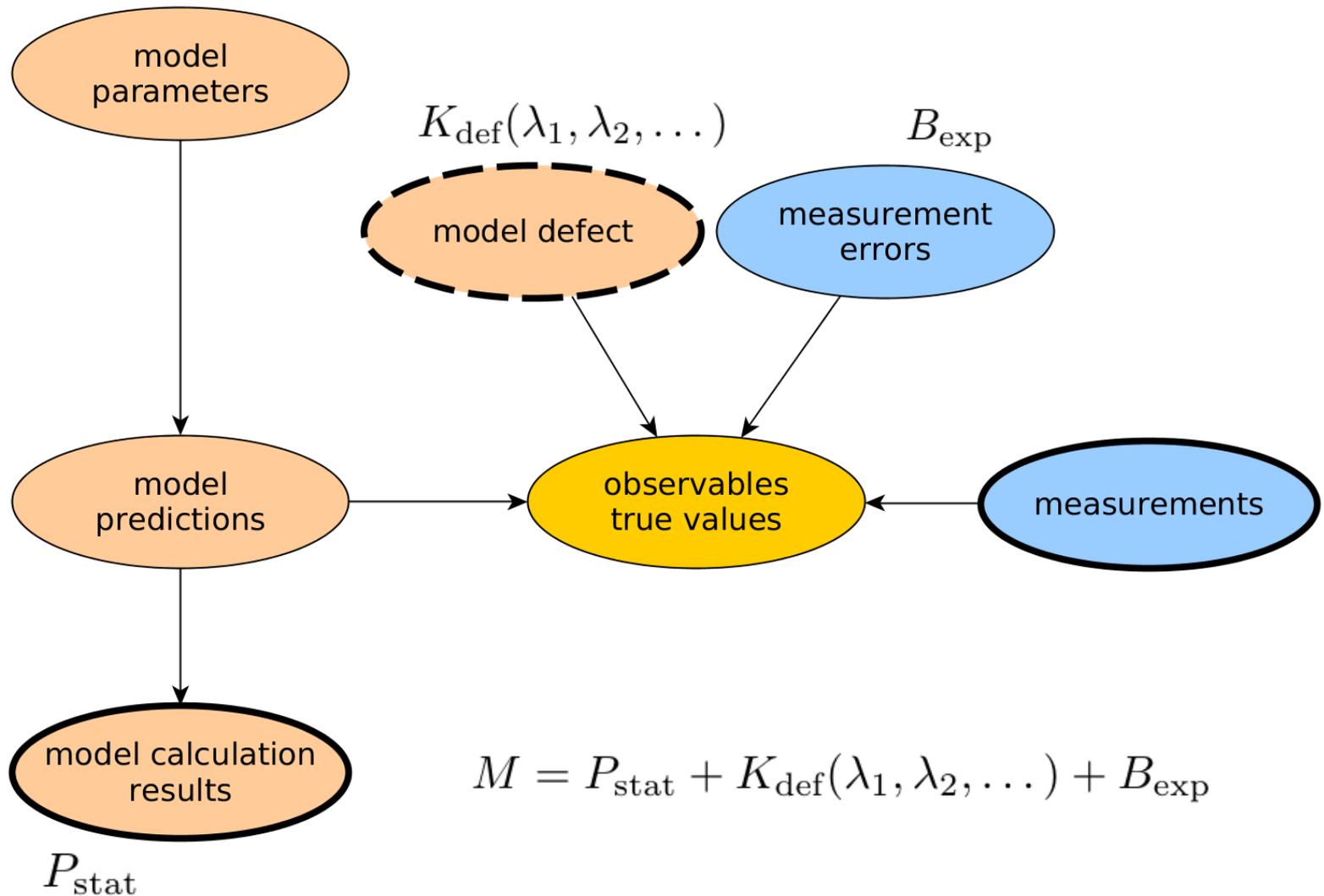
## Neural networks ...

- ... scale better to large data sets
- ... are able to capture non-local features
- ... are difficult to interpret

## GP processes ...

- ... are statistical methods from the ground up (uncertainties)
- ... facilitate the incorporation of prior assumptions
- ... interface well with existing nuclear data evaluation methods

# Model bias estimation



**(p,X)n above 100 MeV**

Isotope	$E_n$	$E_{min}$	$E_{max}$	$\theta_{min}$	$\theta_{max}$	NumPts
C	800	1.2	700	15	150	189
C	1500	1.2	1250	15	150	245
C	3000	1.2	2500	15	150	128
Na23	800	3.5	266	30	150	84
Al27	800	1.2	700	15	150	119
Al27	1000	2.5	280	15	150	223
Al27	1200	2.0	1189	10	160	404
Al27	1500	1.2	1250	15	150	129
Al27	1600	2.5	280	15	150	226
Al27	3000	1.2	2500	15	150	132
Fe	800	1.2	771	10	160	505
Fe	1200	2.0	1171	10	160	417
Fe	1500	1.2	1250	15	150	129
Fe	1600	2.0	1572	10	160	460
Fe	3000	1.2	2500	15	150	133
Cu	1000	2.5	280	15	150	227
Cu	1600	2.5	280	15	150	231
Zr	1000	2.5	280	15	150	229
Zr	1200	2.0	1189	10	160	423
Zr	1600	2.5	280	15	150	229
In	800	1.2	700	15	150	116
In	1500	1.2	1250	15	150	128
In	3000	1.2	2500	15	150	133
W	800	3.1	333	30	150	110
W	1000	2.5	280	15	150	231
W	1200	2.0	1189	10	160	413
W	1600	2.5	280	15	150	231
Pb	318	5.4	356	7	7	53
Pb	800	1.2	771	10	160	624
Pb	1000	2.5	280	15	150	231
Pb	1200	2.0	1189	10	160	563
Pb	1500	1.2	1250	15	150	249
Pb	1600	2.0	1591	10	160	691
Pb	3000	1.2	2500	15	150	131
Pb208	2000	0.4	402	30	150	170
Th232	1200	2.0	1189	10	160	351

Input space:  
A, Z,  $E_n$ ,  $E$ ,  $\theta$

# Covariance brewing

Combination rules for covariance functions

$$\kappa_{1+2}(x_1, x_2) = \kappa_1(x_1, x_2) + \kappa_2(x_1, x_2)$$

$$\kappa_{1 \times 2}(x_1, x_2) = \kappa_1(x_1, x_2) \times \kappa_2(x_1, x_2)$$



Squared exponential covariance functions

$$\kappa_1(x_1, x_2) = \delta_1^2 \exp\left(-\frac{1}{2\lambda_1^2}(x_1 - x_2)^2\right)$$

$$\kappa_2(x_1, x_2) = \delta_2^2 \exp\left(-\frac{1}{2\lambda_2^2}(x_1 - x_2)^2\right)$$

