

# ***Lecture #2***

## ***Design Guide to Superconducting Magnet***

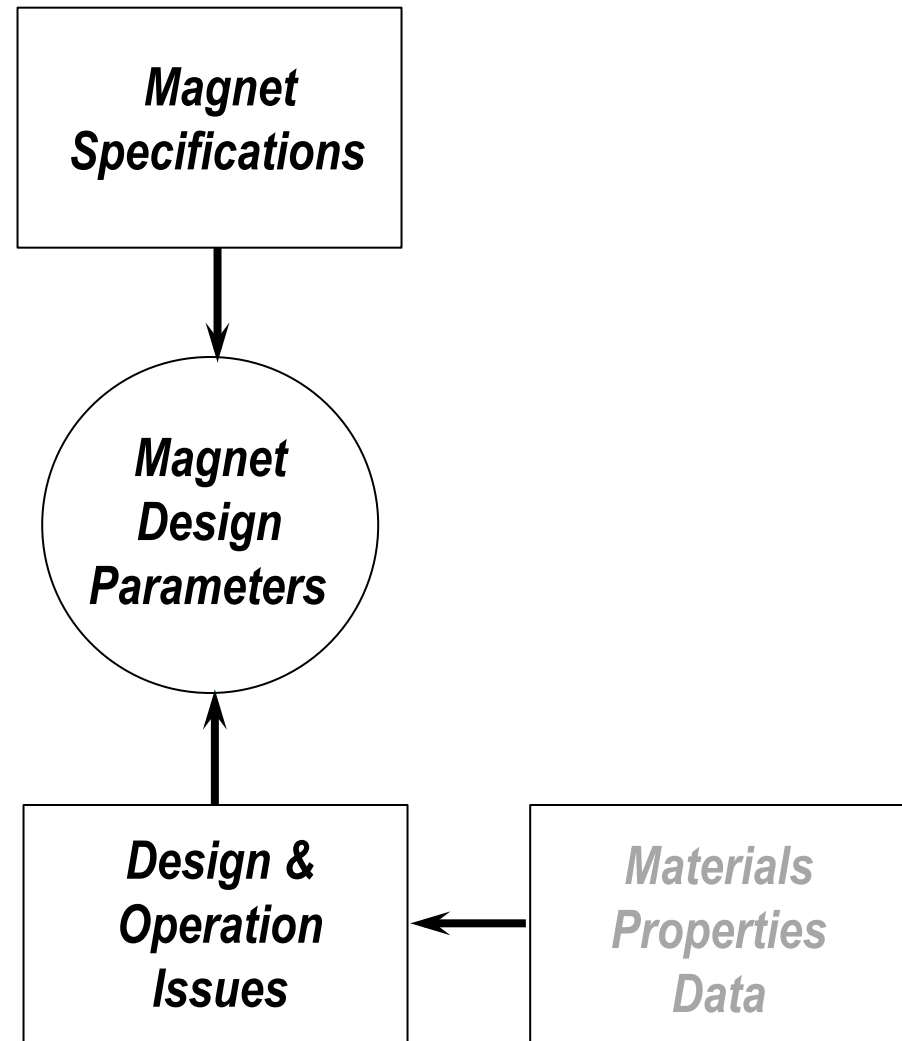
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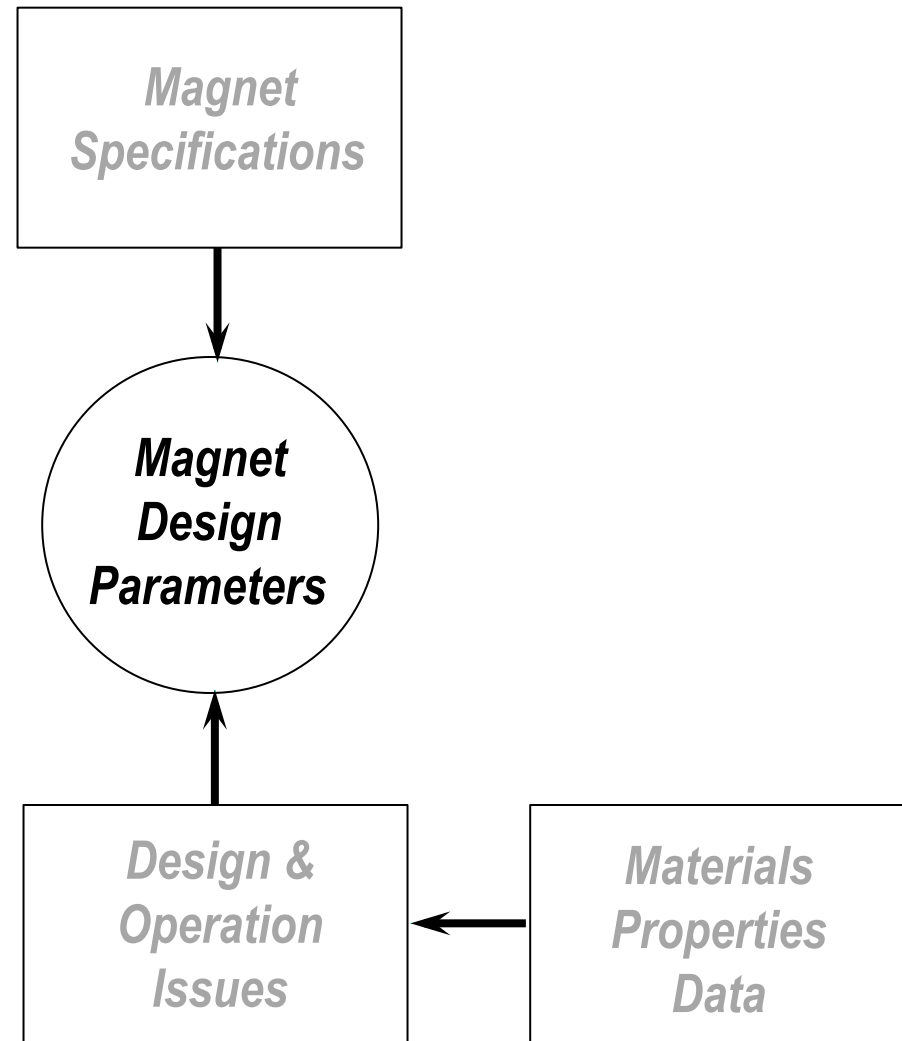
CEA Saclay

June 21, 2016

# Design Block Diagram for a Superconducting Magnet

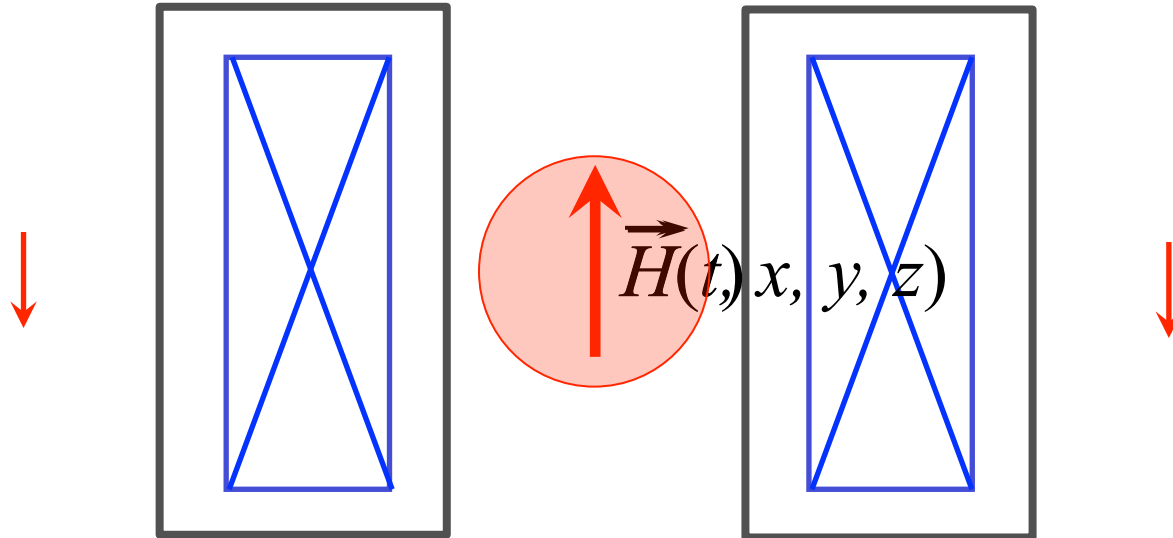


# Design Block Diagram for a Superconducting Magnet



# Magnet Specifications: 1—5

1. Center field vector: strength; direction—selected details in **Lecture #3**
2. Room-temperature bore: orientation; dimensions
3. Field temporal function: driven vs. persistent mode—if *constant*, temporal stability limit
4. Field spatial function: field error limits over, e.g., **10-cm Diameter Spherical Volume (DSV)**  
—**Topics 3** and **4** discussed a bit more later
5. Fringe field (strength space): **shielded** vs. **unshielded**



