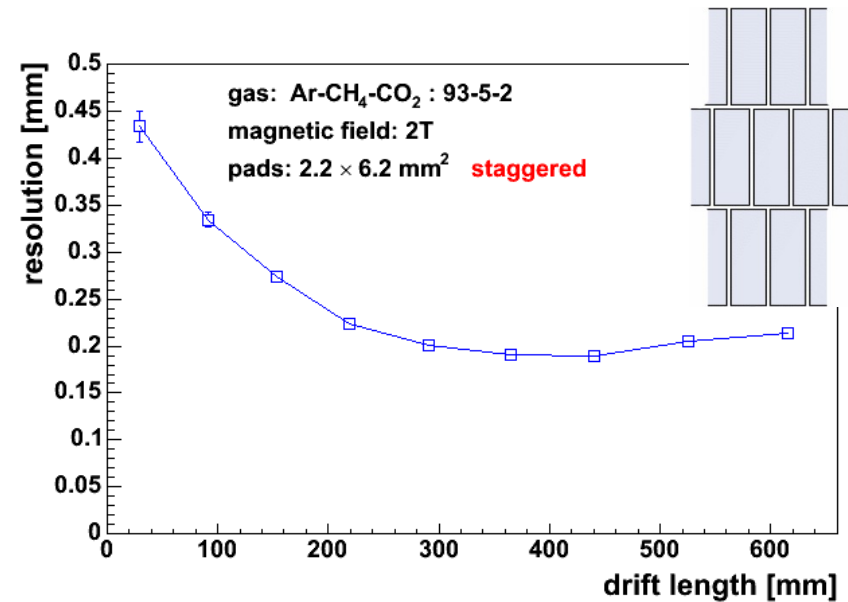
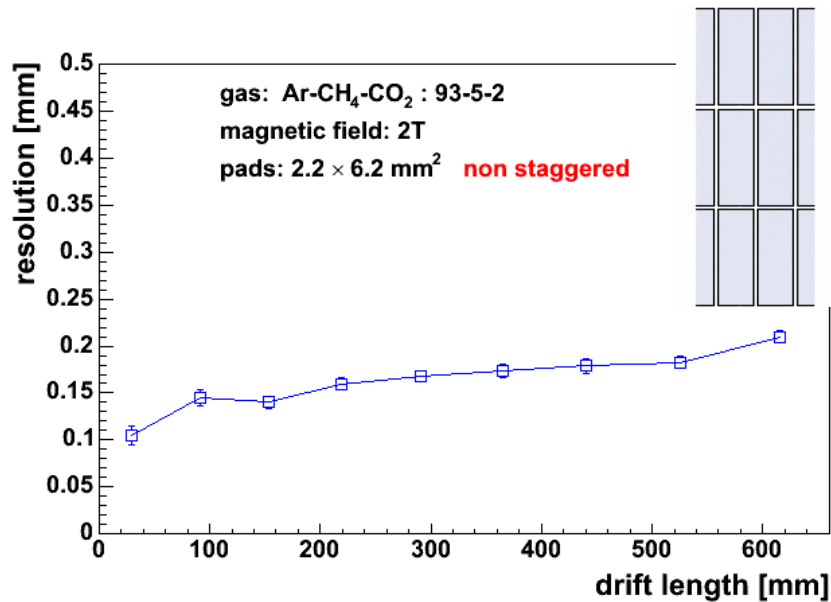