Transition kernel

$$\tau_1(x_1, x_2) = \sigma(x_1)\sigma(x_2)$$

$$\tau_2(x_1, x_2) = (1 - \sigma(x_1))(1 - \sigma(x_2))$$

$$\sigma(x) = \frac{1}{1 + \exp(-k(x - x_0))}$$

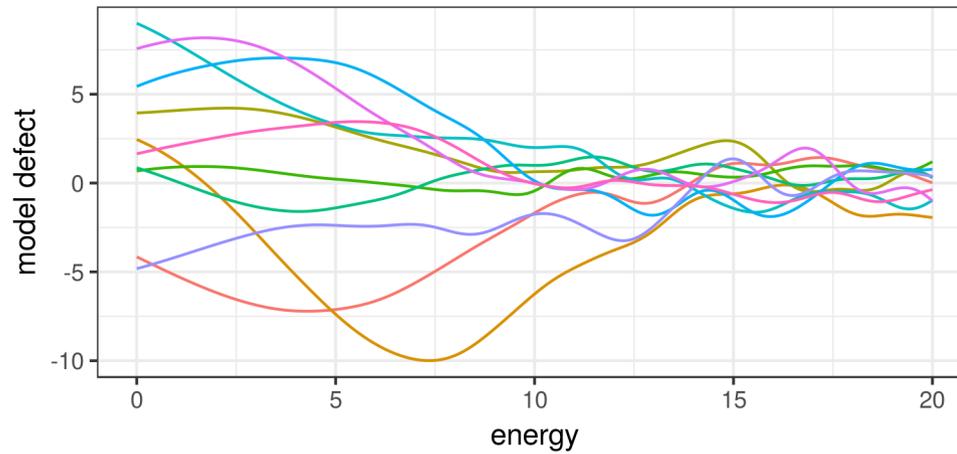


$$\kappa_{\text{comp}}(x_1, x_2) = \tau_1(x_1, x_2) \times \kappa_1(x_1, x_2) + \tau_2(x_1, x_2) \times \kappa_2(x_1, x_2)$$

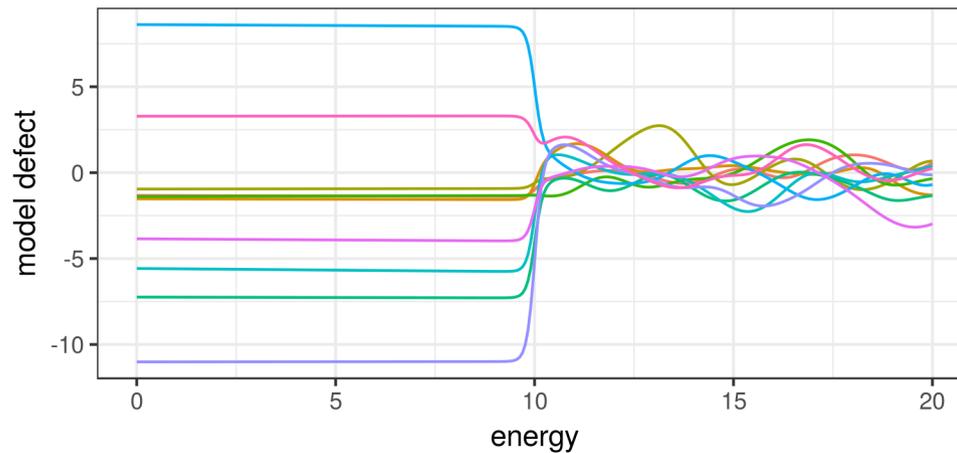
# Prior visualization

$$\kappa_{\text{comp}}(x_1, x_2) = \tau_1(x_1, x_2) \times \kappa_1(x_1, x_2) + \tau_2(x_1, x_2) \times \kappa_2(x_1, x_2)$$

$\delta_1 = 5, \lambda_1 = 5, \delta_2 = 1, \lambda_2 = 1, k = 0.5, x_0 = 10$



$\delta_1 = 5, \lambda_1 = 500, \delta_2 = 1, \lambda_2 = 1, k = 10, x_0 = 10$



# Real case

INCL vs experiment data

**Final goal:** Inclusive DDX data over the complete nuclide chart projectile + target -> ejectile + X (~100 000 data points above 100 MeV, INCL gives predictions for ~40 000)

Inclusive DDX for **p + target -> X + n**

9287 data points, 11 targets, incident energies ranging from 300 to 3000 MeV)

5 dimensional space (A, Z, EN, ANG, E)

$\kappa_1$ :  $\delta_1, \lambda_{11}, \dots, \lambda_{15}$

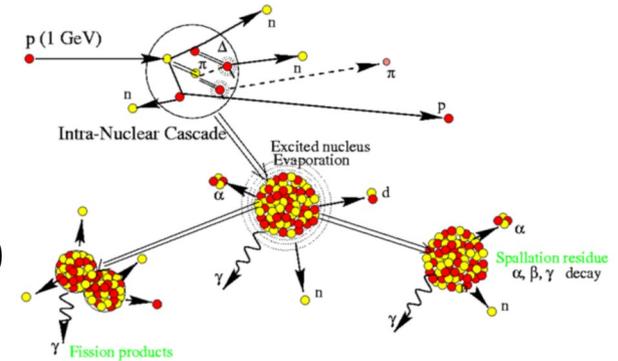
$\kappa_2$ :  $\delta_2, \lambda_{21}, \dots, \lambda_{25}$

T:  $k, x_0, \Phi$

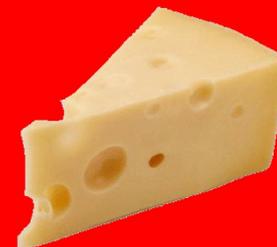
$$M = P_{\text{stat}} + K_{\text{def}}(\lambda_1, \lambda_2, \dots) + B_{\text{exp}}$$

$$\log \rho(\mathcal{D} | \vec{p}_0, \vec{\sigma}_{\text{exp}}, M) = -\frac{N}{2} \log(2\pi) - \frac{1}{2} \log |M| - \frac{1}{2} (\vec{\sigma}_{\text{exp}} - S\vec{p}_0)^T M^{-1} (\vec{\sigma}_{\text{exp}} - S\vec{p}_0)$$

$$\kappa_{\text{comp}}(x_1, x_2) = \tau_1(x_1, x_2) \times \kappa_1(x_1, x_2) + \tau_2(x_1, x_2) \times \kappa_2(x_1, x_2)$$



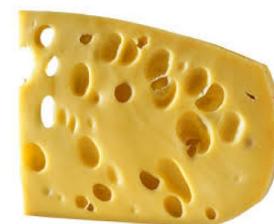
# Introduce sparsity



Assume latent variables (**pseudo-inputs**)

$$\vec{y}_{\text{obs}} = \overbrace{K_{\text{obs,psi}} K_{\text{psi,psi}}^{-1}}^S \vec{y}_{\text{psi}} \quad \vec{y}_{\text{psi}} \sim \mathcal{N}(\vec{0}, K_{\text{psi,psi}})$$

$$K_{\text{sparse}} = S K_{\text{psi,psi}} S^T = K_{\text{obs,psi}} K_{\text{psi,psi}}^{-1} K_{\text{psi,obs}}$$