## Magnet Specifications: 2

### 2. Room-temperature (RT) bore; orientation; dimensions

- RT bore generally 20-50 mm greater than the innermost winding diameter—cryogenics
  - → 50 mm for  $\leq 4.2$ - K operation
  - → 20 mm for  $\gg 4.2$ -K operation
- Field orientation

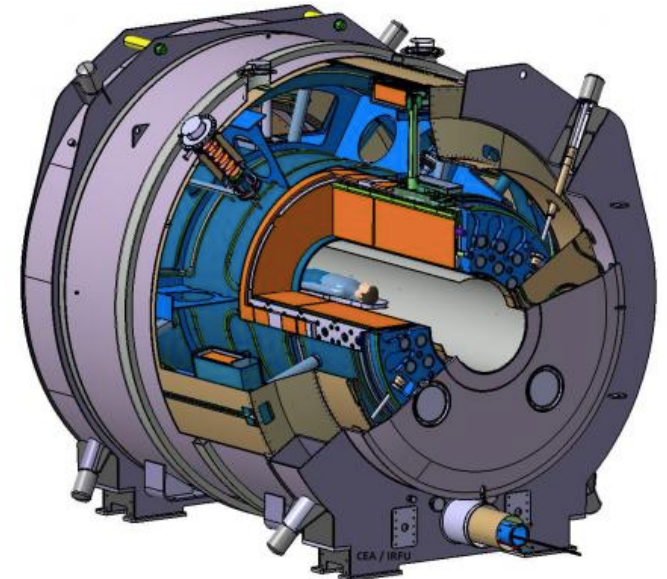
**Vertical:** Most research and NMR magnets

**Horizontal:** Most MRI magnets

- Mechanical and cryogenic issues challenging



930-MHz NMR magnet (NIMS, 2002)  
RT bore: 54 mm

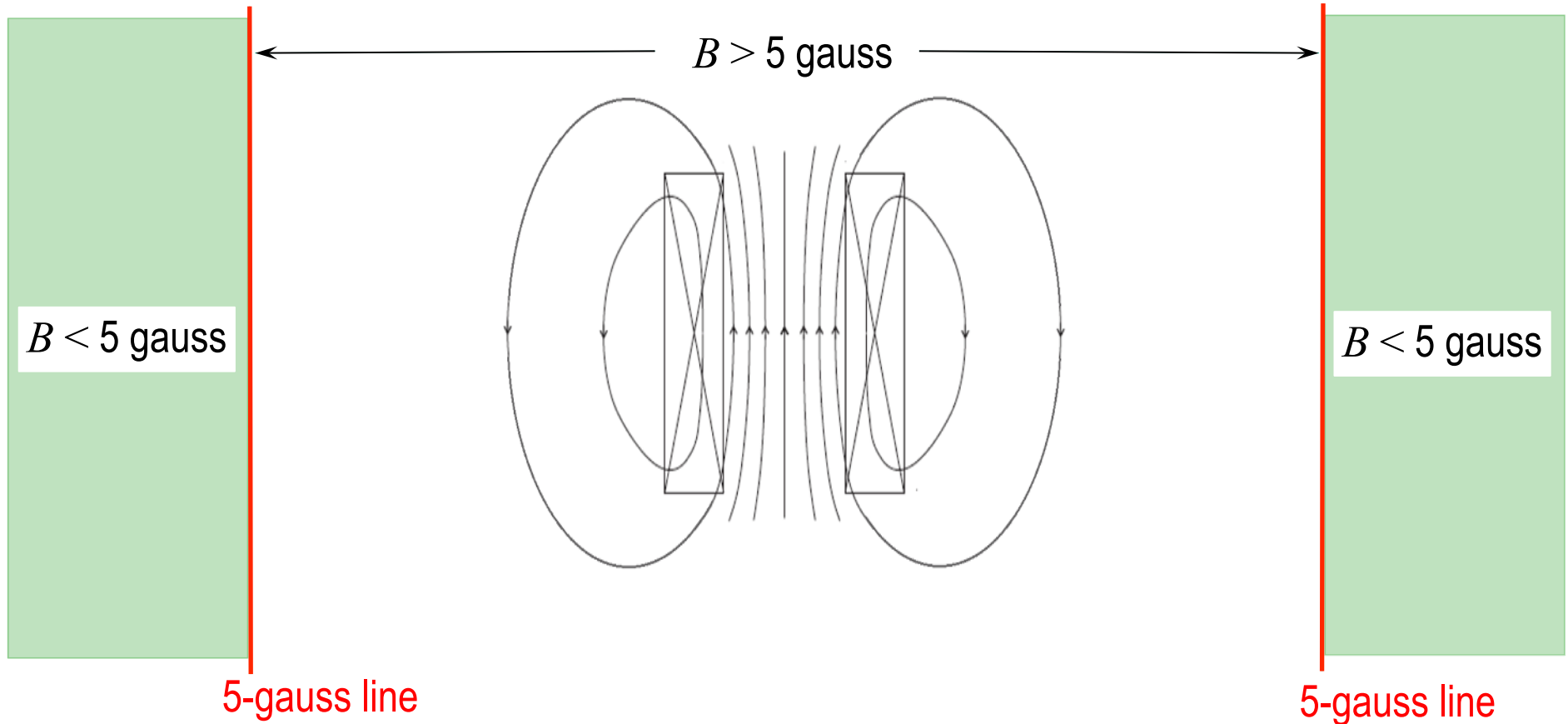


ISEULT MRI magnet (CEA, 2017)  
RT bore: 900 mm

# Magnet Specifications: 5

## 5. Fringe field (strength space): *shielded* vs. *unshielded*

### *Fringe Field in Unshielded Magnet*



- For safety (people, devices, equipment) & convenience, a 5-gauss line closest to the magnet

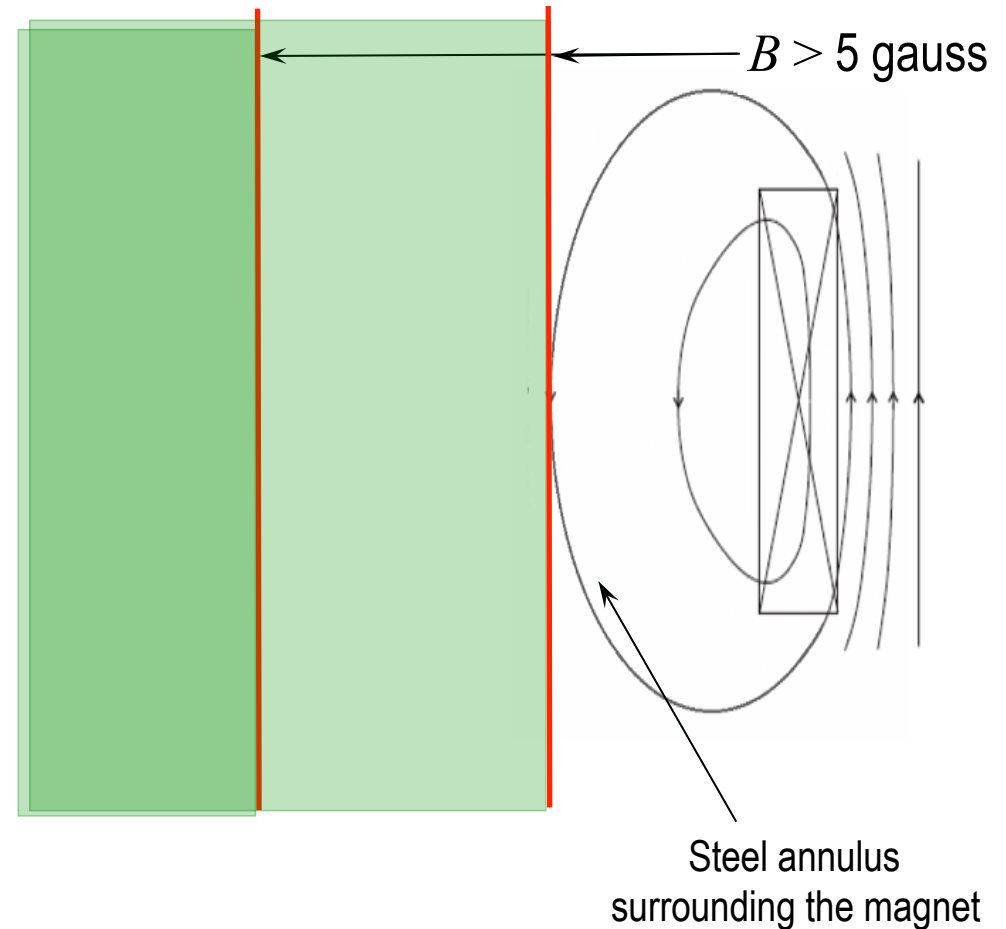
## Magnet Specifications: 5

### 5. Fringe field (strength space): *shielded* vs. *unshielded*

#### *Fringe Field in Passively Shield Magnet*

- Steel annulus an effective for passive shielding
- One ad often overlooked: it shields the magnet center from external magnet signals
- Big negative: can be *very massive*
  - ISEULT would have required a steel mass of 2000 tons

[Thierry Schild, CEA]