The Pad Response

- Motivation:
Resolution results for non-staggered and staggered pad layout



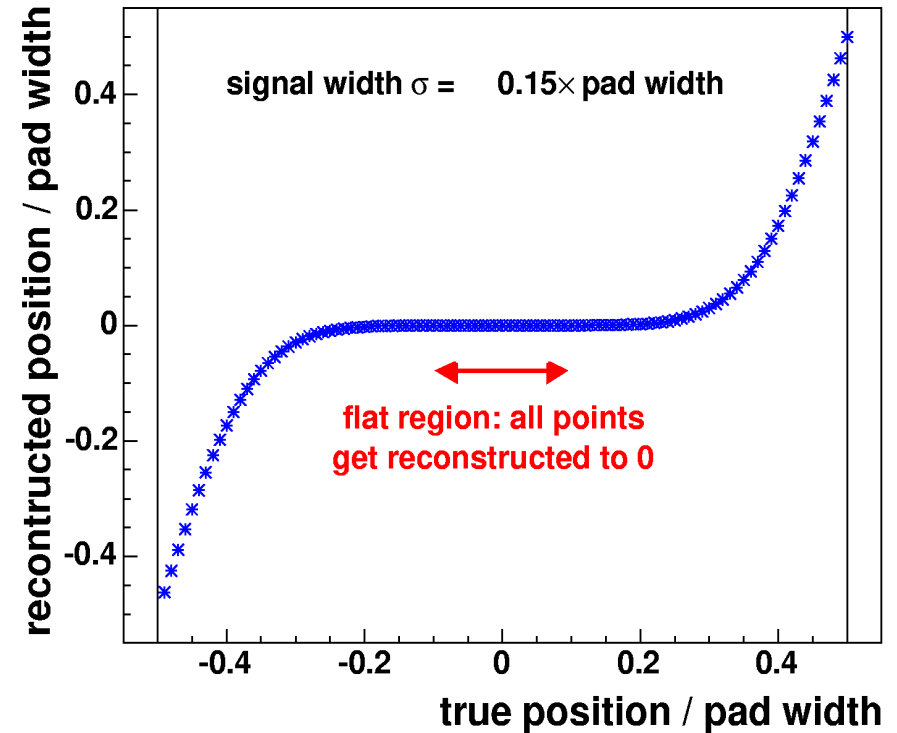
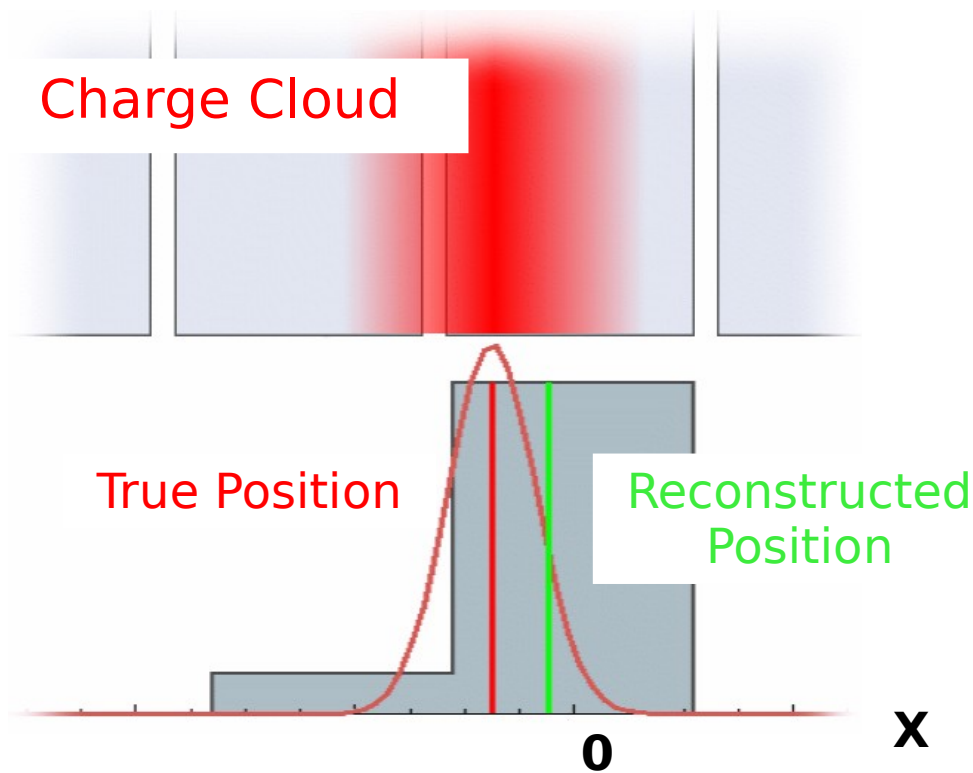
- **Non-staggered** pad layout:

- Expected dependence on drift length

- **Staggered** pad layout:

- Increasing values at small drift lengths
- Explanation: not enough charge sharing for correct reconstruction of point positions and residuals (Pad Response)

The Pad Response

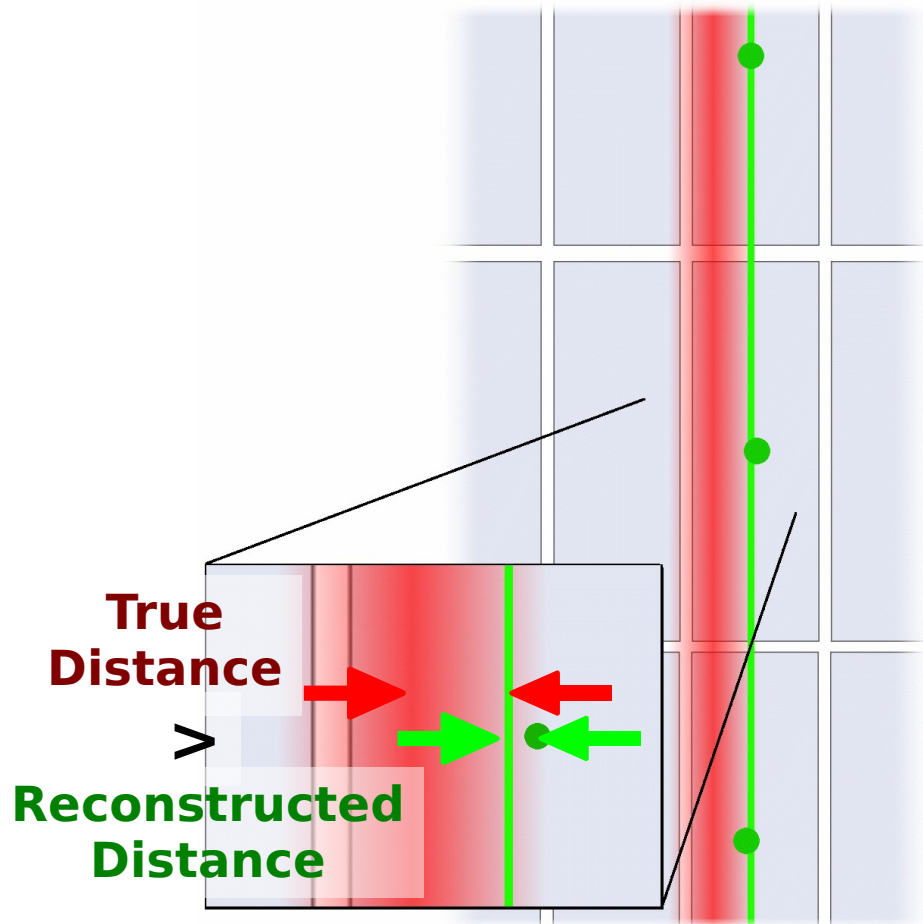


- Not enough charge sharing \rightarrow Instead of at the true position, hits are reconstructed by Center of Gravity method towards the middle of the pad with highest signal