Diagonal correction (essential for continuous optimization)

$$K_{\text{sparse}} = \text{diag}[K_{\text{obs,obs}} - K_{\text{obs,psi}} K_{\text{psi,psi}}^{-1} K_{\text{psi,obs}}] + K_{\text{obs,psi}} K_{\text{psi,psi}}^{-1} K_{\text{psi,obs}}$$

E. Snelson and Z. Ghahramani, "Sparse Gaussian processes using pseudo-inputs", Advances in Neural Information Processing Systems 18, Cambridge, Massachussets, 2006

J. Quinonero-Candela and C.E. Rasmussen, "A Unifying View of Sparse Approximate Gaussian Process Regression", Journal of Machine Learning 6 (2005), 1939-1959

# Joint optimization

Efficient computation of objective function:

$\mathbf{O}(m^2n)$  instead of  $\mathbf{O}(n^3)$  with  $m$  pseudo-inputs and  $n$  observations

$$\log \rho(\mathcal{D} | \vec{p}_0, \vec{\sigma}_{\text{exp}}, M) = -\frac{N}{2} \log(2\pi) - \frac{1}{2} \log |M| - \frac{1}{2} (\vec{\sigma}_{\text{exp}} - S\vec{p}_0)^T M^{-1} (\vec{\sigma}_{\text{exp}} - S\vec{p}_0)$$

## Scenario

300 pseudo-input points (1500 parameters)

15 parameters in covariance function (a.k.a hyperparameters)

9287 experiment data points

## Timings

Objective function: 1.3 sec (4 cores: 0.5 sec)

Gradient wrt hyperpars & pseudo-inputs: 50 sec (4 cores: 17 sec)

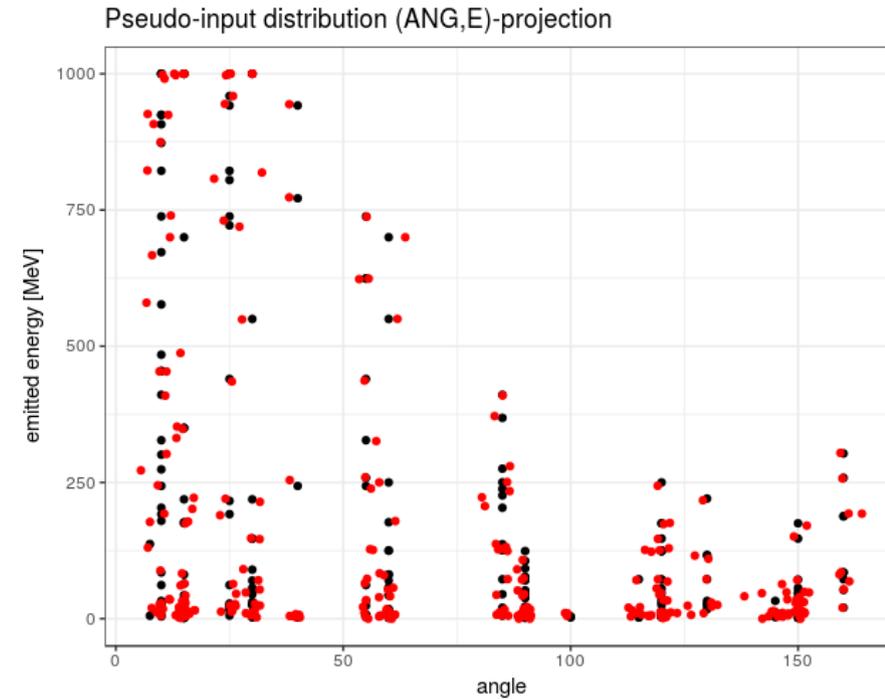
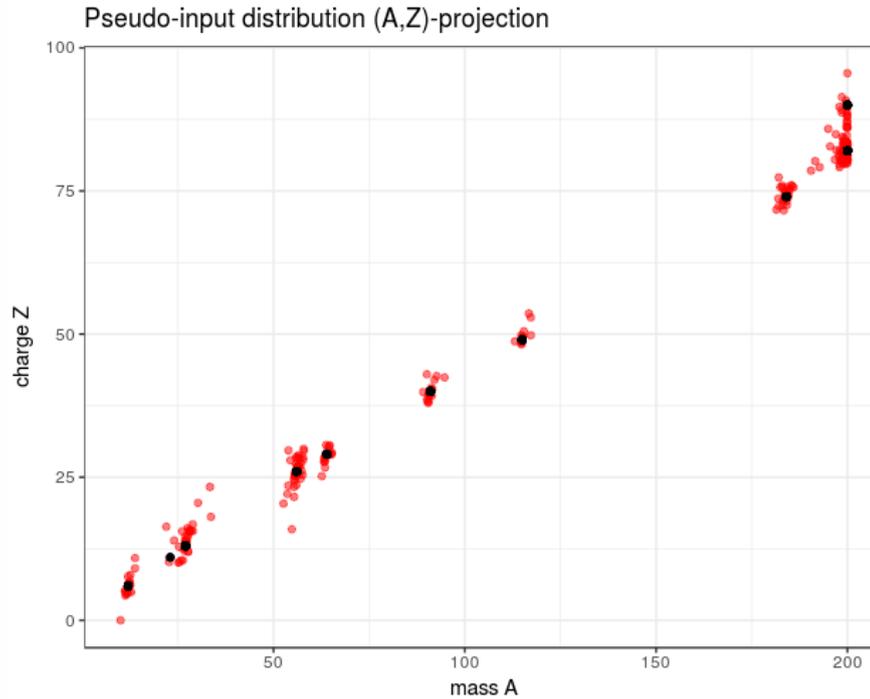
## Optimization on cluster

3500 iterations with L-BFGS-B algorithm in 10 hours

using 25 cores (inefficiency: distributed memory)