# Magnet Specifications: 5

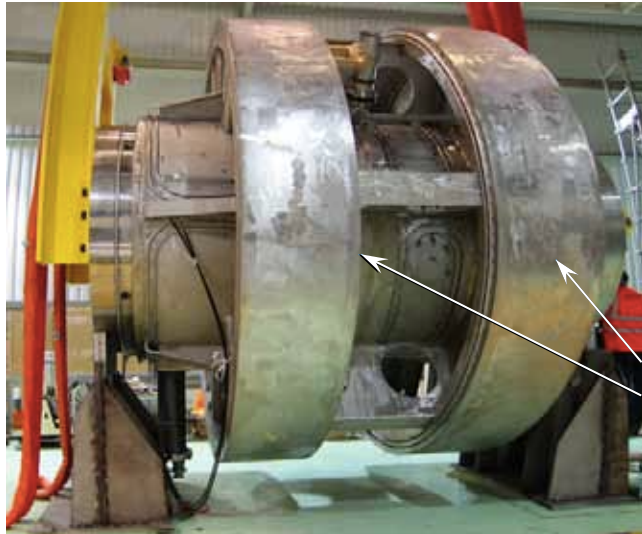
## 5. Fringe field (strength space): *shielded* vs. *unshielded*

### *Fringe Field in Actively-Shield Coil*

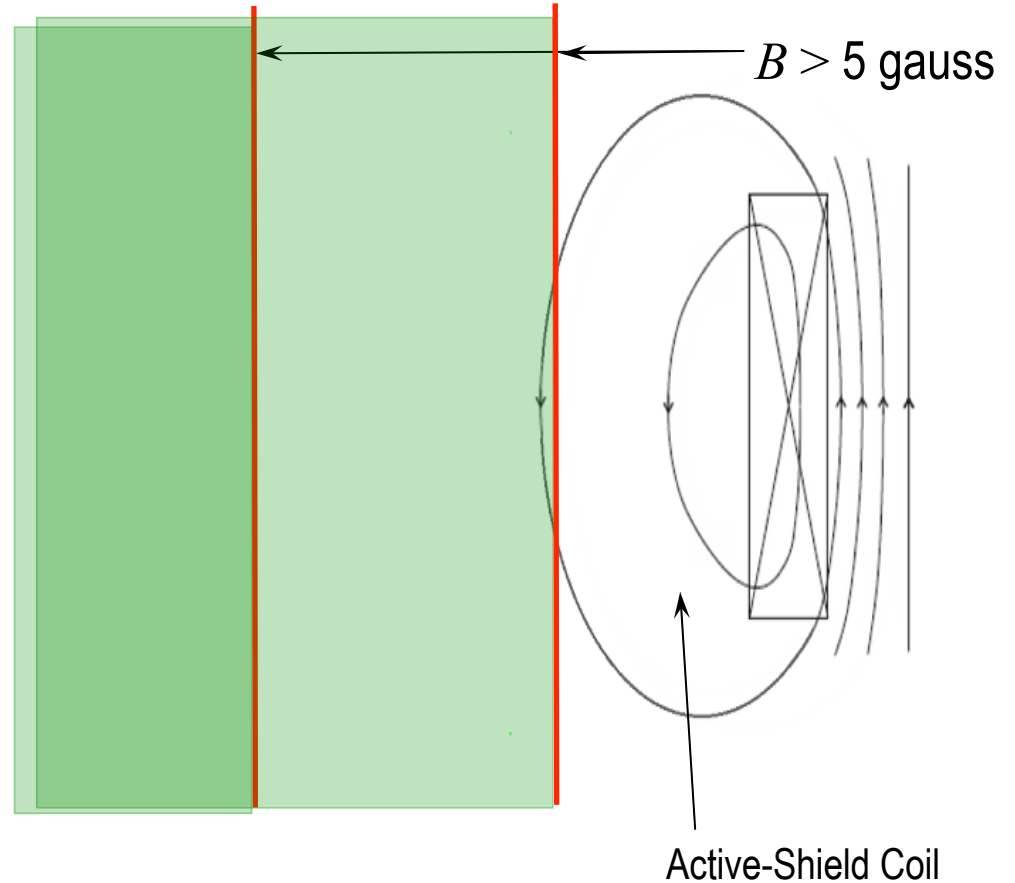
- Generally of superconducting
- Less massive than steel counterpart

### *Negatives*

- Subtract field from the center field
- Large interaction forces
- Enlarges the system overall size



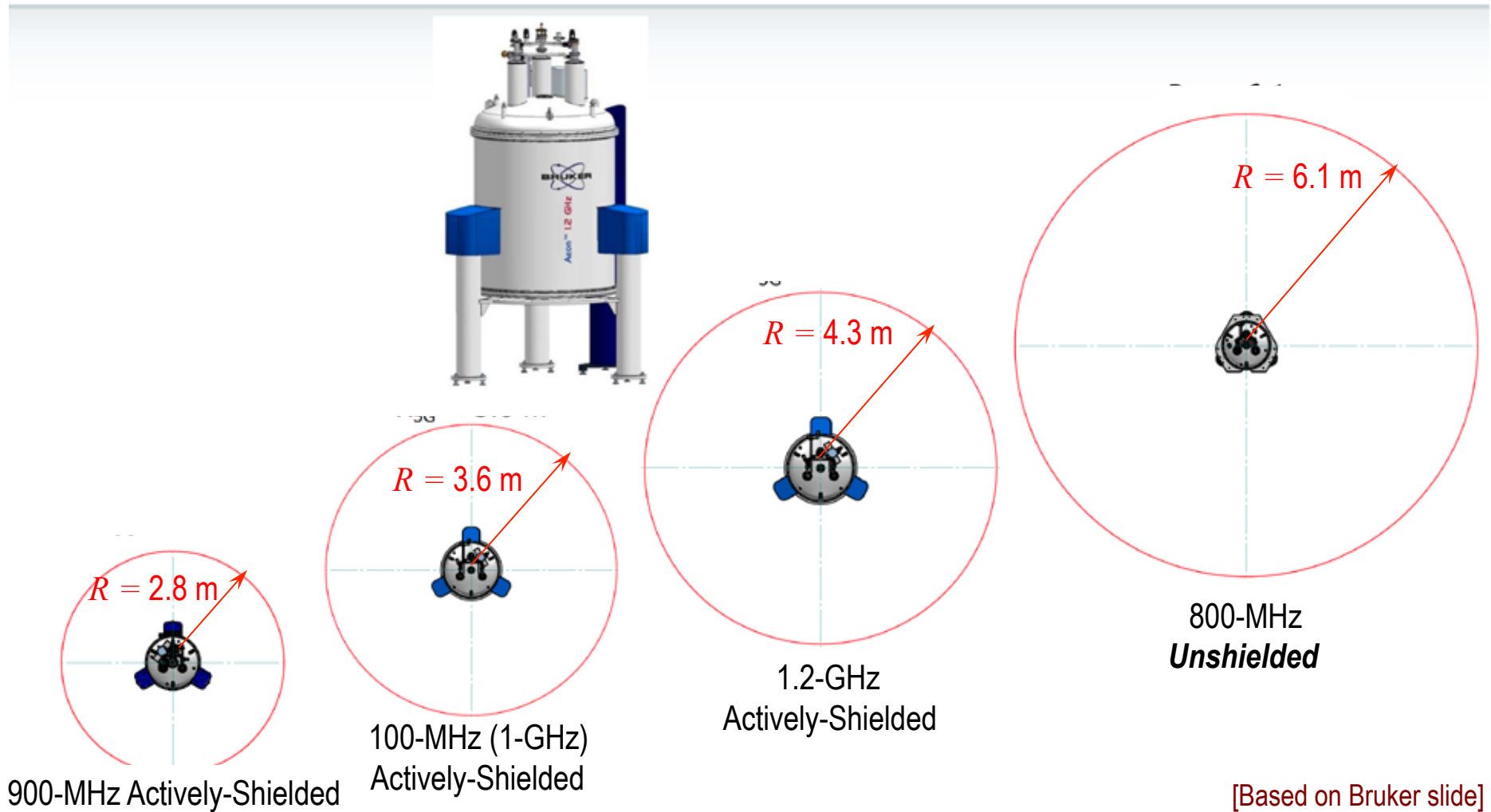
ISEULT active-shield coil pair  
[Alain Payn, CEA]