Effect on the Resolution

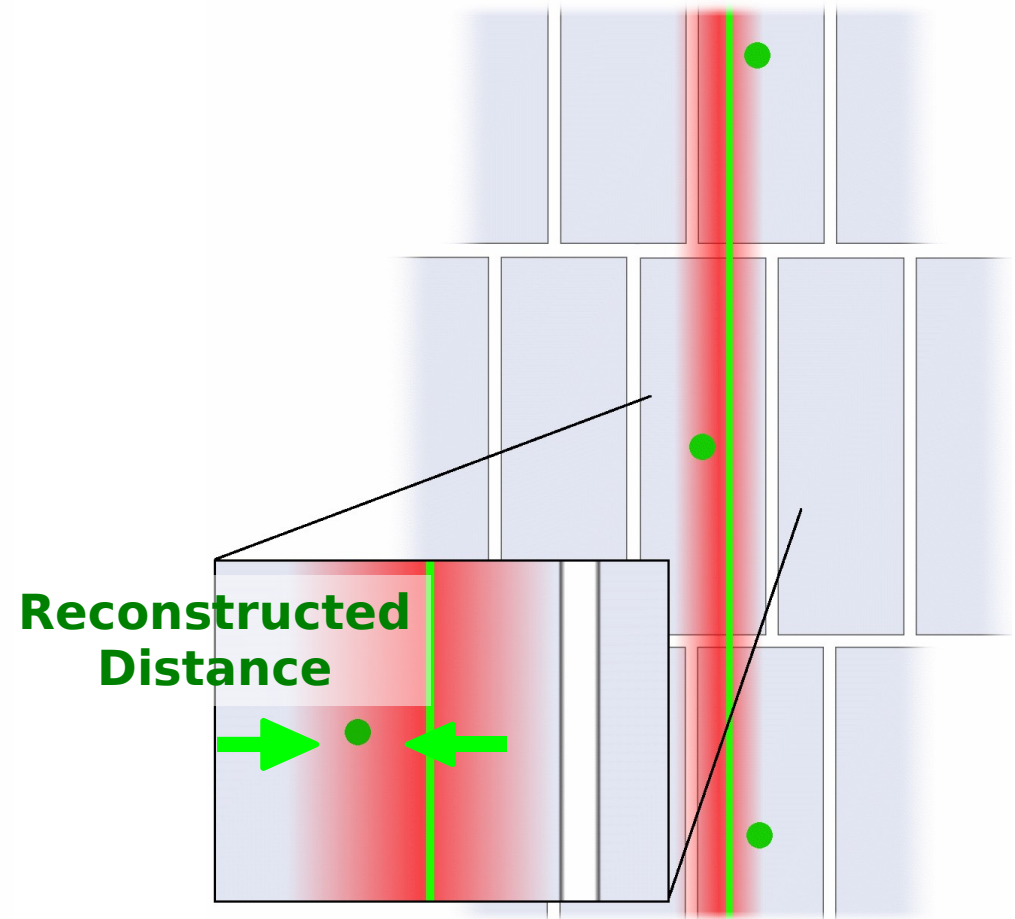
Non-staggered Pads:
reconstructed track
“gets pulled”
towards the reconstructed
points