**$X^2 / n = 1.03$**

# Pseudo-Inputs & Hyperpars

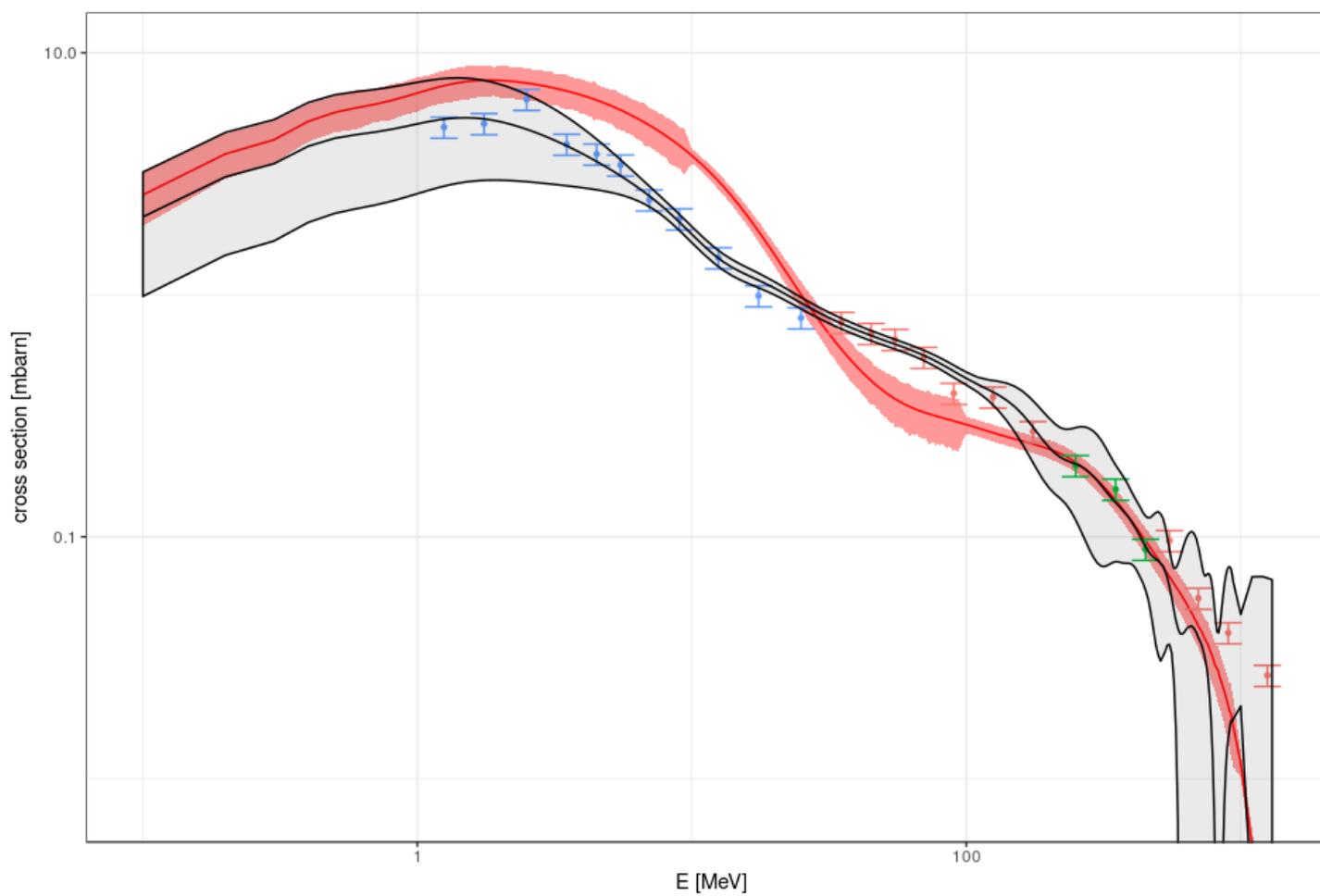


	$\delta$	$\lambda_{EN}$	$\lambda_A$	$\lambda_Z$	$\lambda_{ANG}$	$\lambda_E$
$K_1$	0.5	99	<b>103</b>	<b>41</b>	68	5
$K_2$	0.3	272	<b>115</b>	<b>49</b>	64	42

