# COMPUTATION OF REALISTIC VECTOR POTENTIAL FOR LONG-TERM TRACKING 

DE LA RECHERCHE À L'INDUSTRIE


High
Luminosity LHC


CEA - Saclay

## ABELE SIMONA

Outline

- introduction;
- theoretical aspect of the problem;
- implementation of the code;
- test;
- application to realistic quadrupole;
- general view of the interface with SixTrack ${ }^{1}$;


## INTRODUCTION

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To extend the discovery potential of LHC it's planned to increase its luminosity (rate of collision) by a factor of 10 beyond the original design value (from 300 to $3000 \mathrm{fb}^{-1}$ ).


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Increase luminosity $=$ Reduce size of the beam at the IP $\Rightarrow$ Increase size of the beam in the last triplet, increase crossing angle
$\Rightarrow$ Bigger magnets mechanical aperture $\Rightarrow$ More non-linear effects

Magnetic Field Nonlinearities

The magnetic field $\vec{B}$ in a quadrupole can be written as a Fourier series:

$$
\begin{equation*}
\vec{B}(\rho, \varphi, z)=\sum_{m} \vec{B}_{m}(\rho, z) \sin (m \varphi)+\vec{A}_{m}(\rho, z) \cos (m \varphi) \tag{1}
\end{equation*}
$$

the coefficients of sinus and cosine are called respectively normal and skew harmonics.

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the coefficients of sinus and cosine are called respectively normal and skew harmonics.
So far the effect of a quadrupole over positions and momenta of the particles was modelized using averaged quantities over the longitudinal axis $z$.
With nonlinearities we refers to the effects caused by the harmonics of order bigger then 2 and to the ones caused by the non-uniformity of the harmonics along $z$.

The field at the sides of the quadrupole is called Fringe Field which adds significant non-linear contributions, as shown in the article of [AV Bogomyagkov et al.].


During the fourth HiLumi meeting M. Giovannozzi has shown that the error done in the final triplet ("Inner-Triplet", IT, a sequence of four quadupoles) before the interaction point has the biggest influence over the DA.

in
IT_errortable_v66_4, D1_errortable_v1_spec, D2_errortable_v5_spec (b2=0), Q4_errortable_v1_spec, Q5_errortable_v0_spec

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## OBJECTIVES

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Certain codes, like the one of [T. Pugnat], utilize the Hamiltonian of the system, built from the magnetic vector potential, in order to take into account the $z$ dependence and the effect of the Fringe Field.

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Certain codes, like the one of [T. Pugnat], utilize the Hamiltonian of the system, built from the magnetic vector potential, in order to take into account the $z$ dependence and the effect of the Fringe Field. On the other hand the designers of magnets or measurements can provide the values of the magnetic field or of the harmonics sampled on different types of grid.

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Therefore these are the objectives:

- Provide an accurate description of the magnetic vector potential starting from the harmonics of from the magnetic field;

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Therefore these are the objectives:

- Provide an accurate description of the magnetic vector potential starting from the harmonics of from the magnetic field;
- Provide it in a form that allows a fast tracking procedure, in particular in a polynomial form:

$$
\vec{A}(x, y, z)=\sum_{i, j} \vec{a}_{i, j}(z) x^{i} y^{j}
$$

## THEORETICAL PROBLEM

Framework

Theoretical problem

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Electromagnetic stationary field, no currents, no charges, vacuum.

