

High-order schemes for non-ideal 3 + 1 GRMHD: a study of the kinematic mean-field dynamo process in accreting tori around Kerr black holes

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 - Conclusions
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Dynamo theory

Amplification of Magnetic Fields

Ordered magnetic fields on large scales are a fundamental part of many processes related to accretion disks:

- jets from protostellar systems, AGNs, and micro-quasars,
- Blandford-Znajek mechanism from Kerr Black Holes,
- MRI and turbulent viscosity.

A **mean-field dynamo** mechanism may do the job: *correlated* small-scale fluctuations in velocity and magnetic field can provide a mean electromotive force and amplify seed magnetic fields.

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Mean-field dynamo in classical MHD

Consider small-scale **turbulent fluctuations** in the fields \mathbf{v} e \mathbf{B} :

$$\mathbf{v}(\mathbf{x}, t) = \mathbf{v}_0(\mathbf{x}, t) + \delta\mathbf{v}(\mathbf{x}, t), \quad \mathbf{B}(\mathbf{x}, t) = \mathbf{B}_0(\mathbf{x}, t) + \delta\mathbf{B}(\mathbf{x}, t)$$

[assumption of **kinematic regime** $\Rightarrow \mathbf{v}_0(\mathbf{x}, t)$ fixed].

The resistive induction equation for the mean magnetic field reads:

$$\partial_t \mathbf{B}_0 = \nabla \times (\mathbf{v}_0 \times \mathbf{B}_0) + \eta_r \nabla^2 \mathbf{B}_0 + \nabla \times \mathcal{E}$$

$$\mathcal{E} = \langle \delta\mathbf{v} \times \delta\mathbf{b} \rangle \simeq \alpha \mathbf{B}_0 - \beta \nabla \times \mathbf{B}_0$$



$$\partial_t \mathbf{B} = \nabla \times (\mathbf{v} \times \mathbf{B}) + \eta \nabla^2 \mathbf{B} + \alpha \nabla \times \mathbf{B}$$

- Increase of the magnetic resistivity ($\eta = \eta_r + \beta$)
- Generation of magnetic field parallel to the current ($\mathbf{J} = \nabla \times \mathbf{B}$)
- Generalized Ohm's law ($\mathbf{E}' \equiv \mathbf{E} + \mathbf{v} \times \mathbf{B} = \eta \mathbf{J} - \alpha \mathbf{B}$)

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The $\alpha - \Omega$ dynamo

Let us decompose the magnetic field (and the other quantities) as

$$\mathbf{B} = \mathbf{B}_P + B_T \mathbf{e}_T, \quad \mathbf{B}_P = \nabla \times (A_T \mathbf{e}_T).$$

The induction equation is split as

$$\partial_t B_T + (\mathbf{U}_P \cdot \nabla) B_T = (\mathbf{B}_P \cdot \nabla) U_T + \eta \nabla^2 B_T$$

$$\partial_t A_T + (\mathbf{U}_P \cdot \nabla) A_T = \alpha B_T + \eta \nabla^2 A_T$$

- Differential rotation \Rightarrow Generation of toroidal field (Ω effect)
- Toroidal field \Rightarrow Generation of poloidal field (α effect)

$$\mathbf{B}_P \Rightarrow \mathbf{B}_T \Rightarrow \mathbf{B}_P \Rightarrow \dots$$

Exponentially growing $\alpha - \Omega$ dynamo modes, damped by resistivity.

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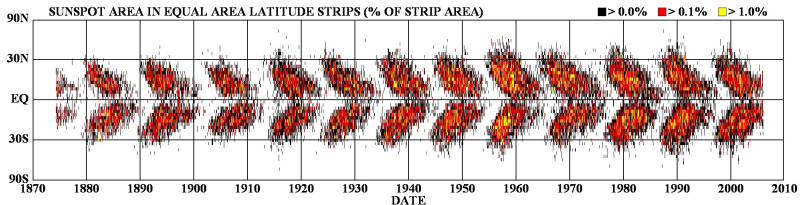
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The solar cycle and the *butterfly diagram*

- Flux tubes of growing toroidal magnetic field emerge through the photosphere: formation of a Sun Spot
- Formation at latitudes $\pm 35^\circ$
- Migration towards the equator
- Strong periodicity (~ 11 yr)

A possible mechanism at its basis is the $\alpha - \Omega$ dynamo.