$\tau: k = 0.3, x_0 = 2.7$

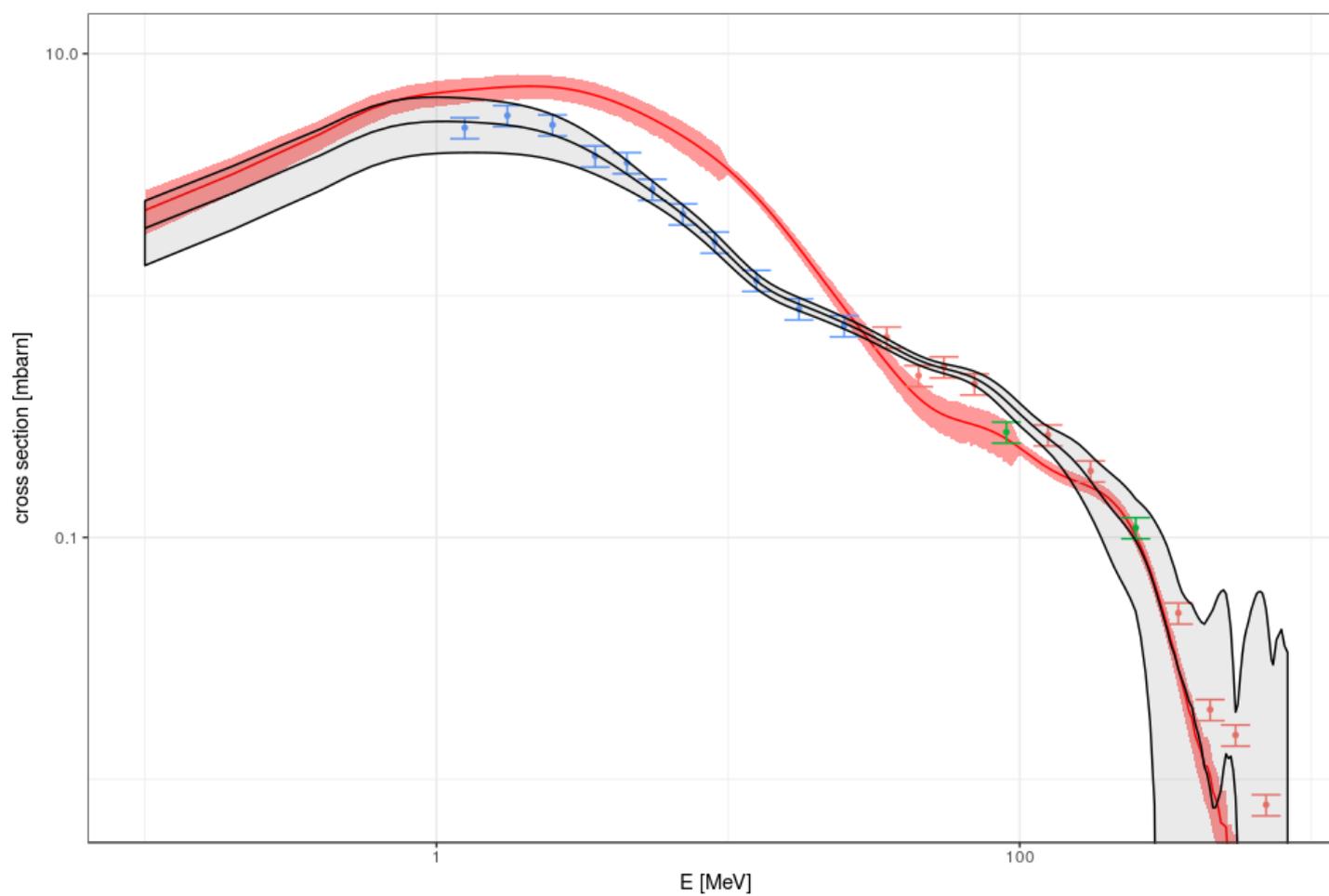
# GP prediction

$P + \text{Al}27 \rightarrow X + n$     EN: 1500 MeV    ANG: **30** deg



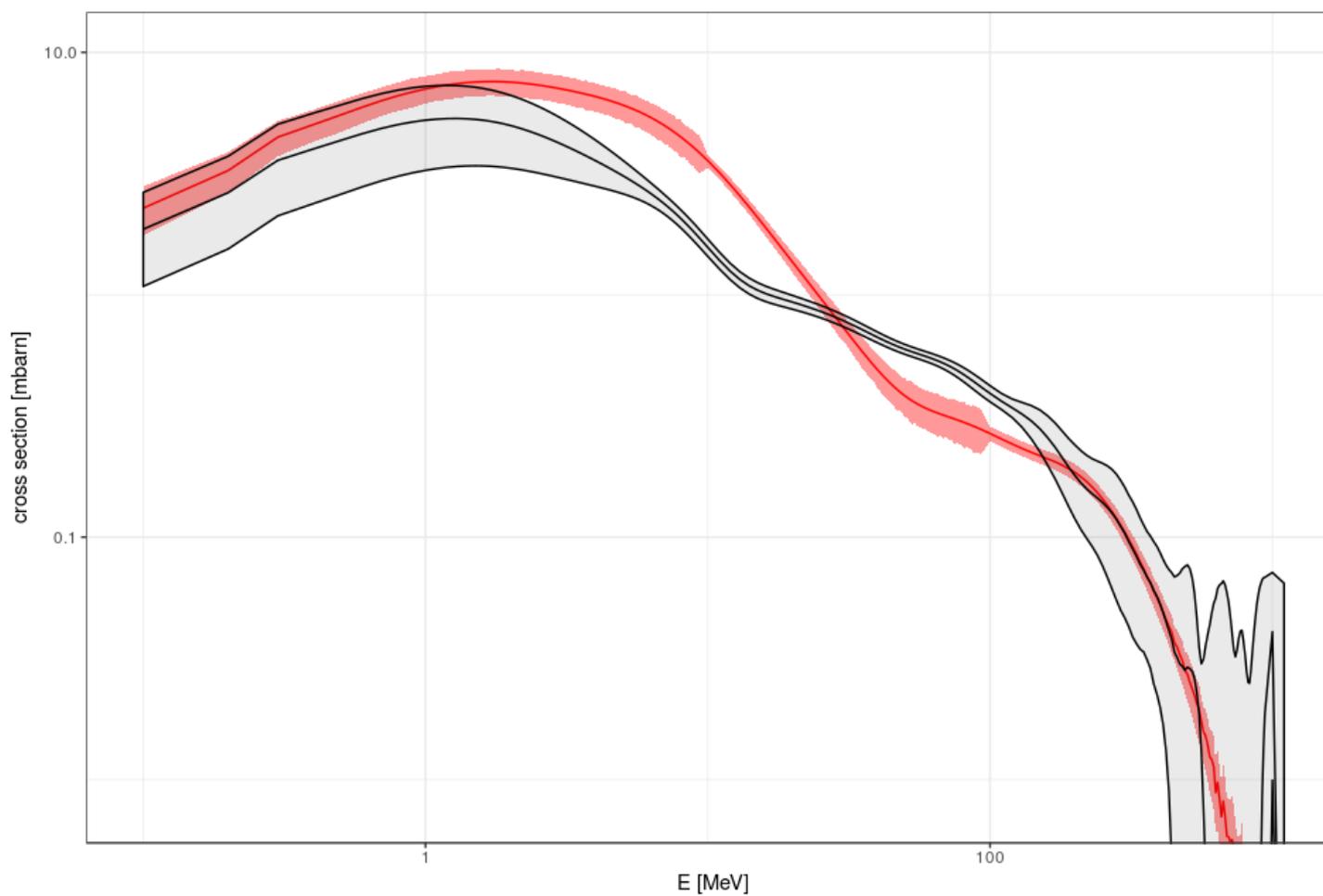
# GP prediction

$P + \text{Al}27 \rightarrow X + n$     EN: 1500 MeV    ANG: 60 deg

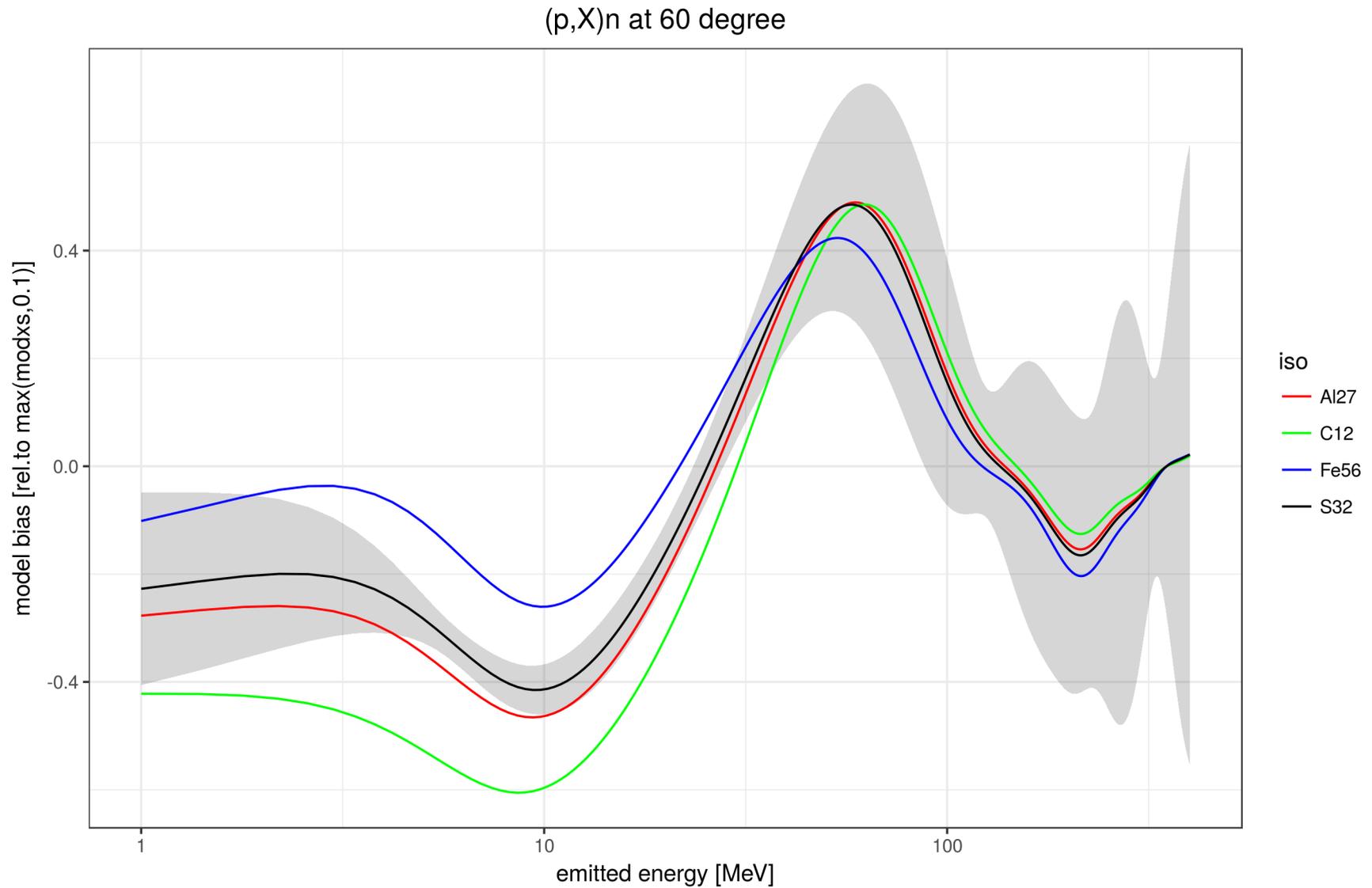


# Interpolation between angles

$P + Al_{27} \rightarrow X + n$     EN: 1500 MeV    ANG: **45** deg

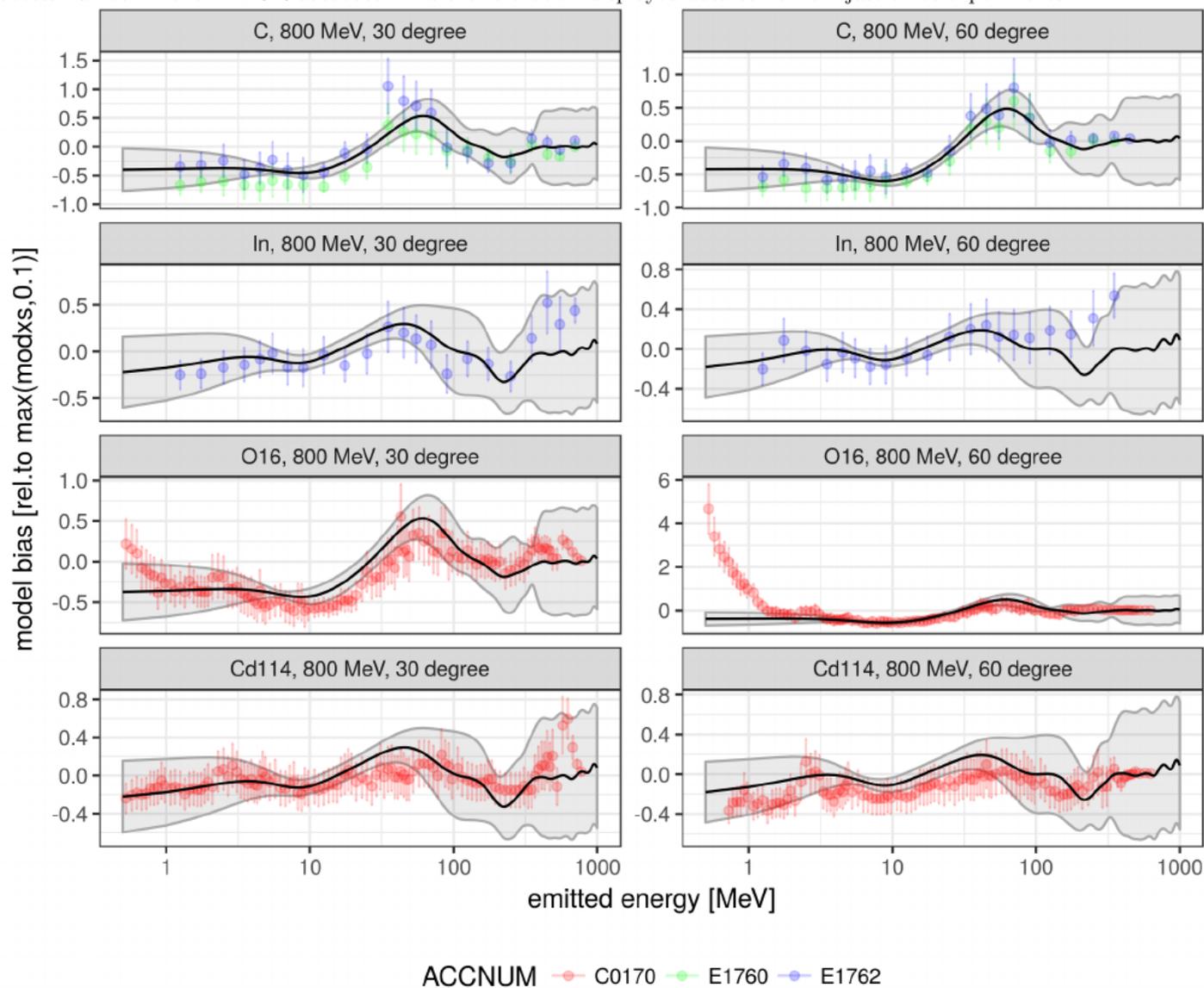