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$$
\text { Maxwell equations } \Rightarrow \begin{cases}\vec{\nabla} \cdot \vec{E}=0 & \vec{\nabla} \times \vec{E}=0 \\ \vec{\nabla} \cdot \vec{B}=0 & \vec{\nabla} \times \vec{B}=0\end{cases}
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$$

$\vec{B}$ can be expressed using a scalar potential $\vec{B}=\vec{\nabla} \psi$ or a vector potential $\vec{B}=\vec{\nabla} \times \vec{A}$

$$
\begin{aligned}
& \vec{\nabla} \cdot \vec{B}=0 \Rightarrow \Delta \psi=0 \\
& \vec{\nabla} \psi=\vec{B} \Rightarrow \vec{\nabla} \psi=\vec{\nabla} \times \vec{A}
\end{aligned}
$$

Procedure

# Magnetic Field 

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Magnetic Field $\rightarrow$ Harmonics

Procedure

## Tests

Magnetic Field $\rightarrow$ Harmonics $\rightarrow$ Gradients

The generalized gradients are functions which depend only on the longitudinal coordinate $z: C_{m}^{[n]}(z) n, m \in \mathbb{N}$.

Procedure

## Tests

Magnetic Field $\rightarrow$ Harmonics $\rightarrow$ Gradients $\rightarrow$ Vector Potential

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## Tests

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To compute the harmonics it's necessary to compute a Fourier Integral over a circumference.


Depending on the grid an interpolation could be needed to provide the values of the field on the circle.

## Generalized Gradients

Theoretical problem

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If we:

- consider the magnetic scalar potential $\psi$ expressed in cylindrical coordinates (as the structure of the quadrupole suggests);


## Generalized Gradients

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- consider the magnetic scalar potential $\psi$ expressed in cylindrical coordinates (as the structure of the quadrupole suggests);
- expand $\psi$ in Fourier series on $\phi$ and in Fourier Transform on $z$ we can obtain a general solution for $\Delta \psi=0$ which involves $I_{m}$;


## Generalized Gradients

If we:

- consider the magnetic scalar potential $\psi$ expressed in cylindrical coordinates (as the structure of the quadrupole suggests);
- expand $\psi$ in Fourier series on $\phi$ and in Fourier Transform on $z$ we can obtain a general solution for $\Delta \psi=0$ which involves $I_{m} ;$
From this general solution and the harmonics at a specific radius it's possible to compute the generalized gradients using the following formula:

$$
C_{m}^{[n]}(z)=\frac{i^{n}}{2^{m} m!} \frac{1}{\sqrt{2 \pi}} \int_{-\infty}^{+\infty} \frac{k^{m+n-1}}{I_{m}^{\prime}\left(R_{a n} k\right)} \widetilde{B}_{m}\left(R_{a n}, k\right) e^{i k z} d k
$$

## Vector potential

Using the generalized gradients, the relation $\vec{\nabla} \times \vec{A}=\vec{\nabla} \psi$ and changing the coordinates from cylindrical to Cartesian the magnetic vector potential can finally be computed in the desired form:

$$
A_{x}=\sum_{m=0}^{+\infty} \sum_{\ell=0}^{+\infty} \sum_{p=0: 2: m} \sum_{q=0}^{\ell} \frac{1}{m} \frac{(-1)^{\ell} m!}{2^{2 \ell \ell}(\ell+m)!} C_{m}^{[2 \ell+1]}(z)\binom{m}{p}\binom{\ell}{q} i^{p} x^{m-p+2 \ell-2 q+1} \quad y^{p+2 q}
$$

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& \vec{A}=\begin{array}{llll}
\sum_{i, j} & \vec{a}_{i, j}(z) & x^{i} & y^{j}
\end{array}
\end{aligned}
$$

IMPLEMENTATION

## Evolution of the code



## Evolution of the code

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## C CODE

- Only Cartesian grid
- Hermite spline for interpolation
- Trapeze method for Fourier Integrals



## Evolution of the code

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## C CODE <br> OCTAVE SCRIPT

- Only Cartesian grid
- Hermite spline for interpolation
- Trapeze method for Fourier Integrals
- Filon Spline formula for Fourier Integrals

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## C CODE

- Only Cartesian grid
- Hermite spline for interpolation
- Trapeze method for Fourier Integrals



## C++ CODE

- Configurable without recompilation
- Computational time reduced
- Optimized output file
- Modular structure

Magnetic grid type

- Cartesian
- Cylindrical


## OCTAVE SCRIPT

- Filon Spline formula for Fourier Integrals


Fourier Integrals methods

- Filon Spline
- Newton-Cotes
- ...