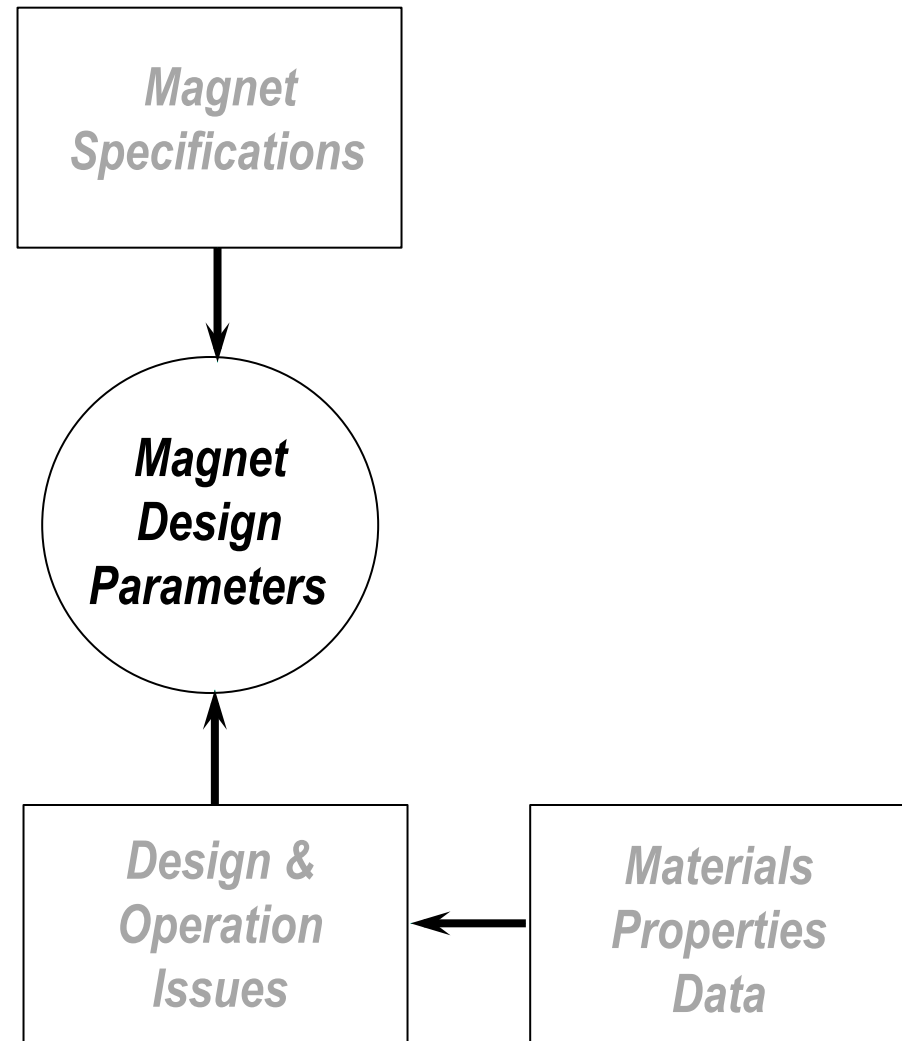


# Magnet Specifications: 5

## Bruker NMR Magnet 5-Gauss Lines



# Design Block Diagram for a Superconducting Magnet



# Magnet Design Parameters: Part 1

## 1. Superconductors (DC Magnets)

### NbTi

- To  $\sim 10$  T, 4.2 K: many superconducting magnets: *LHC*; most MRI magnets
- To  $\sim 12$  T,  $< 4.2$  K: *ISEULT*

### NbTi & Nb<sub>3</sub>Sn

- To  $\sim 18$  T, 4.2 K: high-field magnets
- To  $\sim 24$  T,  $< 4.2$  K: high-field magnets

### NbTi, Nb<sub>3</sub>Sn & Bi223 & REBCO

- To  $\sim 31$  T, 4.2 K: high-field magnets

### Bi223 & REBCO

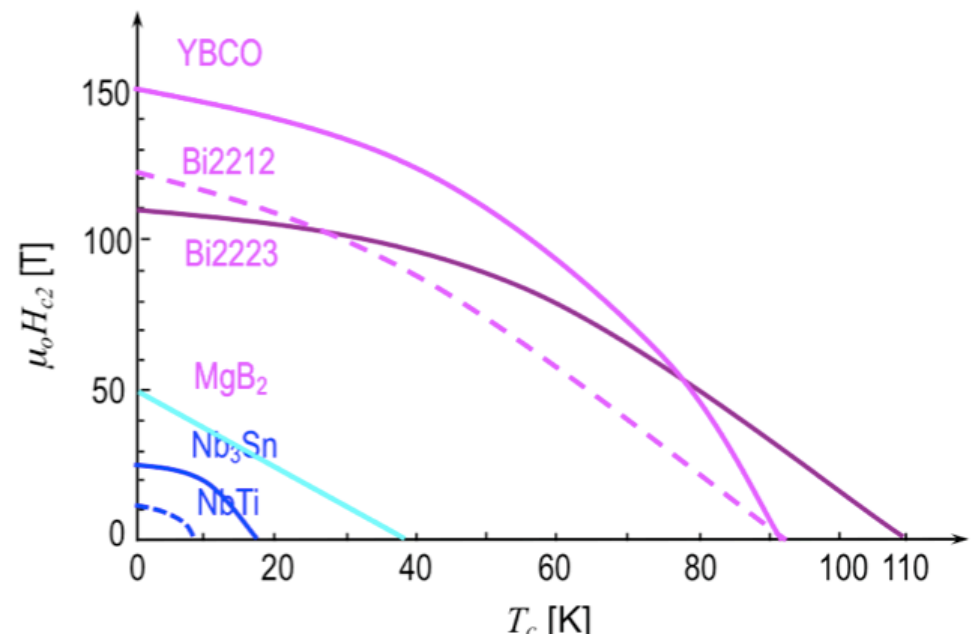
- $> 10$  K  $\rightarrow$  mostly replacing

### REBCO

- To 100 T, 4.2 K: technically feasible

### MgB<sub>2</sub>

- To  $\sim 3$  T,  $> 10$  K: *promising*

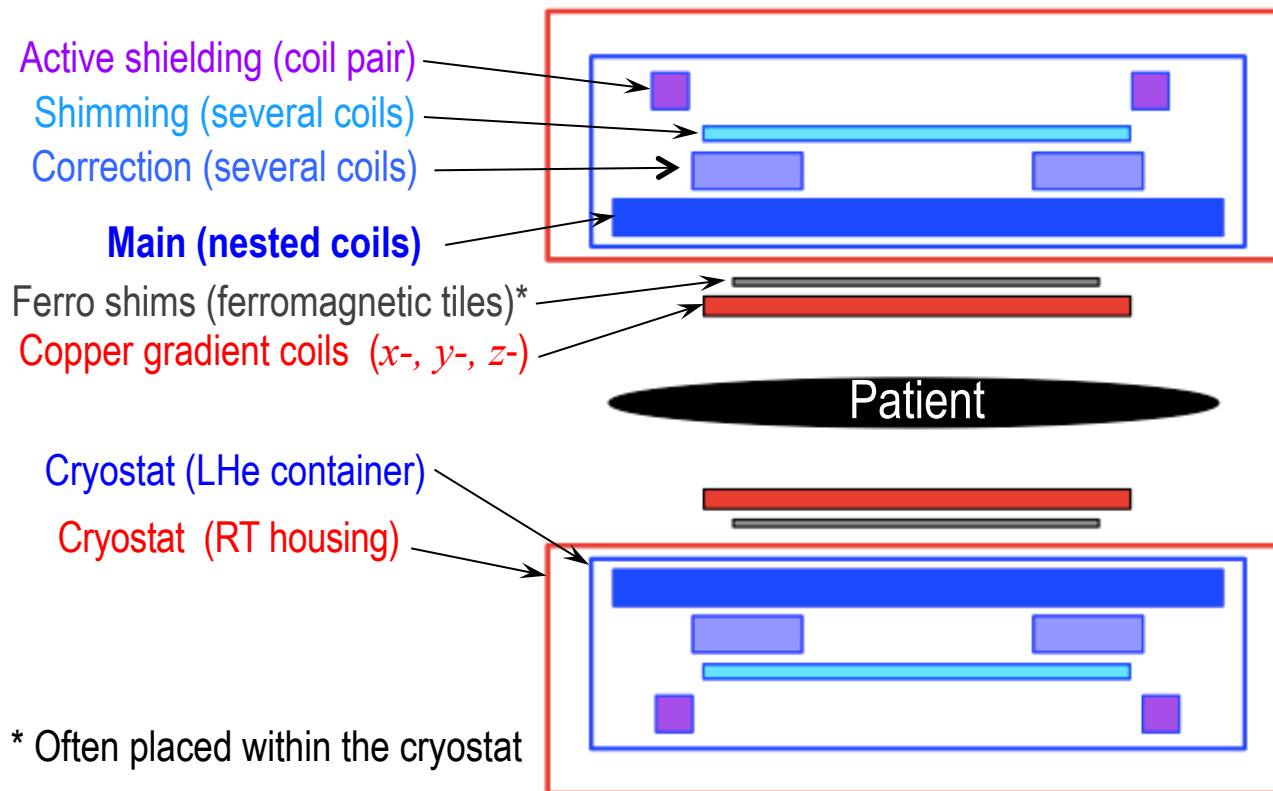


## Magnet Design Parameters: Part 2

### 2. Number of coils in the magnet;

Each coil: winding dimensions and # of turns; matrix metal-SC ratio; conductor length