# Extrapolation to other isotopes

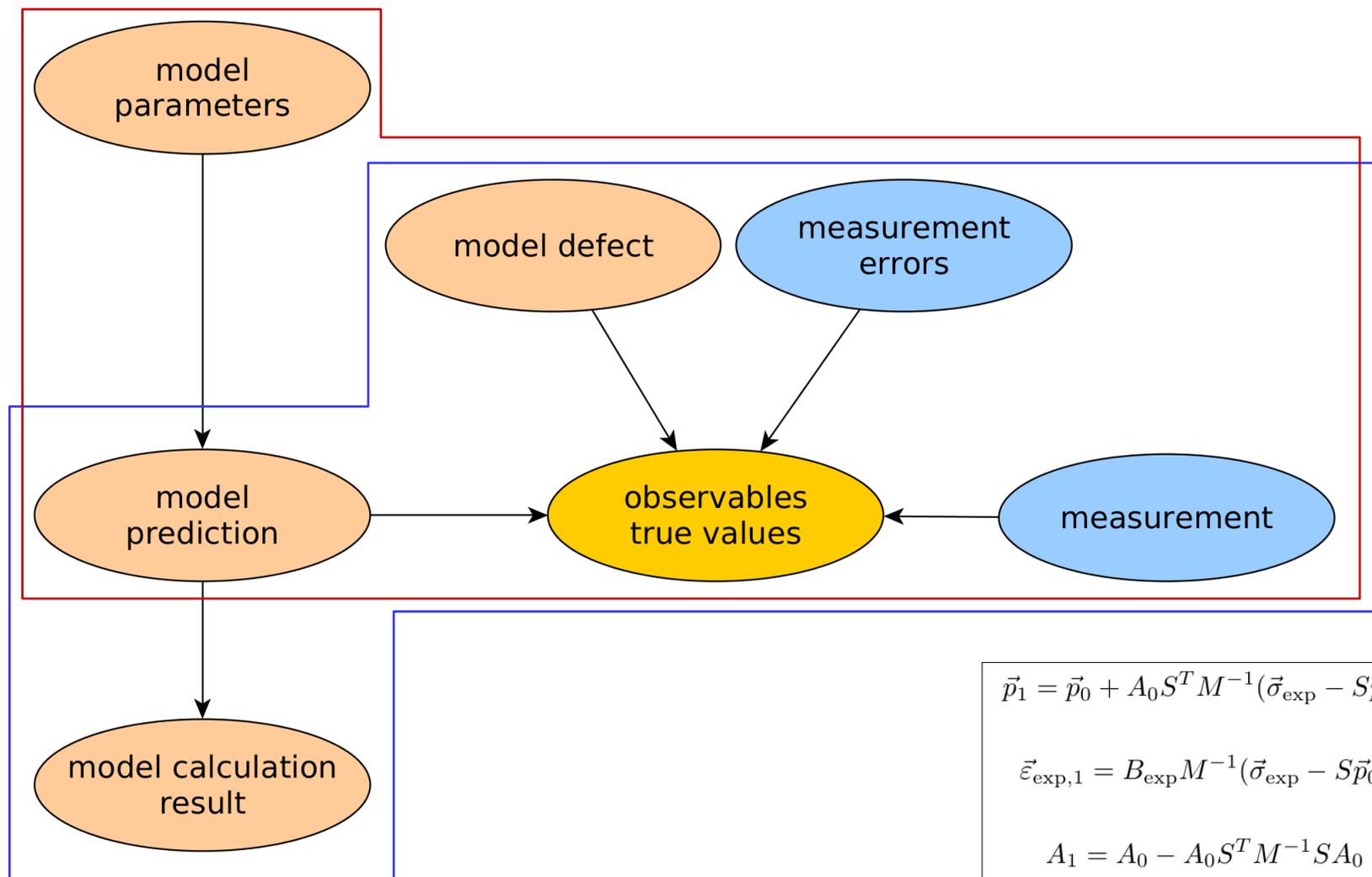


# Discussion of extrapolation

**Fig. 2.** Model bias of INCL in the (p,X)n double differential spectra for 800 MeV incident protons and different isotopes as predicted by GP regression. A missing mass number behind the isotope symbol indicates natural composition. The uncertainty band of the prediction and the error bars of the experiment data denote the  $2\sigma$  