DAILY SUNSPOT AREA AVERAGED OVER INDIVIDUAL SOLAR ROTATIONS



Non-ideal Ohm's law in $3 + 1$ GRMHD: formulation, methods, tests

The ECHO code for GRMHD

Numerical simulations will be performed with the *Eulerian Conservative High-Order ECHO* code (Del Zanna et al., 2007), a versatile tool for MHD and GRMHD combining shock-capturing properties and accuracy.

Main features (Londrillo & Del Zanna, 2000; 2004):

- conservative form, RK time-stepping,
- finite differences, high-order methods (CENO, WENO, MP...),
- simplified Riemann solvers: LLF, HLL, HLLC,
- F90, various geometries, different physical modules,
- Upwind Constrained Transport (UCT) based on 4-state B fluxes.

Upgrades:

- evolution of Einstein equations (Bucciantini & Del Zanna 2011),
- radiation hydrodynamics (Zanotti et al., 2011),
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Conservative 3 + 1 equations

In numerical GRMHD the spacetime metric is split in the **3 + 1 form**

$$ds^2 = -\alpha^2 dt^2 + \gamma_{ij} (dx^i + \beta^i dt)(dx^j + \beta^j dt),$$

where α and β^i are, respectively, the *lapse function* and *shift vector* ($\alpha = 1$, $\beta^i = 0$ in Newtonian MHD), and γ_{ij} is the 3-metric tensor.

The **conservative** equations in ECHO for *ideal* GRMHD are

$$\frac{\partial}{\partial t} \sqrt{\gamma} \begin{bmatrix} D \\ S_j \\ E \\ B^j \end{bmatrix} + \frac{\partial}{\partial x^i} \sqrt{\gamma} \begin{bmatrix} DV^i \\ \alpha S_j^i - \beta^i S_j \\ \alpha S^i - \beta^i E \\ V^i B^j - V^j B^i \end{bmatrix} = \sqrt{\gamma} \begin{bmatrix} 0 \\ \frac{1}{2} \alpha S^{ik} \partial_j \gamma_{ik} + S_i \partial_j \beta^i - E \partial_j \alpha \\ \alpha S^{ij} K_{ij} - S^j \partial_j \alpha \\ 0 \end{bmatrix}$$

where K_{ij} is the *extrinsic curvature* and $V^i = \alpha v^i - \beta^i$ is the *transport velocity*.

Let us now relax the ideal Ohm law (the same in MHD and GRMHD):

$$\mathbf{E} = -\mathbf{v} \times \mathbf{B}.$$

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Covariant generalized Ohm's Law

Covariant Maxwell's equations:

$$\nabla_{\mu} F^{\mu\nu} = -I^{\nu}, \quad \nabla_{\mu} F^{*\mu\nu} = 0$$

$$F^{\mu\nu} = u^{\mu} e^{\nu} - u^{\nu} e^{\mu} + \epsilon^{\mu\nu\lambda\kappa} b_{\lambda} u_{\kappa}, \quad I^{\mu} = q_0 u^{\mu} + j^{\mu}$$

Fully covariant formulation for a **resistive** plasma with **dynamo** action:

$$e^{\mu} = \eta j^{\mu} + \xi b^{\mu}$$

$$(\xi \equiv -\alpha_{dyn}, \quad \eta = \eta_r + \beta_{dyn})$$



$$\Gamma[\mathbf{E} + \mathbf{v} \times \mathbf{B} - (\mathbf{E} \cdot \mathbf{v})\mathbf{v}] = \eta(\mathbf{J} - q\mathbf{v}) + \xi\Gamma[\mathbf{B} - \mathbf{v} \times \mathbf{E} - (\mathbf{B} \cdot \mathbf{v})\mathbf{v}]$$

Classical limit ($|\mathbf{v}| \ll 1, |\mathbf{E}| \ll |\mathbf{B}|$):

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Implementation within 3 + 1 GRMHD

Maxwell's equations in 3 + 1 form are:

$$\gamma^{-1/2} \partial_t (\gamma^{1/2} \mathbf{B}) + \nabla \times (+\alpha \mathbf{E} + \beta \times \mathbf{B}) = 0, \quad (\nabla \cdot \mathbf{B} = 0)$$

$$\gamma^{-1/2} \partial_t (\gamma^{1/2} \mathbf{E}) + \nabla \times (-\alpha \mathbf{B} + \beta \times \mathbf{E}) = -(\alpha \mathbf{J} - q\beta), \quad (\nabla \cdot \mathbf{E} = q)$$