### *A Typical Superconducting Magnet—Here MRI*



# Magnet Design Parameters: Part 3a

3a. Winding options: *layer* vs. *pancake*; epoxy-impregnated vs. none

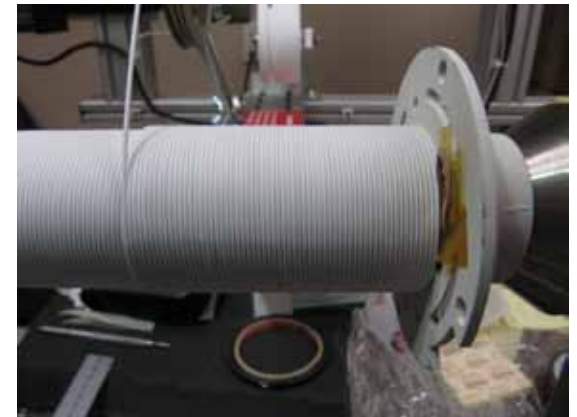
## Layer-Wound Coil

- Conductor, circular or rectangular sometimes tape, wound one turn a time on a plane (layer), and then to the next layer
- Dense winding pack, e.g., close-pack hexagonal formation



## Negatives

- Can require a long continuous length conductor, e.g., up to ~15 km
- Entire wire may become useless



[Ulf Trociewitz, NHMFL, 2016]



Cowindings between turns



[Youngjae Kim, NHMFL, 2016]

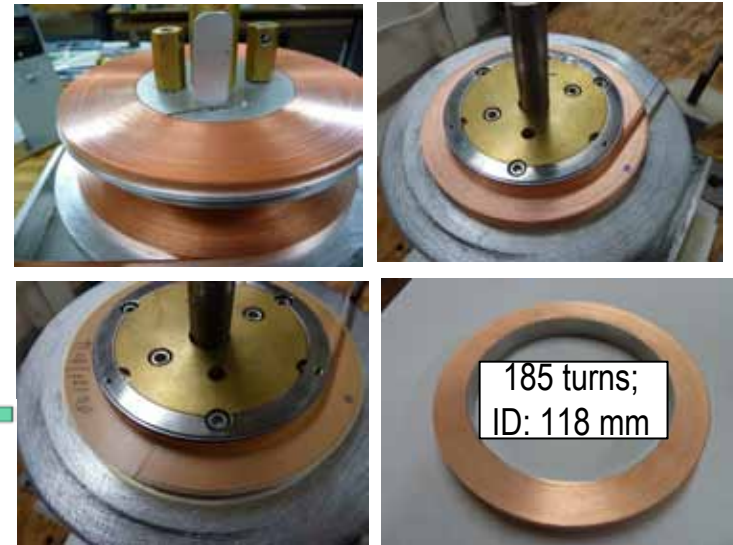
# Magnet Design Parameters: Part 3b

3b. Winding options: *layer* vs. *pancake*; epoxy-impregnated vs. none



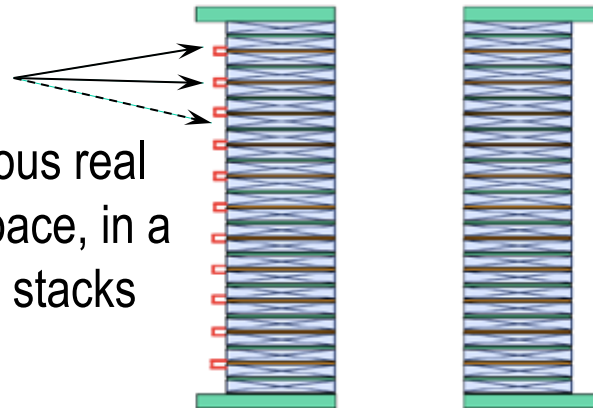
## Pancake & Double-Pancake Coil

- DP magnet: a stack(s) of DP coils
- Modular approach—many “identical” coils
  - QC easier: one DP coil at a time
  - Mishaps often confined to one DP coil



## Negatives

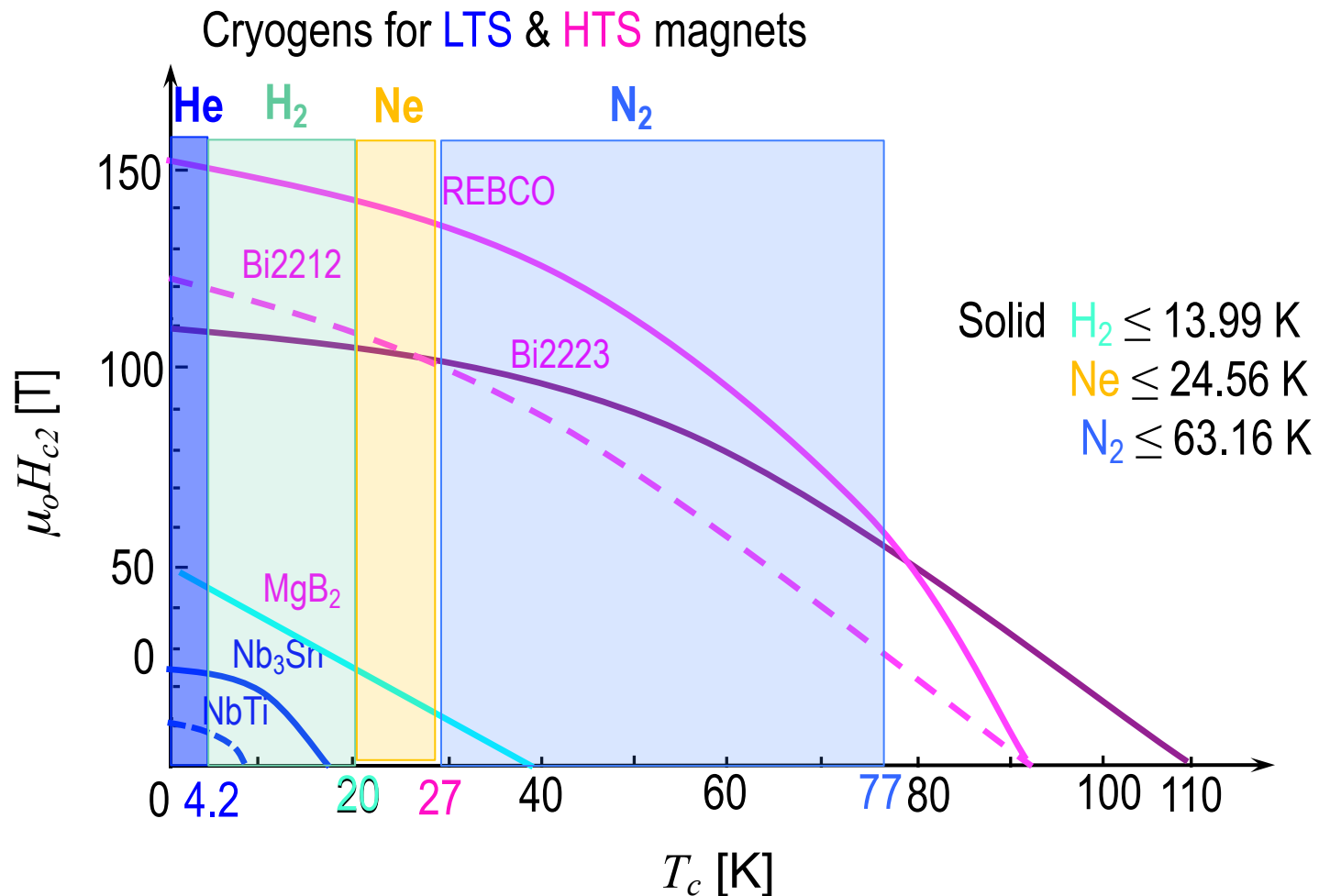
- Many DP-DP joints
- Joints take up precious real estate, i.e., radial space, in a magnet of many DP stacks
- Epoxy-impregnated vs. none:  
Discussed in **Lecture 4: Stability & Protection**