confidence interval. Carbon and indium were taken into account in the GP regression but not cadmium and oxygen. The experiment data is colored according to the associated access number in the EXFOR database. This shows that all displayed data come from just three experiments.



# Status quo



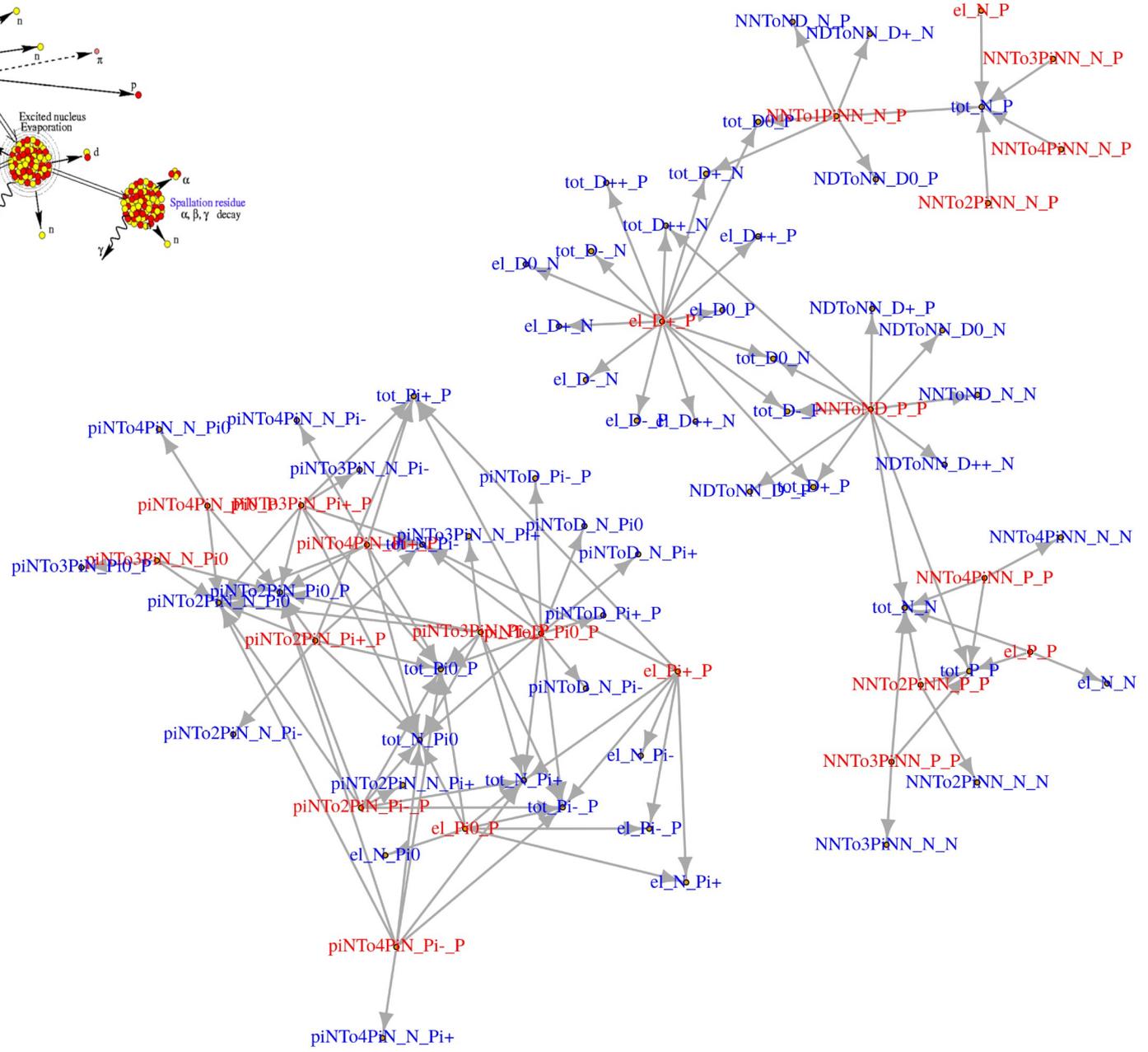
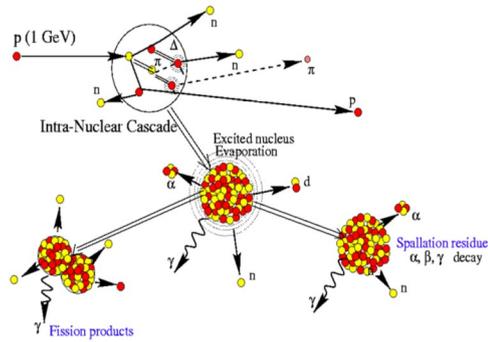
$$\vec{p}_1 = \vec{p}_0 + A_0 S^T M^{-1} (\vec{\sigma}_{\text{exp}} - S \vec{p}_0)$$