**calculated residuals
too small**



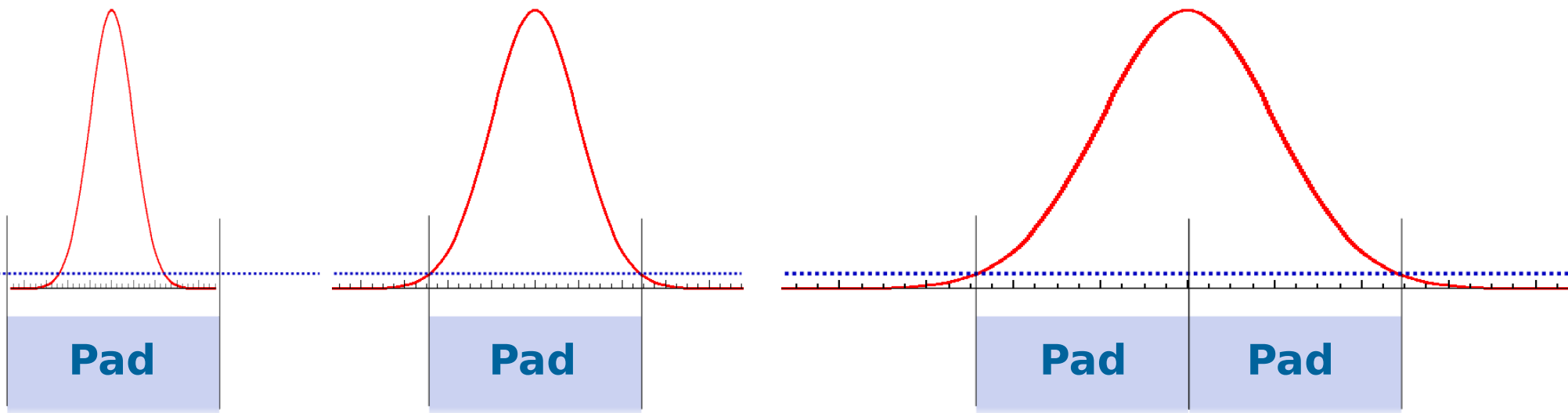
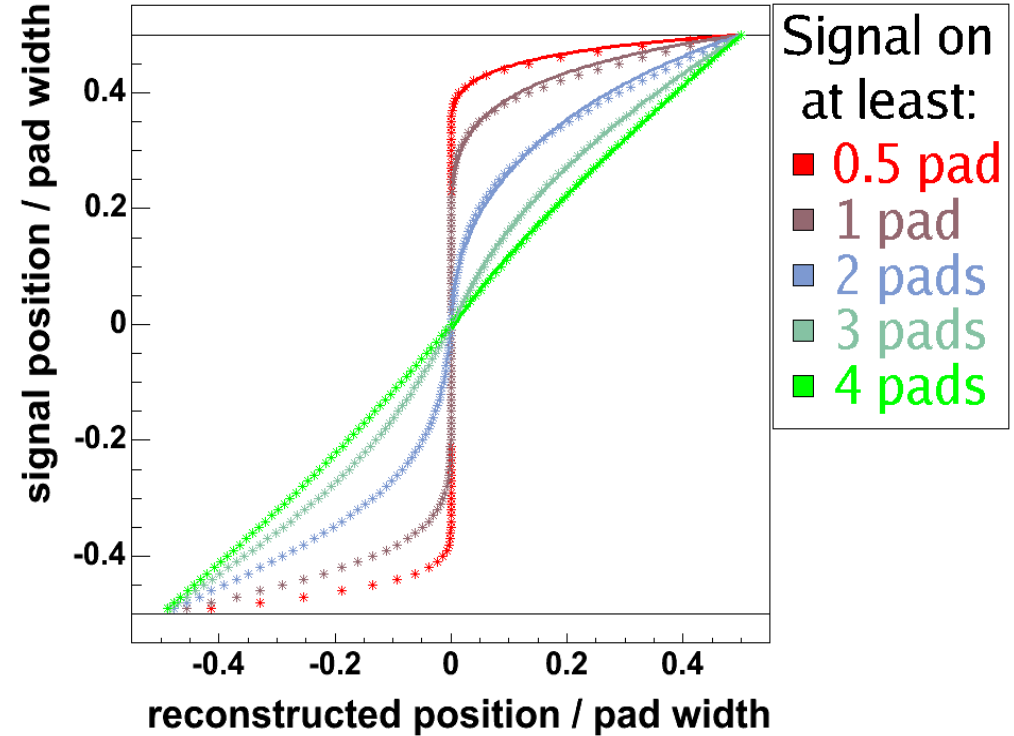
Staggered Pads:
points (Hits) get
reconstructed
too far from track

**calculated residuals
too big**



Pad Response Correction

- Pad Response Function
Simulate signal of a Gaussian charge cloud on your pads
- $$Q_{pad}(y) = \int_{-\infty}^{+\infty} \left(\Theta\left(\psi - \frac{\Delta}{2}\right) * \Theta\left(-\psi + \frac{\Delta}{2}\right) \right) \times \left(\frac{Q_{max}}{\sqrt{2\pi}\sigma_s} * \exp\left[-\frac{(y-\psi)^2}{2\sigma_s^2}\right] \right) d\psi$$
with cutoff at noise value (threshold)
- Apply center of gravity method to get pad response



Pad Response Correction

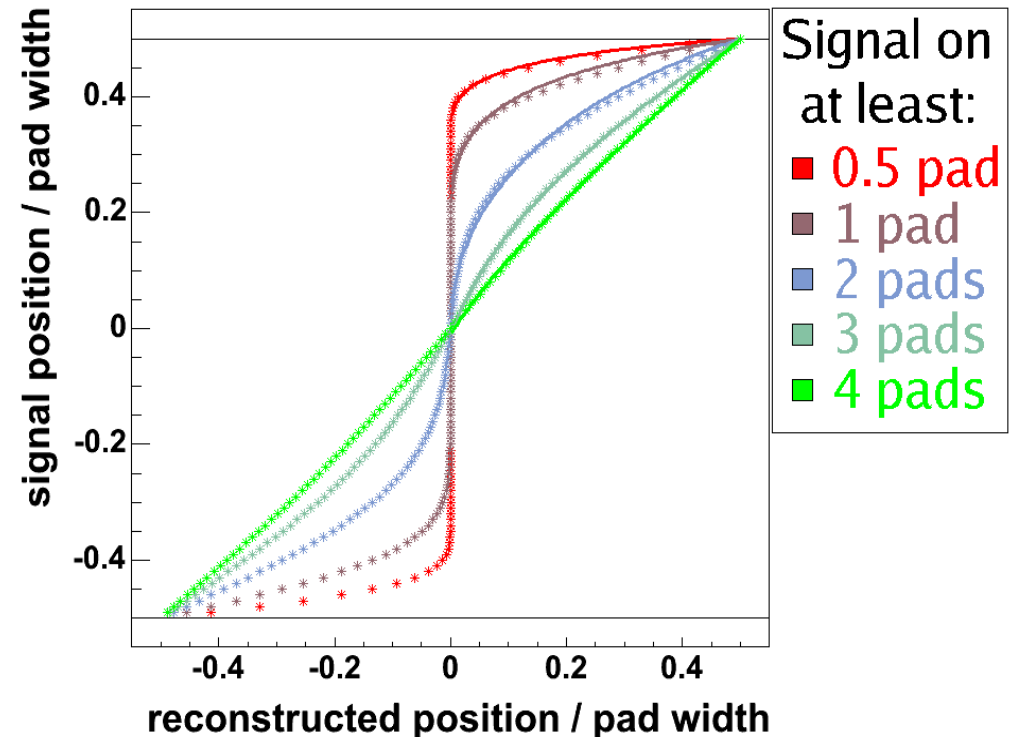
- Pad Response Functions:

$$F_{noflat} = P_1 x + P_2 \sqrt{x} + \left(\frac{1 - P_1}{2} - \frac{P_2}{\sqrt{2}} \right) \cdot \sqrt[3]{2x}$$

$$F_{flat} = P_0 + P_2 \sqrt{x} + \left(\frac{1 - 2P_0}{2} - \frac{P_2}{\sqrt{2}} \right) \cdot \sqrt[3]{2x}$$