## Magnet Design Parameters: Parts 4—5a

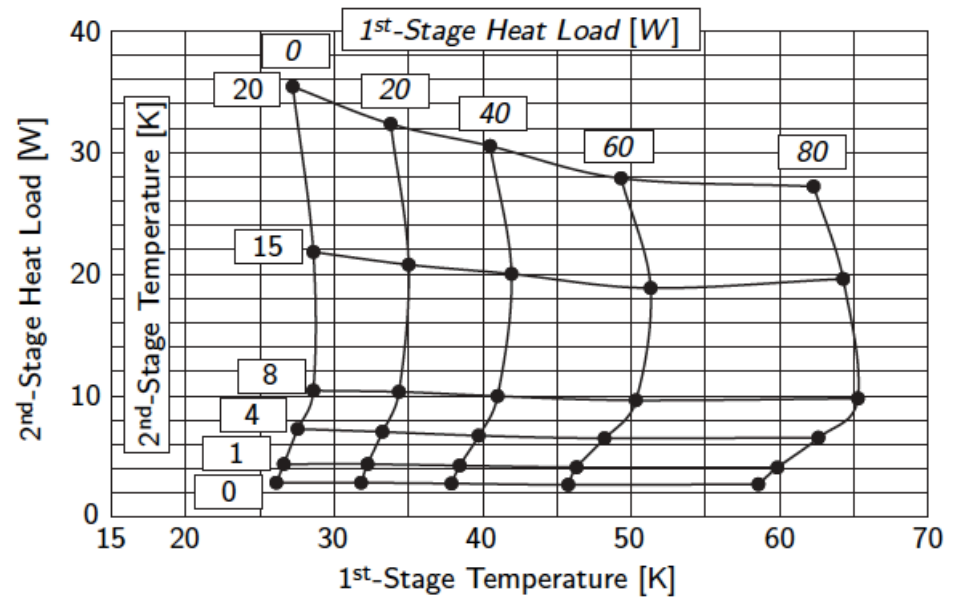
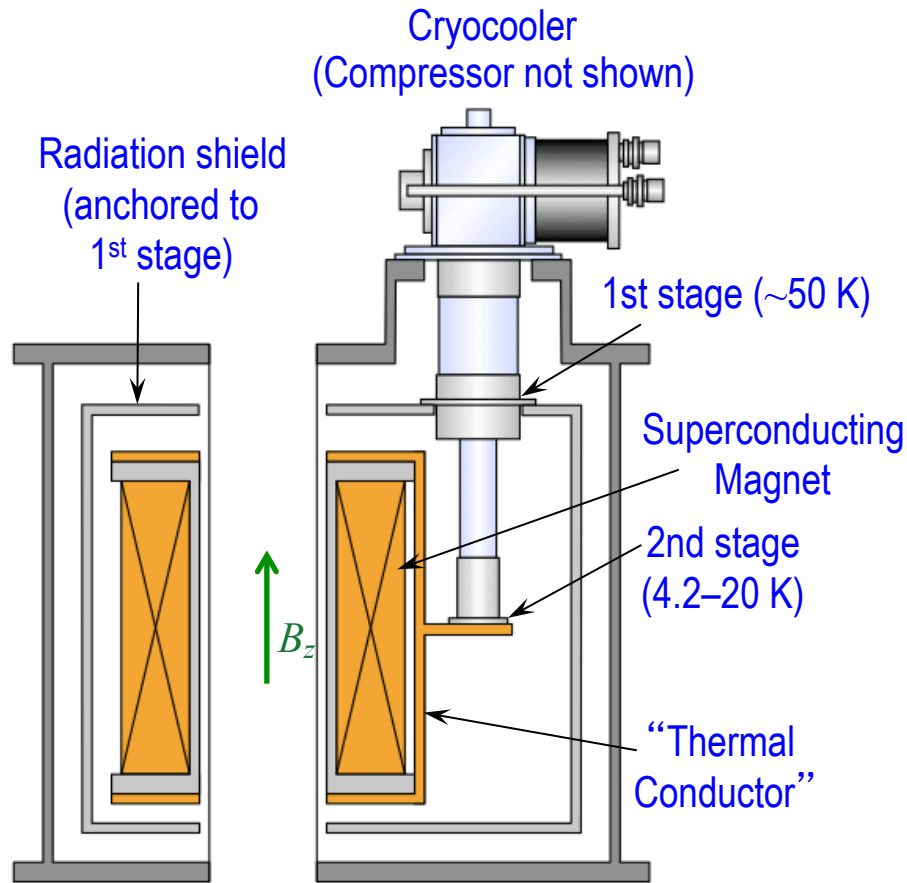
4. Adiabatic vs. cryostable winding: Discussed in **Lecture #4: Stability & Protection**

5a. Operating temperature → cooling: **cryogen** & cryocooler



# Magnet Design Parameters: Part 5b

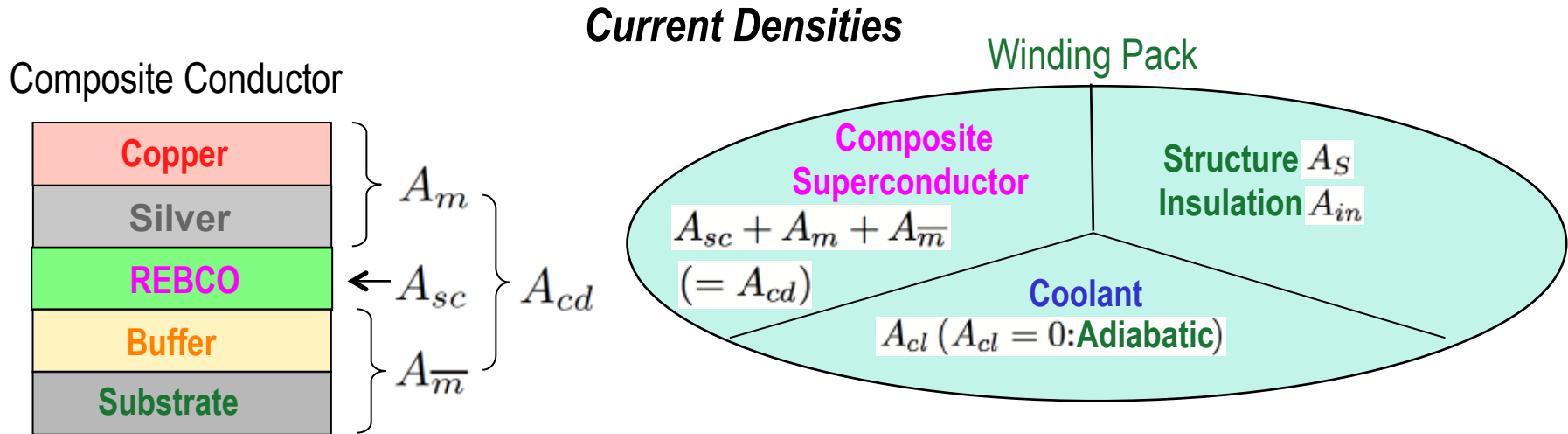
5b. Operating temperature → cooling: cryogen & **cryocooler**





# Magnet Design Parameters: Part 6

6. Operating current → overall & matrix metal



- $J_c = \infty$  ( $A_{sc} = 0$ )  
little impact on  $J_e$   
or  $\lambda J$

Current Density	Relevance	Definition
Critical, $J_c$	Material development	$\frac{I_c}{A_{sc}}$
Engineering, $J_e (= J_{cd})$	Conductor development	$\frac{I_c}{A_{cd}} = \frac{I_c}{A_{sc} + A_m + A_{\bar{m}}}$
Matrix, $J_m$	Stability & Protection	$\frac{I_{op}}{A_m}$
Overall, $\lambda J (= J_{overall})$	Magnet efficiency	$\frac{I_{op}}{A_{wd}} = \frac{I_{op}}{A_{cd} + A_S + A_{in} + A_{cl}}$

# Magnet Design Parameters: Part 7a

7a. Operating mode: **driven** vs. **persistent** → temporal stability

Driven: power supply; Persistent: joints, persistent-current switches, their locations

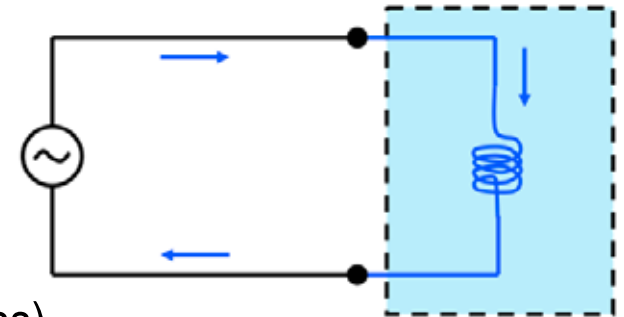
## Driven-Mode

- MRI magnets generally operated in persistent-mode; a prominent exception: *ISEULT* (CEA)

### *ISEULT* Temporal Stabilities

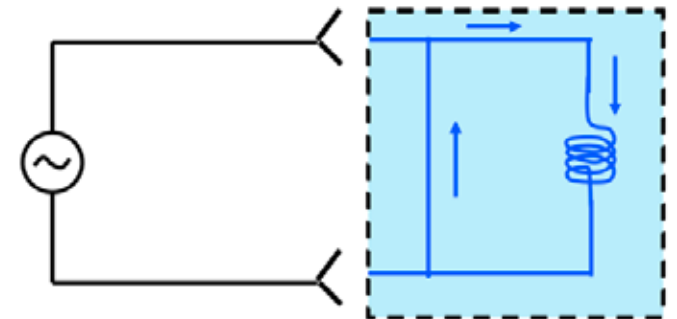
Long term (~hours): 0.05 ppm ( $\pm 0.006$  gauss)

Short term (per scan time, ~30 min): 0.4 ppb (0.00005 gauss)



## Persistent-Mode

- Temporal stability of 0.5 ppb with persistent-mode, corresponding to a decay time constant of ~100,000 yrs
- Resistance of each joint typically  $< \sim$ a few pico-ohms