Computing \mathbf{J} from Ohm's law we get:

$$\begin{aligned} & \gamma^{-1/2} \partial_t (\gamma^{1/2} \mathbf{E}) + \nabla \times (-\alpha \mathbf{B} + \beta \times \mathbf{E}) + (\alpha \mathbf{v} - \beta) \nabla \cdot \mathbf{E} = \\ & -\alpha \Gamma \eta^{-1} \{ [\mathbf{E} + \mathbf{v} \times \mathbf{B} - (\mathbf{E} \cdot \mathbf{v}) \mathbf{v}] - \xi [\mathbf{B} - \mathbf{v} \times \mathbf{E} - (\mathbf{B} \cdot \mathbf{v}) \mathbf{v}] \} \end{aligned}$$

A **stiff** equation: terms $\propto \eta^{-1}$ can evolve on time scales $\tau_\eta \ll \tau_h$.

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$$\begin{aligned} & \gamma^{-1/2} \partial_t (\gamma^{1/2} \mathbf{E}) + \nabla \times (-\alpha \mathbf{B} + \beta \times \mathbf{E}) + (\alpha \mathbf{v} - \beta) \nabla \cdot \mathbf{E} = \\ & -\alpha \Gamma \eta^{-1} \{ [\mathbf{E} + \mathbf{v} \times \mathbf{B} - (\mathbf{E} \cdot \mathbf{v}) \mathbf{v}] - \xi [\mathbf{B} - \mathbf{v} \times \mathbf{E} - (\mathbf{B} \cdot \mathbf{v}) \mathbf{v}] \} \end{aligned}$$

A **stiff** equation: terms $\propto \eta^{-1}$ can evolve on time scales $\tau_\eta \ll \tau_h$.

Letting $\eta = \xi = 0$ we retrieve the ideal case:

$$\mathbf{E} + \mathbf{v} \times \mathbf{B} - (\mathbf{E} \cdot \mathbf{v}) \mathbf{v} = 0 \Rightarrow \mathbf{E} = -\mathbf{v} \times \mathbf{B}.$$

Stiff relaxation equations

System of hyperbolic ODEs + **stiff** relaxation equations:

$$\begin{aligned} \mathbf{X} = \gamma^{1/2} \mathbf{E} : \quad \partial_t \mathbf{X} &= \mathbf{Q}_X(\mathbf{X}, \mathbf{Y}) + \mathbf{R}_X(\mathbf{X}, \mathbf{Y}) \\ \mathbf{Y} = \gamma^{1/2} \mathbf{B} : \quad \partial_t \mathbf{Y} &= \mathbf{Q}_Y(\mathbf{X}, \mathbf{Y}) \end{aligned}$$

- $\mathbf{Q}_{X,Y}$ = **non stiff** terms, evolving as $\sim \tau_h$
- \mathbf{R}_X = **stiff** terms $\propto \eta^{-1}$, evolving as $\sim \tau_\eta \ll \tau_h$

We need appropriate techniques to evolve the system, even for $\xi = 0$:

- Splitting methods
(Komissarov, 2007; Takamoto & Inoue, 2011; Takahashi et al., *subm.*)
- Discontinuous Galerkin methods
(Dumbser & Zanotti, 2009; Zanotti & Dumbser, 2011).
- Implicit-Explicit RK methods
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High-order IMEX schemes

High-order time integration via IMEX Runge-Kutta methods with Strong Stability Preserving properties (Pareschi & Russo, 2005):

- Phase 1: **Explicit** integration

$$\mathbf{X}_*^{(i)} = \mathbf{X}^n + \Delta t \sum_{j=1}^{i-1} \tilde{a}_{ij} \mathbf{Q}_X[\mathbf{X}^{(j)}, \mathbf{Y}^{(j)}] + \Delta t \sum_{j=1}^{i-1} a_{ij} \mathbf{R}_X[\mathbf{X}^{(j)}, \mathbf{Y}^{(j)}]$$

$$\mathbf{Y}_*^{(i)} = \mathbf{Y}^n + \Delta t \sum_{j=1}^{i-1} \tilde{a}_{ij} \mathbf{Q}_Y[\mathbf{X}^{(j)}, \mathbf{Y}^{(j)}]$$