(no physical background, just functions that fit the curves)

- Parameters P_0 , P_1 and P_2 depend on the width of the signal σ



Pad Response Correction

- Pad Response Correction

$$F_{noflat} = P_1 x + P_2 \sqrt{x} + \left(\frac{1-P_1}{2} - \frac{P_2}{\sqrt{2}} \right) \cdot \sqrt[3]{2x}$$

$$F_{flat} = P_0 x + P_2 \sqrt{x} + \left(\frac{1-2P_0}{2} - \frac{P_2}{\sqrt{2}} \right) \cdot \sqrt[3]{2x}$$

- Parameters:

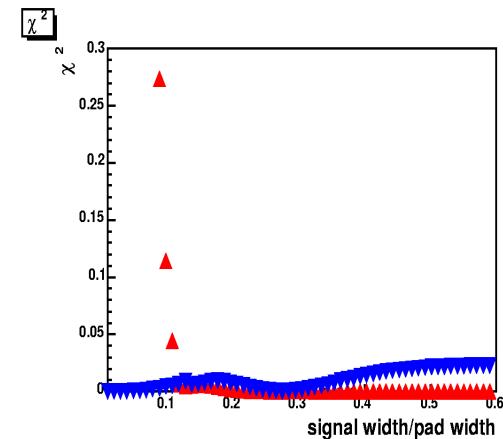
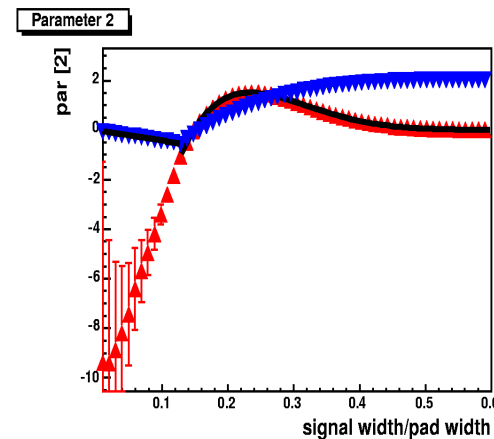
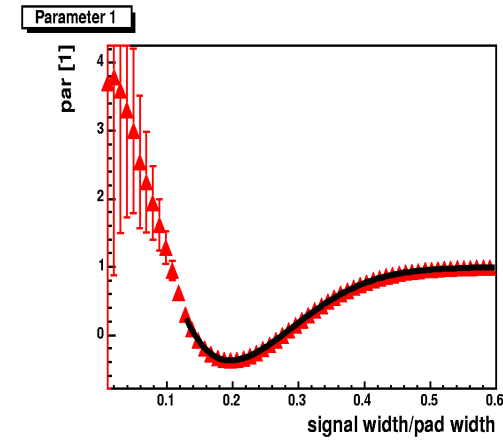
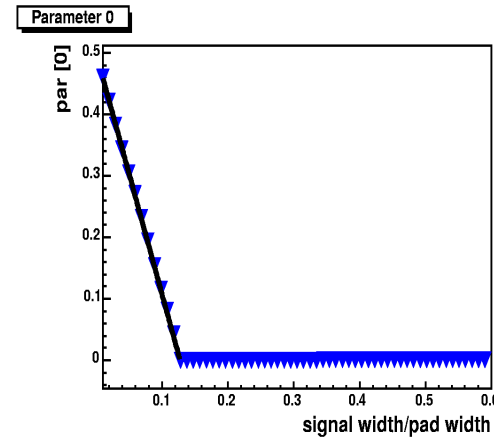
dependent on width σ

Fit F-functions to PRF

functions for many widths

to get P_i for many widths

→ fit appropriate polynomials to the parameter curves



$$P_{0,flat}(\sigma) = a_{01} \cdot ((1 - \sigma)/a_{00})$$

$$P_{1,noflat}(\sigma) = a_{15}\sigma^5 + a_{14}\sigma^4 + a_{13}\sigma^3 + a_{12}\sigma^2 + a_{11}\sigma + a_{10}$$

$$P_{2,flat}(\sigma) = a_{26}\sigma$$

$$P_{2,noflat}(\sigma) = a_{25}\sigma^5 + a_{24}\sigma^4 + a_{23}\sigma^3 + a_{22}\sigma^2 + a_{21}\sigma + a_{20}$$

→ polynomials implemented in Software; needed input: diffusion and defocussing coefficients to calculate width for given Z

Pad Response Correction

- To apply correction:
- Calculate width of hit **on the pad plane** from Z position (by using values from Magboltz):

$$\sigma = \sqrt{D z + \sigma_0}$$

	P5		TDR	
B (T)	D (mm) 10 ⁻⁴	σ_0 (mm ²)	D (mm) 10 ⁻⁴	σ_0 (mm ²)
0	571	0.288	202	0.180
1	24.05	0.227	34.1	0.142
2	7.24	0.190	11.5	0.110
4	1.92	0.140	3.00	0.070