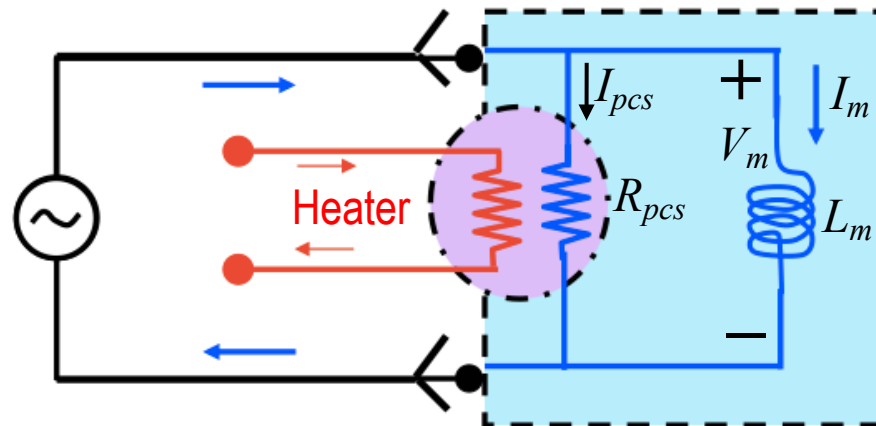
# Magnet Design Parameters: Part 7b

7b. Operating mode: driven vs. persistent → temporal stability

Driven: power supply; Persistent: joints, **persistent-current switches**, their locations

## Requirements for Persistent-Current Switch (PCS)

- $I_{pcs} < \sim 0.1 \times I_m$  : less than 10% of magnet current  $I_s$  through PCS
- $I_{pcs} = V_m / R_{pcs}$  , where  $V_m = L_m \times dI_m/dt$  → Faster charging rate, greater  $R_{pcs}$
- Minimum PCS heater power → All PCS heater power becomes cryogenic load



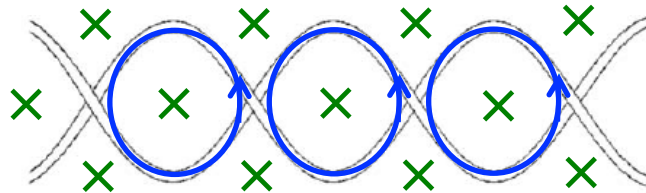
## ***Magnet Design Parameters: Parts 8—12***

8. Stored magnetic energy: inductance matrix
  - Discussed in ***Lecture #4: Stability & Protection***
9. Protection: active vs. passive
  - Active*** Quench detection; discharge voltage; dump resistor; current switching; heater
  - Passive*** Normal-zone propagation; shunt resistors & locations
    - Discussed in ***Lecture #4***
10. Magnetic fields: center; peak; spatial field homogeneity → Correction coils & shim coils  
Fringe fields: Shielded vs. non-shielded → *Passive* vs. active
  - Selected topics in ***Lecture #3: Solenoidal, Dipole, Quadrupoles, Racetrack Coils***
11. Magnet support structure, within and outside the windings
  - Limited discussion in ***Lecture #5: Mechanical Issues***
12. Stresses (within windings) and strains (superconductors)  
—***Lecture #5: Mechanical Issues***

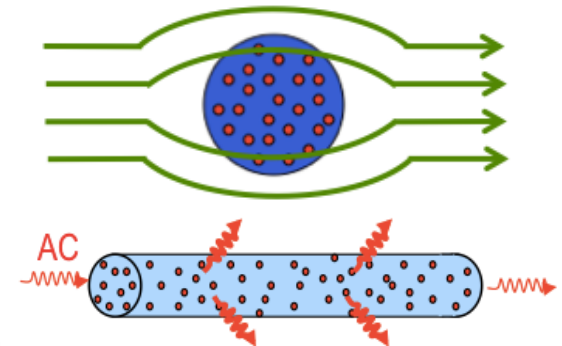
# Magnet Design Parameters: Part 13

## 13. Time-varying field: AC losses in Type II Superconductors

- Hysteresis: manifestation of hysteretic magnetization
  - Smaller hysteresis area  $\rightarrow$  smaller loss, i.e., smaller filament size
- Coupling among filaments



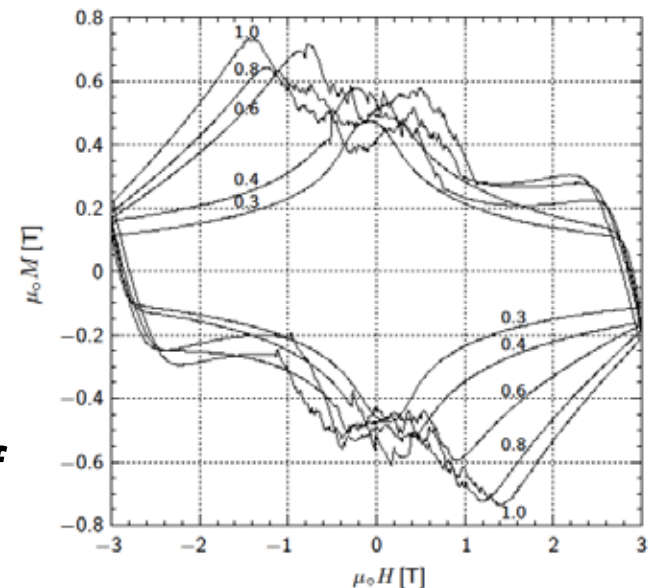
- Smaller loop size  $\rightarrow$  smaller loss, i.e., shorter twist pitch
- Eddy current in matrix metal and other metallic objects



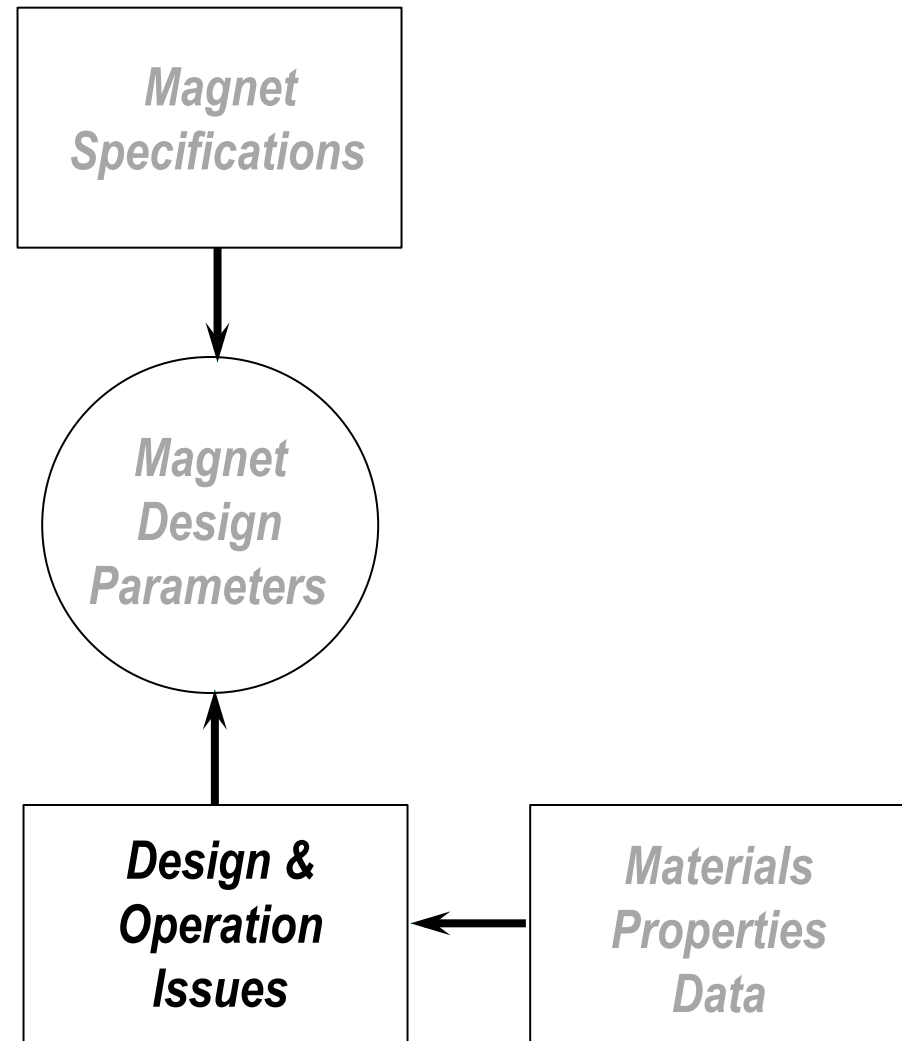
### Sources of AC Losses

- Time-varying magnetic field
- Time-varying current
- Time-varying field & current