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- Phase 3: **Final step**

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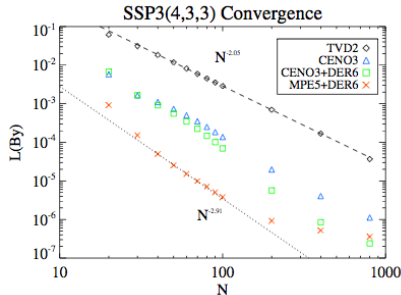
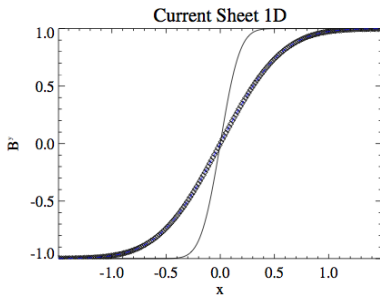
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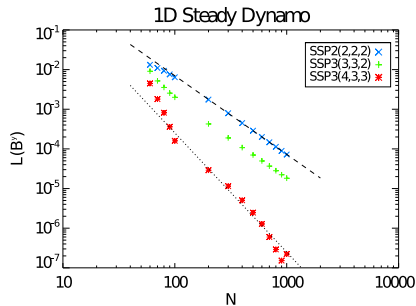
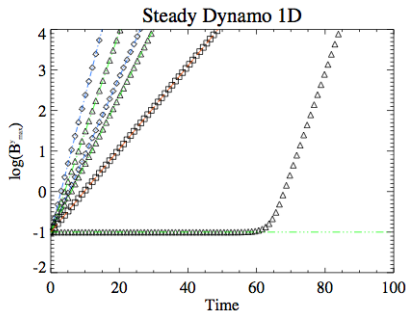
Numerical tests: 1D current sheet



Diffusion equation:

$$\rho \gg B^2 \Rightarrow B^y(x, t) = B_0 \operatorname{erf} \left(\frac{x}{2\sqrt{\eta t}} \right); \quad [\eta = 0.01, t = 1, 10]$$

Numerical tests: 1D dynamo



Exponentially growing dynamo modes:

$$B^y(x, t) = B_0 \exp(\gamma t) \cos(kx), \quad \gamma = \frac{\sqrt{1 + 4\eta k(\xi - \eta k)} - 1}{2\eta}$$

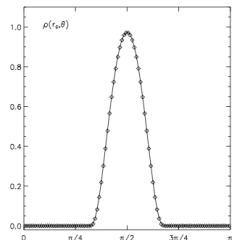
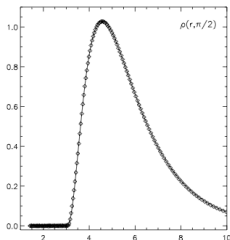
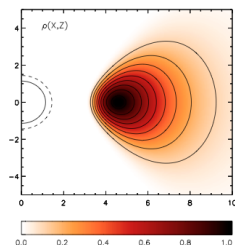
Kinematic dynamo in accretion tori

GRHD thick torus

Equilibrium: axisymmetric torus in Kerr metric and Boyer-Lindquist coordinates (Abramowicz et al., 1978; Font & Daigne, 2002).

Bernoulli equation for barotropic EOS $p \propto (\rho h)^\kappa$, differential rotation $\Omega = u^\phi / u_t$, constant specific angular momentum $l_0 = -u_\phi / u_t$:

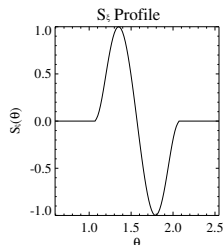
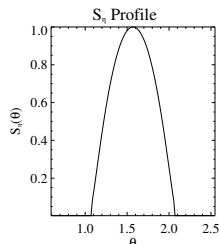
$$W - W_{\text{in}} + \frac{\kappa}{\kappa - 1} \frac{p}{\rho h} = 0, \quad W = \ln |u_t| = \frac{1}{2} \ln \left(\frac{g_{t\phi}^2 - g_{rr} g_{\phi\phi}}{g_{\phi\phi} + 2g_{t\phi} l_0 + g_{tt} l_0^2} \right)$$