Interpolation methods

- Hermite splines
- ...


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A modular structure allows to easily implement new methods and types of grid and to compare them at runtime.


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Cartesian grid


Subdivisions of the circle[-]

Cylindrical grid


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Cartesian grid


Cartesian grid


Subdivisions of the circle[-]

$$
\left\lvert\, \begin{array}{|l|l|}
-B_{2}^{T r}-B_{6}^{T r}-B_{10}^{T r}-B_{14}^{T r} \\
\cdots \cdots B_{2}^{S i} \cdots \cdots \cdots B_{6}^{S i} \cdots \cdots \cdots B_{10}^{S i} \cdots \cdots B_{14}^{S i} \\
--B_{2}^{F S}--B_{6}^{F S}--B_{10}^{F S}-\cdots B_{14}^{F S}
\end{array}\right.
$$

Cylindrical grid


Cylindrical grid


Subdivisions of the circle[-]

| $-B_{2}^{T r}$ | $-B_{6}^{T r}-B_{10}^{T r}-B_{14}^{T r}$ |  |
| :--- | :--- | :--- |
| $\cdots \cdots B_{2}^{S i}$ | $\cdots \cdots \cdots B_{6}^{S i}$ | $\cdots \cdots \cdots B_{10}^{S i}$ |
| $\cdots \cdots$ | $B_{14}^{S i}$ |  |
| $--B_{2}^{F S} \cdots-B_{6}^{F S} \cdots-B_{10}^{F S} \cdots-B_{14}^{F S}$ |  |  |

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$$
C_{m}^{[n]}(z)=\frac{i^{n}}{2^{m} m!} \frac{1}{\sqrt{2 \pi}} \int_{-\infty}^{+\infty} \frac{k^{m+n-1}}{I_{m}^{\prime}\left(R_{a n} k\right)} \widetilde{B}_{m}\left(R_{a n}, k\right) e^{i k z} d k
$$

Absolute Error


Relative Error


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$$
C_{m}^{[n]}(z)=\frac{i^{n}}{2^{m} m!} \frac{1}{\sqrt{2 \pi}} \int_{-\infty}^{+\infty} \frac{k^{m+n-1}}{I_{m}^{\prime}\left(R_{a n} k\right)} \widetilde{B}_{m}\left(R_{a n}, k\right) e^{i k z} d k
$$



Angular frequency samples[-]

Relative Error


Angular frequency samples[-]

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$$
B_{m}=\sum_{\ell=0}^{N D}(-1)^{\ell}(m+2 \ell) \frac{m!}{4^{\ell} \ell!(m+\ell)!} \rho^{m+2 \ell-1} C_{m}^{[2 \ell]}(z)
$$

The analytical harmonics are built with 20 derivatives


Absolute Error

Relative Error

## Application to a realistic quadrupole (1)

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Prototype for IT of HL-LHC


The magnetic field is provided on a Cartesian grid with a step of 0.003 m ( $x$, $y, z$ ). Both the harmonics and the gradients are computed.

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Prototype for IT of HL-LHC



The magnetic field is provided on a Cartesian grid with a step of 0.003 m ( $x$, $y, z$ ). Both the harmonics and the gradients are computed.

| Harmonic | $E_{m}^{L^{2}, A}$ | $E_{m}^{L^{2}, R}$ | $E_{m}^{L^{\infty}, A}$ | $E_{m}^{L^{\infty}, R}$ |
| :--- | :---: | :---: | :---: | :---: |
| $B_{2}$ | $2.65479 \cdot 10^{-6}$ | $3.75942 \cdot 10^{-7}$ | $2.7754 \cdot 10^{-5}$ | $3.93021 \cdot 10^{-6}$ |
| $B_{6}$ | $2.93802 \cdot 10^{-7}$ | $2.53589 \cdot 10^{-6}$ | $3.20346 \cdot 10^{-6}$ | $2.76499 \cdot 10^{-5}$ |
| $B_{10}$ | $1.11986 \cdot 10^{-7}$ | $6.95825 \cdot 10^{-6}$ | $1.272 \cdot 10^{-6}$ | $7.90355 \cdot 10^{-5}$ |
| $B_{14}$ | $9.64632 \cdot 10^{-8}$ | $4.33002 \cdot 10^{-5}$ | $1.085 \cdot 10^{-6}$ | $4.8703 \cdot 10^{-4}$ |