**AC losses one big obstacles for application of superconductivity to electrical devices**



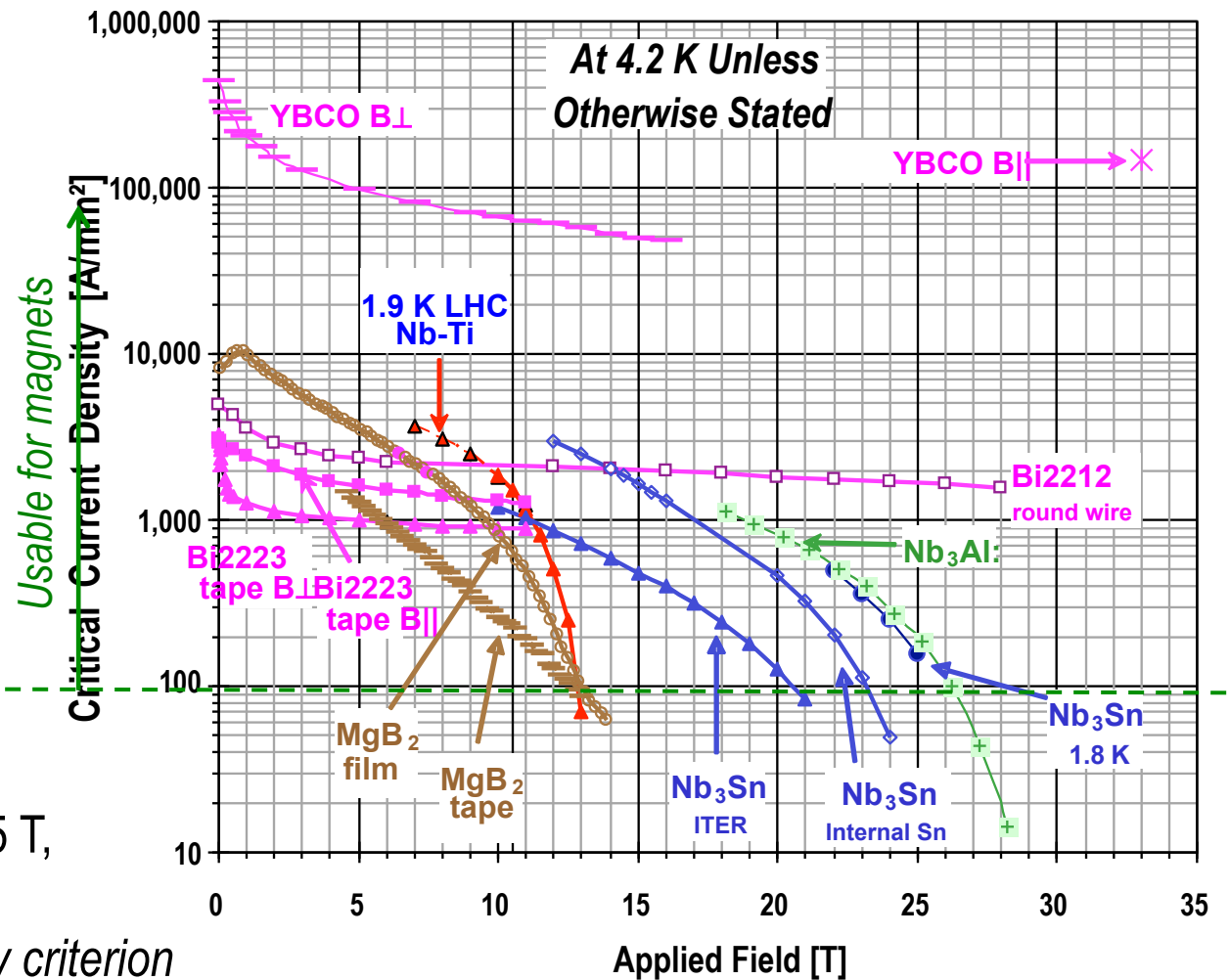
# Design Block Diagram for a Superconducting Magnet



# Design and Operation Issues: Part 1

## 1. Critical current densities of superconductors

- $\text{Nb}_3\text{Sn}$  to  $\sim 20$  T @ 4.2 K  
 $\sim 25$  T @  $\sim 2$  K
- $\text{NbTi}$  to  $\sim 10$  T @ 4.2 K  
 $\sim 12$  T @  $\sim 2$  K
- HTS, except  $\text{MgB}_2$ ,  $\geq 25$  T, **enabling** performance, not cost, primary criterion
- HTS, except  $\text{MgB}_2$ ,  $< 25$  T, **replacing**, cost, not performance, primary criterion
- $\text{MgB}_2$  promising  $< 3$  T @ 10-20 K



## ***Design and Operation Issues: Parts 2 & 3***

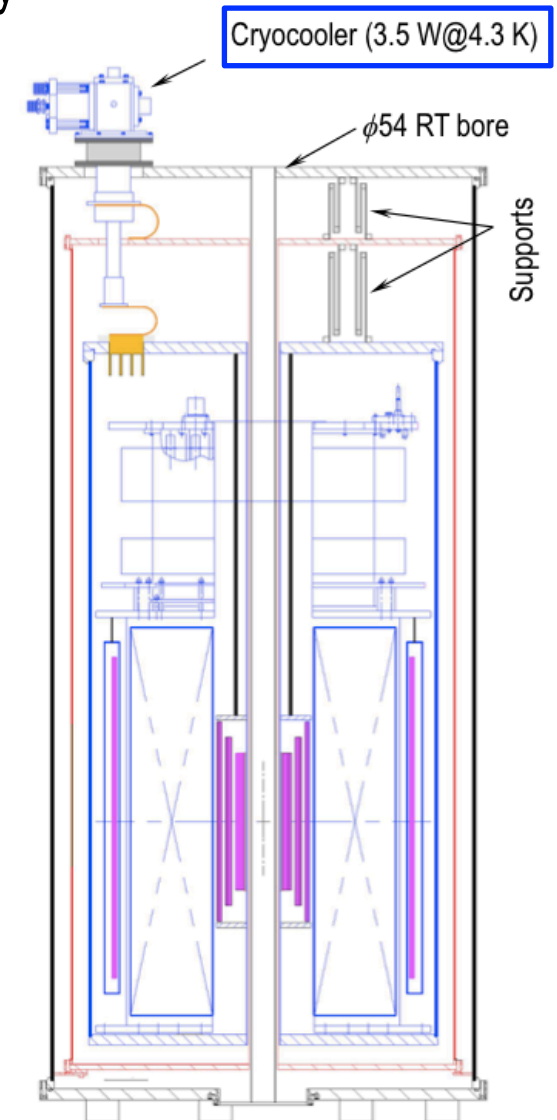
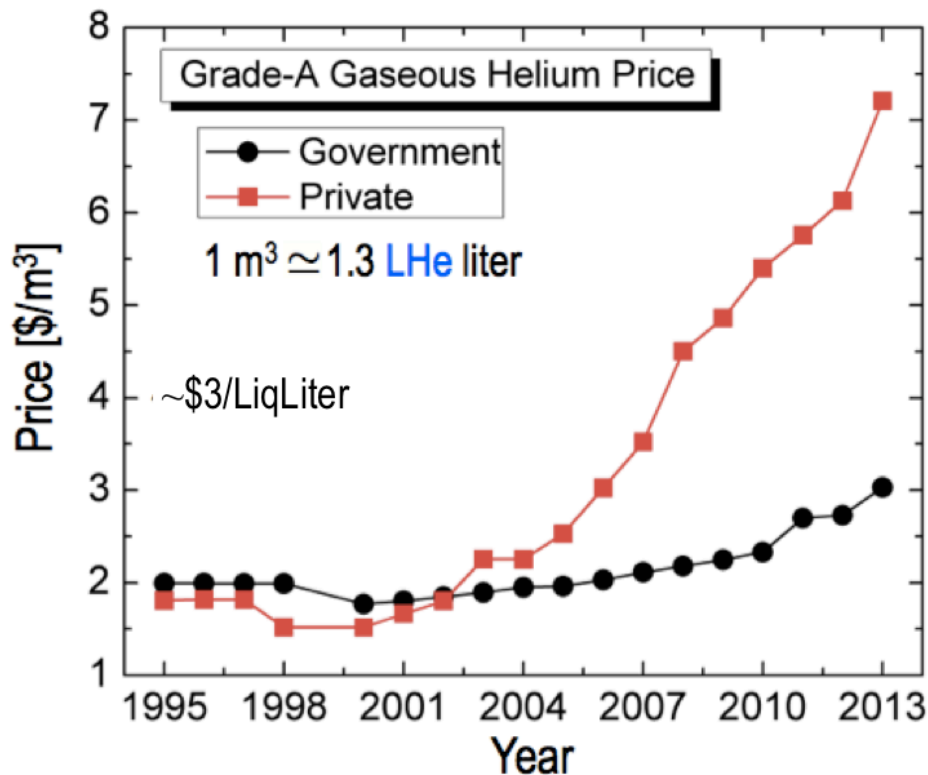
2. Mechanical integrity: axial, hoop, radial stresses  
strain tolerances of superconductors & other materials; "Gee," vibration; fault-mode forces  
Selected topics in ***Lecture #5: Mechanical Issues***
3. Stability: cryostable vs. adiabatic—***Lecture #4: Stability & Protection***



## Design and Operation Issues: Part 4

### 4. Cryogenics: cryogen vs. cryocooler; *LHe-free superconducting magnets*

- Driving force on LHe-free magnets: world-wide helium scarcity
  - Easier solution: re-condense He vapor with a cryocooler
  - More challenging: No LHe bath



## ***Design and Operation Issue: Part 5***

5. Protection: *passive* vs. *active*; quench detection; maximum winding temperature  
—***Lecture #4: Stability & Protection***

***Joyeux Solstice d'été!***