Numerical set up

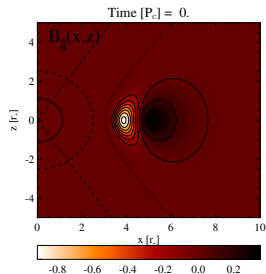
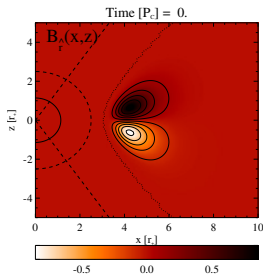
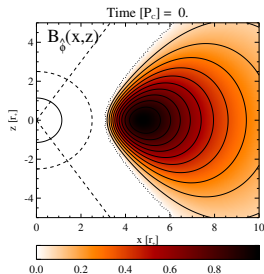
- Spatial interpolation: **MPE5 + DER6**.
- Time integration: **IMEX-RK SSP3(4,3,3)**.
- Two-dimensional grid in (r, θ) .
- Maximally rotating Kerr BH ($a = 0.99$).
- Ideal, corotating atmosphere.
- Spatially varying ξ and η .
- Different choices of **dynamo numbers**:

$$C_{\xi} = \frac{\xi R}{\eta} \geq 1, \quad C_{\Omega} = \frac{\Delta\Omega R^2}{\eta} \gg 1$$



Initial seed magnetic field

- Initial seed magnetic field $B \sim 10^{-6}$ either **toroidal** or **poloidal**.
- Initial ideal electric field ($\mathbf{E} = -\mathbf{v} \times \mathbf{B}$).



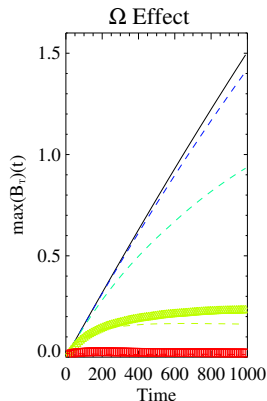
Study of the Ω effect vs resistivity

- No dynamo action ($\xi = 0$).
- Competition between **ideal Ω effect** and resistive **η dissipation**.
- Estimate of saturation toroidal field:

$$\Delta B \sim T \Delta \Omega |\mathbf{B}_P| \sim -T \frac{\eta}{R^2} B \Rightarrow$$

$$B_{sat} \sim \frac{\Delta \Omega R^2}{\eta} |\mathbf{B}_P| \equiv C_{\Omega} |\mathbf{B}_P|$$

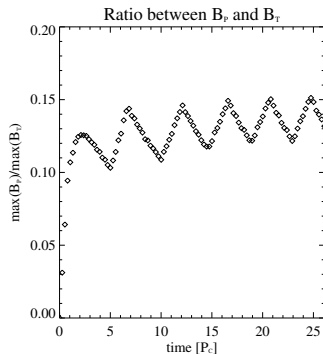
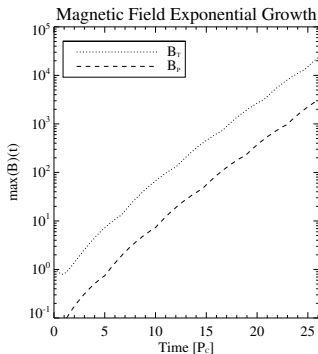
- Long-term runs ($P_c = 76.5$) confirm this ($\eta = 0, 10^{-5}, 10^{-4}, 10^{-3}, 10^{-2}$).



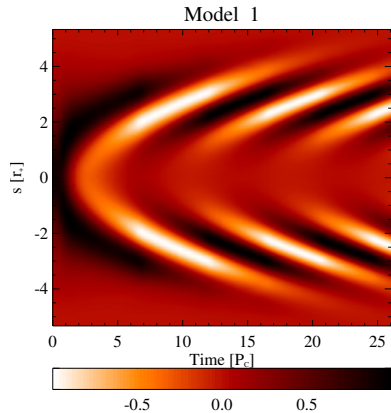
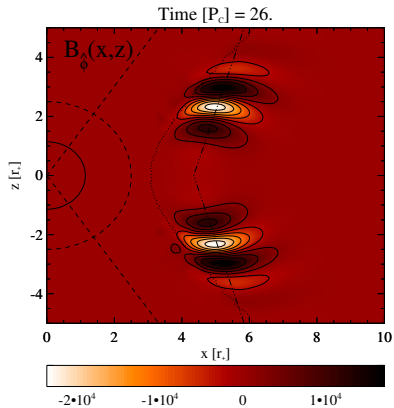
Evolution of the toroidal component