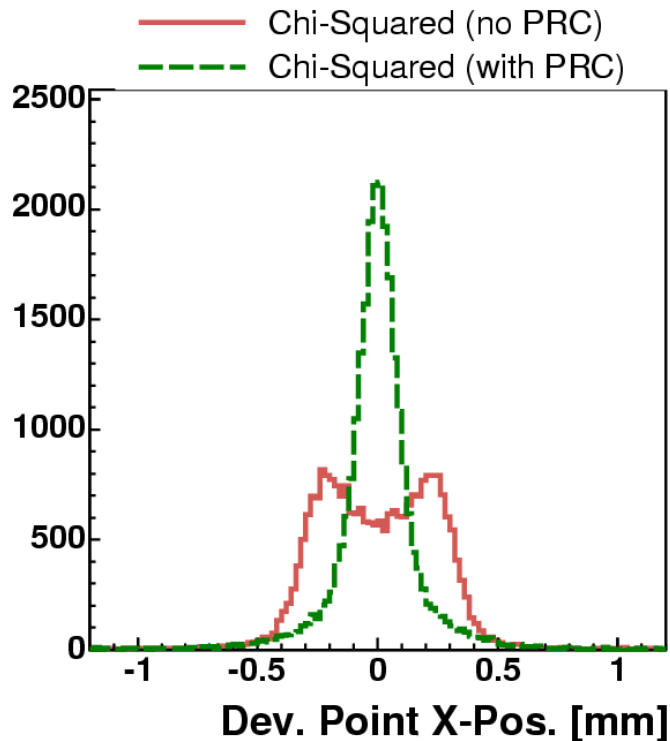
- Use this width to calculate the parameters P_0 , P_1 and P_2 (and decide which function to use: “flat” or “noflat”)
- Use the pad response to correction function to calculate the “real” position from the measured position (from Center of Gravity method)
- If the signal is only on one pad or in the flat region: no correction possible, Hit gets assigned the coordinate of the center of the pad

Performance of Correction

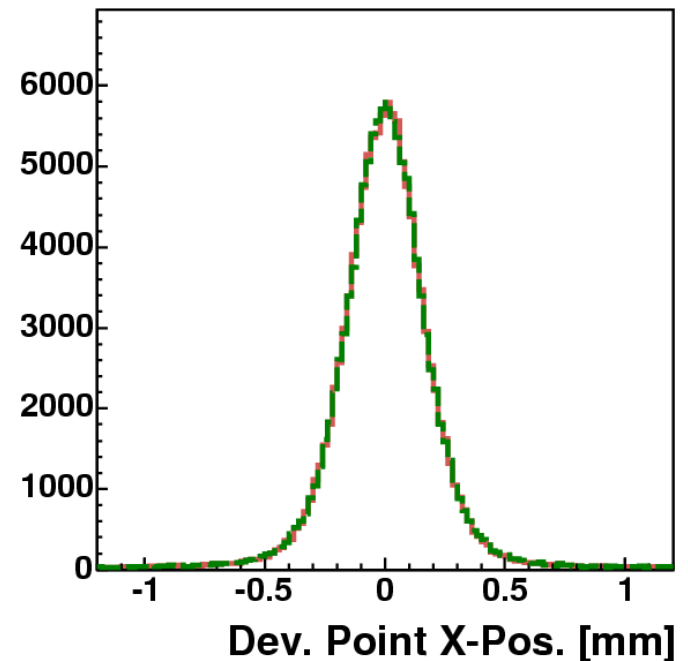
- Use of Pad Response Correction in the point (Hit) reconstruction leads to a significant improvement

Deviation: hit position \leftrightarrow Monte Carlo track
Monte Carlo Data: 2T, P5 gas, staggered pad layout