$$\vec{\epsilon}_{\text{exp},1} = B_{\text{exp}} M^{-1} (\vec{\sigma}_{\text{exp}} - S \vec{p}_0)$$

$$A_1 = A_0 - A_0 S^T M^{-1} S A_0$$

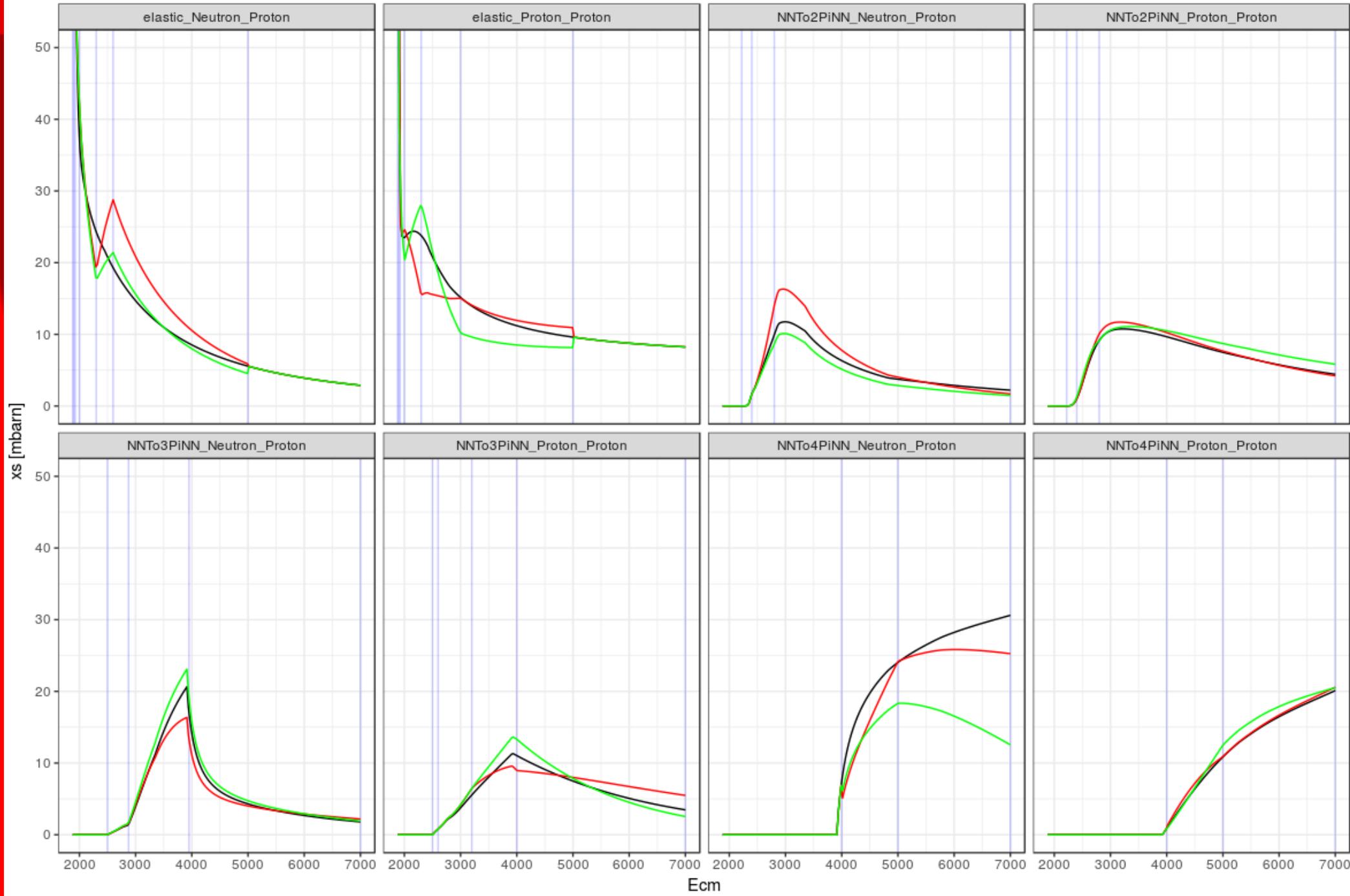
$$B_{\text{exp},1} = B_{\text{exp}} - B_{\text{exp}} M^{-1} B_{\text{exp}}$$

# Cross sections & isospin



$$M = SA_0(\delta_1, \delta_2, \dots)S^T + K_{\text{def}}(\lambda_1, \lambda_2, \dots) + B_{\text{exp}}$$

# Pulling the strings



# From deterministic to stochastic

Marginal Likelihood for deterministic linear model

$$\log \rho(\vec{\sigma}_{\text{exp}} | \vec{p}_0, S, M) = -\frac{N}{2} \log(2\pi) - \frac{1}{2} \log |M| - \frac{1}{2} (\vec{\sigma}_{\text{exp}} - S\vec{p}_0)^T M^{-1} (\vec{\sigma}_{\text{exp}} - S\vec{p}_0)$$

Marginal Likelihood for stochastic linear model

$$\rho(\vec{\sigma}_{\text{exp}} | \vec{p}_0, M) = \int \rho(\vec{\sigma}_{\text{exp}} | \vec{p}_0, S, M) \rho(S) dS$$

e.g.  $10^4 \times 10^4$  matrix

## Challenge

Likely, no analytic solution of integral

Size of  $N \times M$  matrix **S** with

$N$  ... number of experimental data points

$M$  ... number of model parameters

equals number of integration variables

For inclusive neutron DDX: 200.000 integration variables



# Work ahead and outlook

## Methodological

Complete framework for stochastic linear models

Investigate the propagation of model bias through simulations

Conceive a Monte Carlo algorithm for non-linearity

## Practical

Include other reaction data from EXFOR (e.g. isotope production, cumulative xs)

Use the approach on other model parameters (e.g. potentials)

Propagate found uncertainties through a transport code

DE LA RECHERCHE À L'INDUSTRIE



# Common sense inference

## Hypothesis

Compute cluster maintenance

Network cable not plugged in

Irfu intranet down

Password expired

## Observation

Can connect to compute cluster

Cannot connect to compute cluster

If  $A$  is true, then  $B$  is true

$B$  is true

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Therefore,  $A$  becomes more plausible



CC-IN2P3