Evolution of the poloidal components

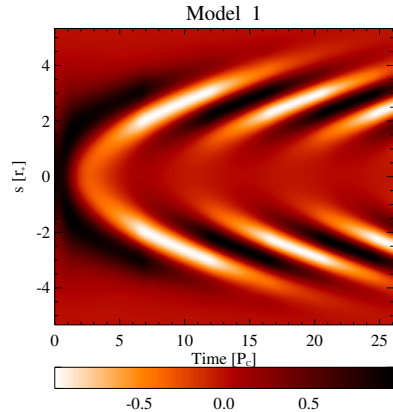
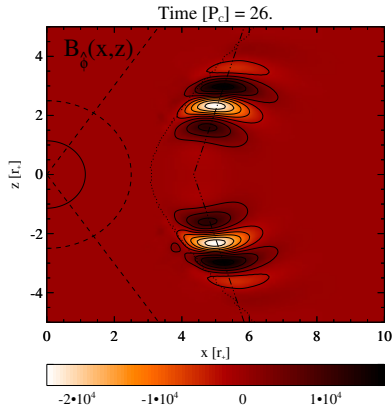
Growth rate and ratio B_P/B_T



Butterfly diagram

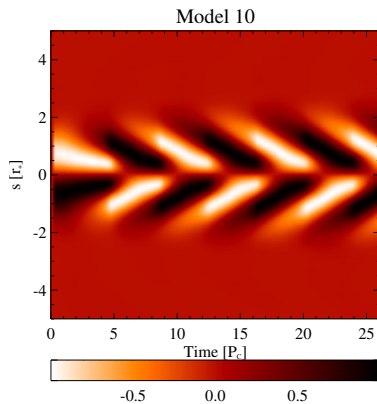


Butterfly diagram



Migration reversal

The *solar analogy* is reproduced by choosing $\xi < 0 \Rightarrow \alpha_{dyn} > 0$:



Summary of results

	B_{init}	C_{ξ}	C_{Ω}	Growth Rate	Period	s_{max}	$(B_P)_{\text{max}}/(B_T)_{\text{max}}$
Model 1	B_T	5	400	0.39	8.43	2.41	0.13
Model 2	B_T	-5	400	0.21	8.17	0.04	0.13
Model 3	B_T	25	400	1.58	2.77	2.05	0.42
Model 4	B_T	1	400	0.07	26.38	2.63	0.04
Model 5	B_T	5	80	0.39	5.79	3.35	0.22
Model 6	B_T	5	2000	0.22	16.46	1.82	0.06
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- resistivity and dynamo action in ECHO and X-ECHO,
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- Unification with the version for radiation RHD ([Zanotti et al., 2011](#); [Roedig et al., 2012](#)).

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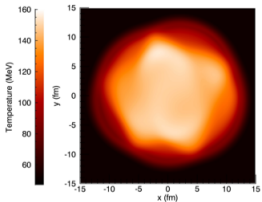
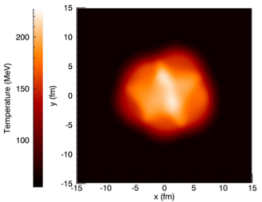
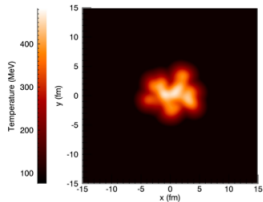
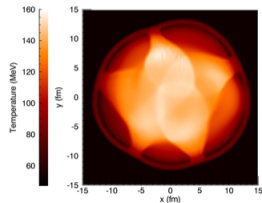
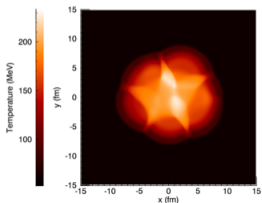
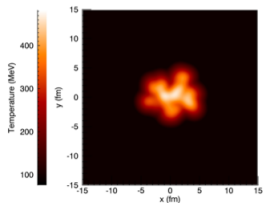
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