a) Z = 0 - 100mm

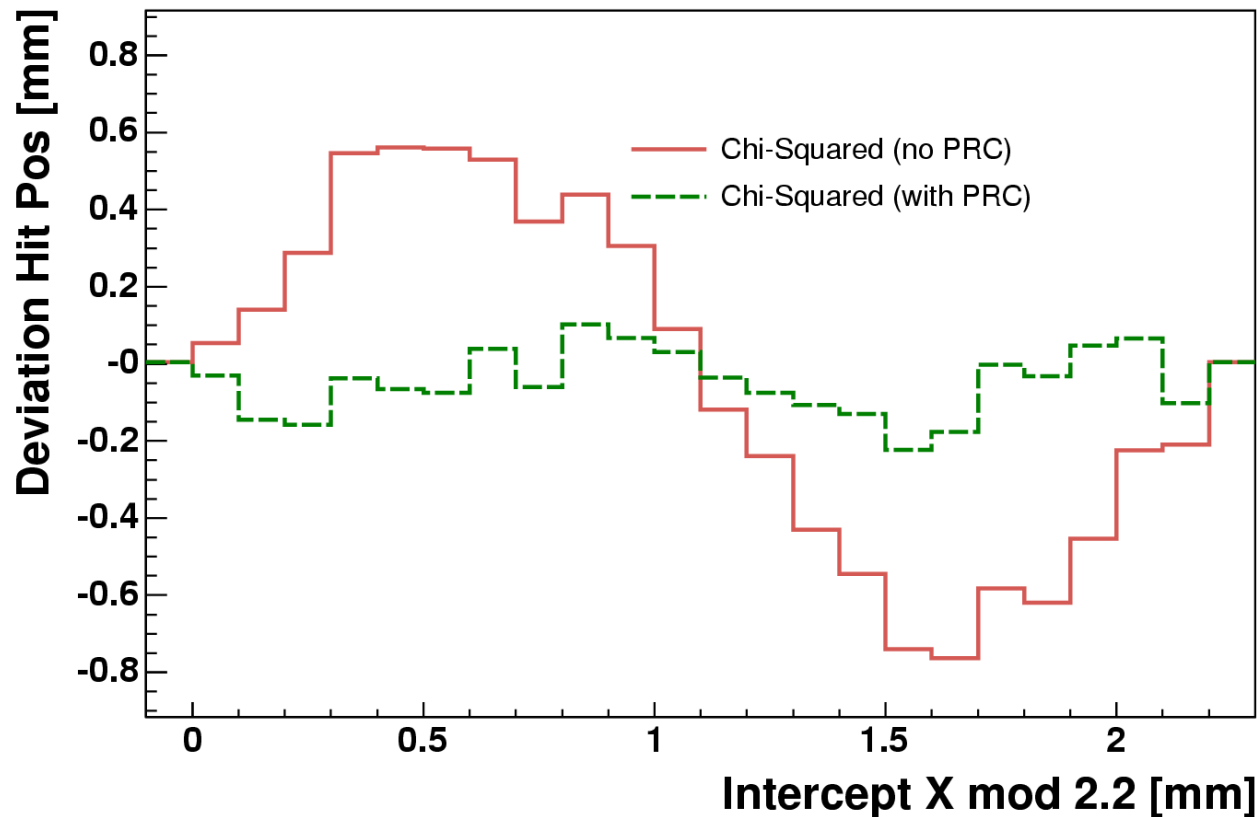


b) Z = 500 - 600mm



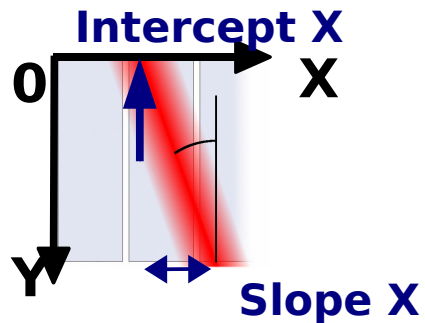
Performance of the Correction

- Deviation of the reconstructed Hit position from the Monte Carlo track position
- Plotted in dependency on the location of the Monte Carlo track on the pad

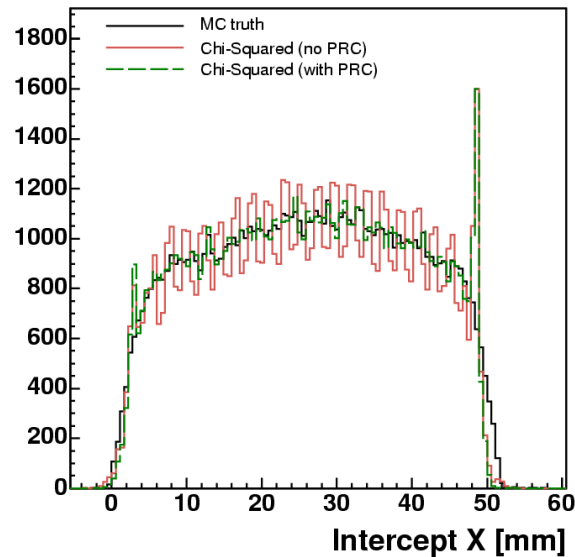


Performance of Correction

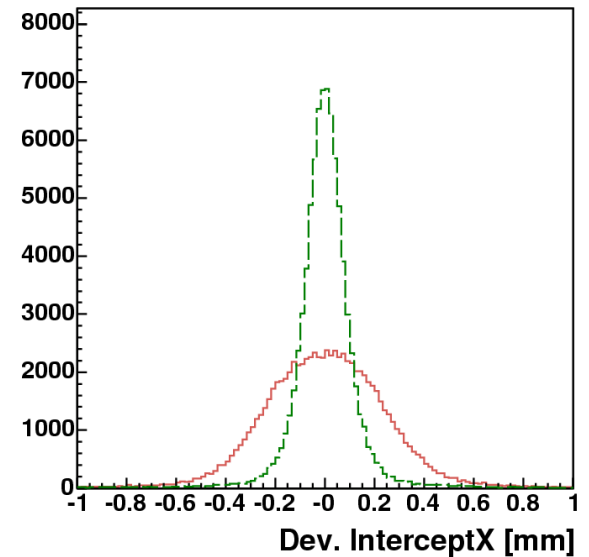
- Improvement of the reconstructed track parameters