The maximum absolute value is comparable with the one obtained by $[B$.
Dalena et al.].

* Courtesy of to S. Izquierdo Bermudez and E. Todesco.


## Application to a realistic quadrupole (2)



The normal and skew harmonics of a more detailed design, are provided with a $z$ step of 0.02 m . The presence of connectors on one side generates an asymmetry and skew harmonics.


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| Harmonic | $E_{m}^{L^{2}, A}$ | $E_{m}^{L^{2}, R}$ | $E_{m}^{L^{\infty}, A}$ | $E_{m}^{L^{\infty}, R}$ |
| :--- | :---: | :---: | :---: | :---: |
| $B_{2}$ | $2.73535 \cdot 10^{-7}$ | $4.12566 \cdot 10^{-8}$ | $1.3563 \cdot 10^{-6}$ | $2.04567 \cdot 10^{-7}$ |
| $B_{6}$ | $7.65192 \cdot 10^{-9}$ | $7.93646 \cdot 10^{-8}$ | $3.61656 \cdot 10^{-8}$ | $3.75105 \cdot 10^{-7}$ |
| $B_{10}$ | $8.69318 \cdot 10^{-11}$ | $6.34951 \cdot 10^{-9}$ | $4.31059 \cdot 10^{-10}$ | $3.14846 \cdot 10^{-8}$ |
| $B_{14}$ | $5.47241 \cdot 10^{-12}$ | $2.88597 \cdot 10^{-9}$ | $2.37895 \cdot 10^{-11}$ | $1.25458 \cdot 10^{-8}$ |
| $A_{2}$ | $1.60238 \cdot 10^{-9}$ | $4.62285 \cdot 10^{-8}$ | $1.09001 \cdot 10^{-8}$ | $3.14467 \cdot 10^{-7}$ |
| $A_{6}$ | $7.92291 \cdot 10^{-11}$ | $1.6105 \cdot 10^{-8}$ | $4.52242 \cdot 10^{-10}$ | $9.1928 \cdot 10^{-8}$ |

[^0]
## SixTrack IMPLEMENTATION

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- theoretical derivation of the method to compute the vector potential;
- translation in C++ and improving of C code and octave scripts;
- systematic testing of the methods;
- in collaboration with Thomas Pugnat, implementation in SixTrack of the tracking code;
- Harmonics: understand influence of the interpolating methods on various grids;
- Gradients: implement new stable methods of order higher than Trapeze that can also be used in the reconstruction of the harmonics;
- study error dependence on data noise;
- develop a symplectic integrator using an Hamiltonian without the paraxial approximation;
- study alternative symplectic integrators with respect to the one optimized by [ $T$. Pugnat];
- derive a transfer map in the case of a dipole;


## THANK YOU FOR YOUR ATTENTION

AV Bogomyagkov et al. "Analysis of the Non-Linear Fringe Effects of Large Aperture Triplets for the HL-LHC Project, IPAC 2013 (WEPEA049)". In: (2013).
B Dalena, O Gabouev, M Giovannozzi, R De Maria, RB Appleby, A Chancé, J Payet, and DR Brett. "Fringe fields modeling for the high luminosity LHC large aperture quadrupoles". In: (2014).

Thomas Pugnat. "Calcul d'une "carte de transport" réaliste pour particules chargées". In: (2015).


[^0]:    * Courtesy of S. Izquierdo Bermudez and E. Todesco.