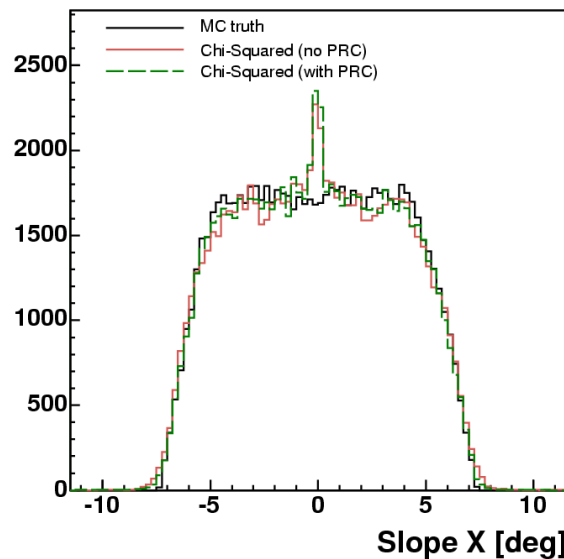
a) Intercept X



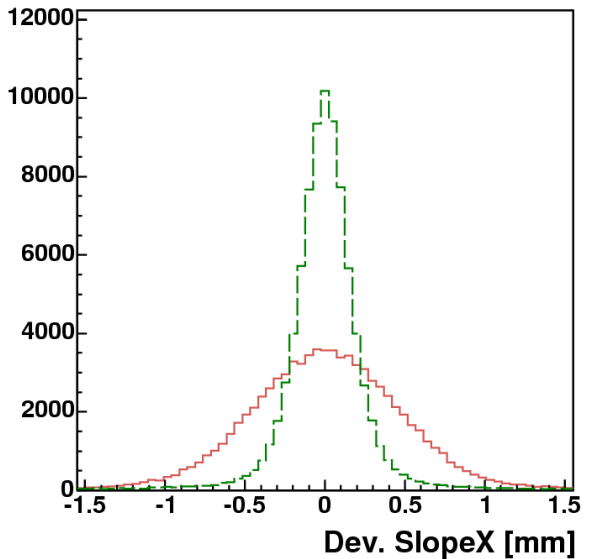
b) Deviation from MC Truth



a) Slope X



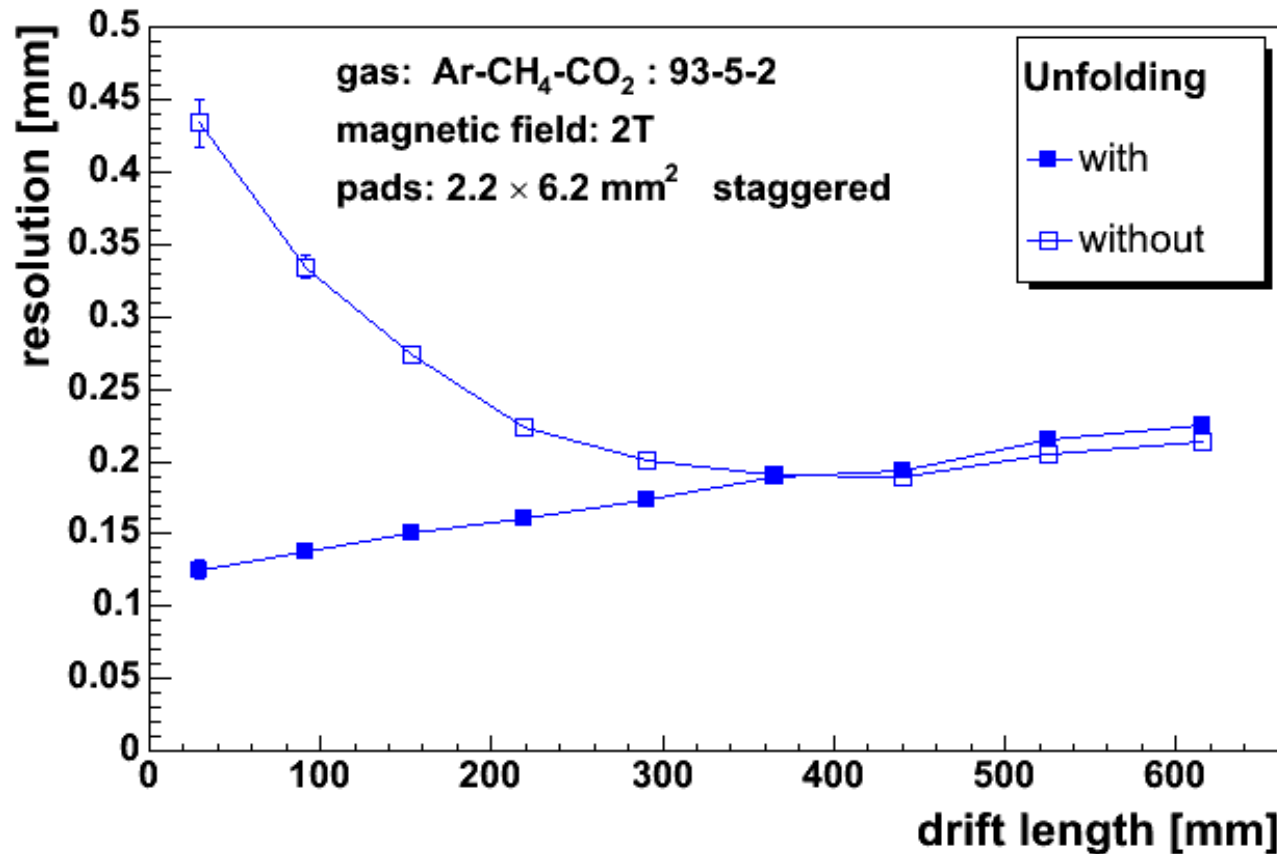
b) Deviation from MC Truth



Monte Carlo Data:
4T, P5, staggered pad
layout

Resolution with Correction

- Use of Pad Response Correction leads to a significant improvement of the point resolution calculation for a staggered pad layout



Point Resolution for staggered pad layout with and without PRC

Remarks

- Angle dependency not included; effect is small for small angles and usually then a significant improvement is reached by applying the PRC, although results are not “exact”
- The noise value you use to cut of the Gaussian distribution of the charge signal is a very important input. When changing this input value, the Pad Response Functions will change significantly
- The Global Fit method incorporates the Pad Response in its fit functions including the angle dependency